It’s More Fun Than Crayons
WARNING — It has been determined that reading this ad may be hazardous to your health, if you own another type computer system. We will not be responsible for ulcers, heartburn, or other complications if you persist in reading this material.

4 K BASIC® — 8 K BASIC®

* Full floating point math
* 1.0E-99 to 9.99999999E+99 number range
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* Direct mode provided for most statements
* Will run most programs in 8K bytes of memory (4K Version)
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COMMANDS

LIST
RUN
NEW
SAVE
LOAD
PATCH

STATEMENTS

REM
END
GOTO*
STOP
GOSUB*
PATCH*
RETURN

FUNCTIONS

ABS
VAL
SIN
INT
EXTS
COS
RND
LEN
TAN
SGN
LEFT$
EXP
CHR
MID$
LOG
USER
RIGHT$
SQR
TAB

MATH OPERATORS

( unary) Negate
* Multiplication
/ Division
+ Addition
- Subtraction
† † Exponent

RELATIONAL OPERATORS

= Equal
<> Not Equal
< Less Than
> Greater Than
<= Less Than or Equal
>= Greater Than or Equal

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You guys are out of your minds, but who am I to complain. Send —

☐ 4K BASIC CASSETTE $4.95 ☐ MP-68 Computer
☐ 8K BASIC CASSETTE $9.95 Kit $395.00

NAME

ADDRESS

CITY STATE ZIP

Southwest Technical Products Corp.
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You get more games, more fun, more computer uses with this new joystick

AND THERE'S AN EASY WAY TO INPUT IT TO YOUR COMPUTER

You'll get a lot more fun out of your computer with this new joystick.

But note that it is not just an ordinary joystick — it is a console. It has a 2-axis joystick and contains a speaker and speaker amplifier. You can have sound with your games or, say, warning sounds in other applications. Or have your computer talk to you.

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To couple the new joystick to your computer, just use our D+7A™ I/O board. It will couple not only one but two consoles to your Altair™ 8800 or IMSAI 8080. And you'll still have several analog channels left over (and one 8-bit output port). The D+7A plugs into the Standard 100 (S-100) bus of your Altair or IMSAI computer.

EASY TO DISPLAY

Displaying the joystick outputs with the software below is also easy. Just use our TV DAZZLER™ board. It also plugs into the S-100 bus.

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Here's some new Cromemco software for the joystick (to display, use DAZZLER interface):
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DAZZLE DOODLE (1 person, 1 joystick): lets you draw pictures in 4 colors on your color TV terminal using the joystick.

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Cromemco wishes you more fun, more use from your computer. Get this new joystick console and other Cromemco peripherals at your computer store or order from the factory.

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SOFTWARE

(Punched paper tape with documentation)
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Mastercharge and BankAmericard accepted with signed order. Please show complete card number and expiration date.

Mail orders shipped prepaid if fully paid with order. Purchase orders accepted subject to credit approval.

California users add 6% sales tax.
In This Page 26

It's More Fun Than Crayons! Read how Mike and Alex Rosner, ages 7 and 5, discovered the joys of computer art and incidentally proved the need for timesharing computers in the home. On the cover are super stars Mike and Alex at work.

If Isaac Newton were alive today, he'd be immersed in long and complicated physics manipulations, which are ultimately tested using calculations involving multidimensional matrices and matrix operations of linear algebra. Chances are he might be interacting with a computer, with an interpreter from the APL tree of languages. Read Mark Arnold’s What Is APL? to find out a bit about APL, a language with a mathematical orientation but utility for general purpose programming as well.

How do you do graphics in a weekend, without spending a fortune? In Beer Budget Graphics, Peter Nelson tells all: how the synergistic combination of a couple of digital to analog converters and an output latch or two brings the world of point plotting to an oscilloscope for about $20 in parts.

In the July 1976 BYTE, we ran a functional specification for a graphics interface in answer to reader Paul Hyde Jr’s letter. Practically before the ink had dried on the July press run (figure of speech) reader Thomas R Buschbach sent in this article on how he made just such a graphics interface for his Digital Group system using existing timing logic of the television display unit. Given an existing 8 K memory, processor and television display generator, this high resolution display can be added to a system for as little as $25 in additional semiconductors.

Star Trek freaks should turn to Joe Deres’ article to find An Enterprising Display. In the article you’ll find information on a design for a television graphics output which can be built from a kit (or your own parts) for less than $100.

Ira Rampil provides Some Graphics Background Information, including a comparison of several display devices available to individuals.

Don’t be satisfied with simple visual readouts, Make Your Next Peripheral a Real Eye Opener by implementing a true vector display using an XY oscilloscope, circuits and software similar to Steve Ciarcia’s design. In his article you’ll see how to draw a picture of a moderately high resolution Star Ship Enterprise.

Build This Video Display Terminal, advises Alfred Anderson, who took C W Gantt Jr’s TV interface circuit described in the June 1976 BYTE, made a few changes, added a few goodies, and wrote a few lines of software. Now he tells you how you can do it.

What’s NOT In This BYTE

...Software Bug of the Month, Book Reviews, Ask BYTE, a slew of What’s New and BYTE’s Bits items we were dying to print, lots of good letters, and some dynamite articles. Even using smaller type in places didn’t enable us to include much that we urgently wished to. If you missed it this month, watch for it next.

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Imagine a microcomputer

Imagine a microcomputer with all the design savvy, ruggedness, and sophistication of the best minicomputers.

Imagine a microcomputer supported by dozens of interface, memory, and processor option boards. One that can be interfaced to an indefinite number of peripheral devices including dual floppy discs, CRT’s, line printers, cassette recorders, video displays, paper tape readers, teleprinters, plotters, and custom devices.

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Imagine a microcomputer that will do everything a mini will do, only at a fraction of the cost.

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The Altair 8800b is a second generation design of the most popular microcomputer in the field, the Altair 8800. Built around the 8080A microprocessor, the Altair 8800b is an open ended machine that is compatible with all Altair 8800 hardware and software. It can be configured to match most any system need.

NOTE: Altair is a trademark of MITS, Inc.
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New, heavy duty power supply. +8 volts at 18 amps, +18 volts at 2 amps, 18 volts at 2 amps. 110 volt or 220 volt operation (50/60 Hz). Primary tapped for either high or low line operation.

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**altair 8800-b**

MITS, Inc. 1976/2450 Alamo S.E./Albuquerque, New Mexico 87106
Photo 1: Alex Rosner, age 5, shown preparing the graph paper coding sheet for his picture from a pencil sketch. Once the correlation between picture locations and commands was learned, both children stopped planning layouts in advance on the coding sheets. The "snow with house and mailbox" is shown in photo 5.

Now that the home computer is emerging from its crystal radio stage and now that we are becoming more applications oriented rather than hardware oriented, we are going to find that we have competition for computer time right in our homes. While I have been putting microcomputers using microprocessors together for almost two years, it wasn't until I hooked up the TV to my present system that my family took interest.

Now, when I walk in the door after work, the kids corner me asking which one can use the computer first.

The microcomputer system uses a MOS Technology 6502 CPU, a TIM (Teletype Interface Monitor), and 1 kilobyte of programmable memory. The graphics module contains a 2 K by 8 programmable memory allowing a 128 by 128 point display. In these pictures the display is configured

Photo 3: "Cage," by Alex Rosner, freehand.
Photo 4: Rocket Ship With Moon, by Mike Rosner.
Photo 5: Snow With House and Mailbox, by Alex Rosner.
(under software control) as a 32 by 32 array.
The data for the display is entered serially. The software commands are
- R, reset to top line,
- N, go to beginning of next line,
- W, enter a white square,
- K, enter a black square, and
- H, halt (return to monitor).

The procedure is to take a piece of graph paper with a 32 by 32 grid blocked off and
to then draw a picture by filling in some of the squares. After the drawing is complete
the paper tape with the program is loaded into the processor and the data is entered
with the above five commands using the drawing as a coding sheet.

This, of course, is not an ideal hardware or software approach for a video interface.
The interface was built for another application and the processor was used as a test
If you thought a rugged, professional yet affordable computer didn’t exist,

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San Leandro, CA 94577
(415) 483-2093
fixture. After testing the display unit, I put a little "HELLO MOM" and a starship on the screen and showed it to my wife and two kids. The children immediately wanted to do the same thing and we now have a new toy.

The older child, Michael, is seven and learned to generate a picture and use the program after about two hours of instruction. He is shown in photo 2 as he puts his third creation on the screen, a rocket with the moon. Above his right hand can be seen the drawing he is working from. (The pattern in the lower portion of the TV screen is the random data in the programmable memory chips when the power is turned on.) All his efforts at keypunching have been saved on paper tape for delayed replay when Grandma comes to visit.

The younger child, Alex, five, is shown in photo 1 as he prepares the coding sheet from a sketch for his third picture — a house with mailbox and snow. Alex required a considerable amount of help with his first two pictures, but he quickly learned to use the graph paper correctly.

The cover photo shows the entire setup. Alex is putting a picture on the TV while Mike is using BRUIN (a language similar to BASIC). It seems that second graders are now being taught the rudiments of algebra. When my calculator batteries went dead I called up my company’s computer to do some simple calculations. Mike saw me using the CRT terminal and wanted to try it. While we can’t call this programming, he is having fun.

The collection of photos from the TV screen shows some of the work the kids have been doing along with the titles. The inception, generation and titling of all the pictures are the kids' own without help from adults. Mike’s first three pictures were made using work sheets as were Alex’s first three. The rest were made without first making drawings.

The microcomputer is set up in the family playroom. I consider myself quite fortunate in that I have never had to fight with my wife for space. From the beginning of this venture I have had my wife’s full support. Perhaps this is because (as she has recently informed me) she plans on using the computer to help her in the various business courses in which she is enrolling, as well as for household functions such as diet menu planning.

If you are as lucky as I am, you may find yourself putting up a signup sheet as the family competes for computer time.

Editor’s Note: Readers will detect a careful balance between the amount of photographic exposure given to Alex and Mike. Author Richard Rosner reports that the realpolitik of family life requires equal treatment for both children in his article... CH
A Proposed Standard for Publishing Binary Data in Machine Readable Form

Walter Banks and Roger Sanderson of the University of Waterloo, Waterloo, Ontario CANADA, have proposed a method of publishing machine readable programs in magazines such as BYTE. This proposal was the subject of some discussion in a technical session at the Personal Computing 76 show in Atlantic City. I wrote the present report, based upon preliminary written information provided by Walter and Roger, and telephone discussions with Walter on August 15 1976. The technical content of this report, with the exception of the proposal of format 3 and addition of a frame identification field to the block format, is supplied by Walter and Roger... CH

Purpose

The purpose of this technology is to provide a method of encoding binary data in the form of printed marks on a magazine, book or other published page. These printed marks are to be in a predefined format which can be read by a simple and inexpensive optical scanning head which drives a single bit input port of a personal computer; decoding will be done by means of software in the computer. The goal is to provide a means of disseminating program information in a machine readable form.

Physical Formats

Figure 1 details three possible physical formats. These are proposals at the present time. Other formats are possible and should not be excluded from contention; readers are invited to make proposals. The formats are described in the captions of figure 1. The following comments can be made.

- Format 1, bar width modulation with alternate light and dark, is the most compact method of encoding. Its density varies with the detailed content, but for a given minimum light (or dark) interval measurable by the input routine and a given binary string of data, this method will be higher density than either format 2 or format 3 below. A disadvantage is that emergency manual reading of the data with a magnifier is probably more difficult due to the need to interpret four states: wide space, wide mark, narrow space, narrow mark. This method had been proposed for use in the retail trade by Research Inc, Box 24064, Minneapolis MN 55424, some time ago, before the UPC (Universal Product Code) scheme was adopted for grocery product checkout use.

- Format 2, ratio recording, has an advantage in certain points of view in its fixed width. Being fixed width, the amount of data per page is fixed, as is the amount of data per line of machine readable type. However, it is a lower density form than either format 1 or format 3 below. It can probably be read by eye with greater ease than format 1 since every bit is present as a short or long bar which is actually printed, and only two states need be interpreted.

- Format 3, fixed gap bar width modulation, is basically a higher density version of ratio recording. Take the layout of format 2, and compress the gaps between black marks to a fixed length, and you will get format 3. Since this format is higher density, it may be preferable to format 2, while retaining the advantages of having a human readable black mark for every bit.

Frame Layout and Page Layout

Figure 2 shows the layout of a single frame of information, interpreted within the
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If you've been considering the purchase of a microcomputer and looking at the myriad of products on the market, chances are you're just a bit confused about which system makes sense for you.

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Figure 1: Three possible formats. These are proposals at this time, with the appropriate parameters indicated.

Figure 1a: Format 1: Bar width modulation, with alternate dark and light. The parameters to be specified in printing are widths T0 and T1. A trailing bit complementary to the last data bit in a string is required. The leading bit of a string will be assumed to be in the dark state. In reading this code, time between transitions falls into two categories, long for a 1 bit, and short for a 0 bit.

Figure 1b: Format 2: Ratio recording. The parameters to be specified in printing are the bit length, TB and the T0 and T1 widths for states of the data. This format has a fixed length per bit which is independent of the state of the data. In reading this code, the time from one light to dark transition to the next light to dark transition is the duration of the bit cell, which is compared to the duration of the dark period to find out whether a 1 bit (long) or 0 bit (short) was read.

Figure 1c: Format 3: Fixed gap bar width modulation. The parameters to be specified in printing are the interbar gap width TG, and the bit length parameters T0 and T1. In reading this code, the length of the interbit gap gives a calibration for judging the next dark period as a 0 bit (short) or 1 bit (long). The data density (as in format 1) varies with the statistics of the number of 0s and 1s in a given region of the printed data.

String as a synchronization pattern followed by 8 bit bytes of information.

The SYNCH pattern is an 8 bit character which must occur as the first byte of every frame, and may be preceded by several timing bits to initialize adaptive software. Once the input string equals the SYNCH character, the decoding algorithm can proceed bit by bit with the rest of the frame.

The CHECKSUM field contains an 8 bit check sum of the data in the current frame. This is the primary error detection technique employed. In manual scanning, when an error occurs, the sensor head can be drawn

Figure 2: Frame Format. The timing bits may not be required, but provide a preliminary leader before the ASCII SYN character (hexadecimal 16) which leads off the frame. All data is transmitted most significant bit first. Following the synchronization character is an 8 bit check sum representing 2's complement modulo 256 summation of all the remaining data on the record. The FRAMEID field is an 8 bit integer used for relative positioning within an extended file. Its purpose is to allow manual rescan in the event of errors, so that the software will recognize the input as the same record. The length field contains a direct integer value for the number of bytes in the data field. From 1 to 255 bytes can be in the data field; a length of 0 is reserved for a special case "end of file" frame. Finally, the remainder of the frame contains 8 bit bytes of data.
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TDL
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TECHNICAL DESIGN LABS, INC.
342 COLUMBUS AVENUE
TRENTON, NEW JERSEY 08629
Figure 3: Page Layout. A page of data in printed form [as we would run in BYTE] would be laid out with the data running parallel to the center margin of the magazine. This allows the maximum amount of data in a frame, thus minimizing the overhead bits of the frame format.

Figures 3

How Is the Data Generated?

The secret of this whole method at the magazine production end is using modern phototypesetting equipment to create the images of the data which are used in the magazine master layouts. When (for example) an article describing an advanced high level language interpreter written by a university or basement lab hacker is to be printed, the paper tape or magnetic tape text of the program and its relocatable loader would be converted into phototypesetting commands for the typesetting equipment, on 9 track tape or paper tape compatible with the typesetter. Once the copy is received from the typesetter, the rest of the layout is standard operating procedure for any magazine — keep track of the order of the program pages and add any auxiliary copy needed to identify pages or segments within the program. With 2 K bytes per page, dissemination of an 8 K to 10 K package would only require four or five pages in the magazine, and would be easily accomplished. We expect to perform experiments with this sort of dissemination technique in future editions of BYTE.

Will It Work?

The experiment looks quite reasonable, but there are numerous possible hitches which can be considered. For example, will the data density projected (50 bits per inch, 20 bits per centimeter) be practical? What will be the incidence of errors due to ink splatters and other glitches? Will the simple conception of a reading head (photo transistor, TTL level converter and straight edge as a guide) provide the signal needed? This report is written on the basis of preliminary experiments; further information on this subject will appear in future BYTES.
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Bon appetit!
Editorial

The Address Space Saturation Problem
(or, What Happens After You Use 32 16 K Dynamic Memory Chips?)

According to an article by Marvin Gold in the September 6 1976 edition of Electronic News, the 16 K dynamic memory chips are almost ready for volume production, and price estimates are quoted. According to Mr Gold's article, the 1976 average selling price of 16 K memory chips will be an estimated $16 each, and when volume production levels are reached in 1977, the average price at the factory will be $12. Assuming a personal computing company which has moderate volume production purchases the 16 K memories at $12, its component cost for a 16 K memory segment is $96, and for a 32 K memory segment is $192 in mid to late 1977. Multiply this by a factor of 3 to 5 to take into account packaging, manufacturer profit margins, and merchant markup; and it can be expected that in mid to late 1977 the personal computer with 32 K memory will have a memory subsystem cost of perhaps $600 to $1000 at the retail store.

The designers of the early microprocessors never conceived of the large scale integration computer as anything more than a controller in dedicated applications (so the grapevine says). The rumor which was running around some time ago was that one LSI firm's reaction to the idea of a FORTRAN (or other high level language) for their microcomputer was "who'd ever want to do such a silly thing." The history of small general purpose computers implemented with LSI processors since then demonstrates that a lot of people want to do exactly that, and more: APL, SNOBOL, LISP, PASCAL, ALGOL, TRACTM etc, etc. Similarly, the reaction currently might be "who'd ever want to put more than 64 K bytes of memory in a personal computing system?" My claim is that there are plenty of people who would want to (in order to

Continued on page 65

Personal Computing 76:

Outstanding Computer Hobbyist of the Year Award

by John Dilks
Cochairman of PC 76

At the Personal Computing 76 show, the members of the committee organizing the show felt it would be most appropriate to create an award for a person who has made some outstanding contributions to the progress of computing by individuals. We selected the person, then dreamed up the award. The person is Sol Libes, president of the Amateur Computer Group of New Jersey. The award consists of a plaque for Sol to keep, and a second plaque with spaces for future entries to be engraved. This is how traditions are started.

We had numerous reasons for wanting to present this award to Sol. Sol is employed as an educator, and is a true amateur interested in using the computer. He is one of the principal organizers of the Amateur Computer Group of New Jersey, seeing it grow from a near handful of people last year to over 400 members with typically 200 attending the many meetings. He is a leader in computer education, where at the Union County Technical Institute he has created a hands-on training program in microcomputer technology and has set up courses which could easily serve as prototypes for similar courses throughout the country. He set up and ran the Trenton Computer Festival of the ACGNJ, one of the first such happenings ever. And, during the past summer, he and his family travelled throughout the USA, meeting with amateur computer clubs and club leaders and manufacturers both to find out what's happening and to further the development of the field. We think these reasons more than justify the recognition, which was a complete surprise to Sol and his family at the banquet August 28. We hope to continue this award and tradition at future Personal Computing shows.
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What Is APL?

APL is the modest name of A Programming Language, created by Kenneth Iverson. APL is simple to learn, yet in many ways it is the most powerful language in use today. While to the untrained eye APL looks like the strangest computer language around, with the possible exception of LISP, the structure of APL is fairly close to that of more common languages such as FORTRAN or BASIC. This article will look at some of the features of a large system APL. Also, I will explore what features I think a small APL system for a microcomputer could have.

Writing in FORTRAN is like writing how to go downtown: You don't have to think a lot about what parts of the language you use; you just tell exactly what to do. Writing in APL is like writing poetry: You want to use the exact part of the language that will express what you want without any excess. APL haters criticize APL because there are so many operators for the user to remember, and the code doesn't always flow out without some thought, but APL enthusiasts like APL because the large number of operators greatly reduces the size of programs.

APL is extremely time-efficient (at least on large computers) for parallel operations, such as adding two sets of numbers together. Suppose your program was to figure out the bowling average of each of the four players on your team. In most languages you would have to use a loop which would go around for each time there was a new score. In APL, all you would need (provided the program was set up right) would be a +.

APL operates as an interpreter; that is, it looks at the APL language program and does the operation (perhaps after some intermediate translation). This is different from a compiler which translates to machine language before the program is run. Because of this, there are two states in which you operate APL. The first is called evaluated input and the second is called function definition. "Function" is the APL name for what would be called a "program" in other languages. A workspace is all the functions and variables that you have created. There can be more than one function in a workspace, and often you can save the workspace on an auxiliary storage device.

The evaluated input mode is as simple as 1 + 1. When evaluated input is in control, APL prints six spaces and requests input. If you type 1 + 1, APL will print out the sum of 1 and 1. It would look like this (where the indented part is what you type and the answer is printed out starting at the left hand margin)

```
1+1
USER --+ 2
```

Notice that no "Print Statement" is neces-
sary as it would be in BASIC. Some common operators are $+, -, \times, \div$. These are the normal math symbols for the basic operations, but not the normal BASIC and FORTRAN symbols. The original APL used these and many more strange characters for its operators, and since the first APL systems were implemented on IBM/360s, this was no major problem. Changing a character set simply meant changing balls on a Selectric terminal. Most of the operators have two meanings (as summarized in table 1 for all APL operators). The example above of adding 1 to 1 is known as dyadic; that is, the addition operator has two operands: the one on the left and the one on the right. The $-$ is an example of a monadic operator that has only one operand on the right:

\[-3\]

APL scans an expression from the right to the left which is opposite the way most high level languages do. This means 2\(-3\)\(-4\) yields 3 instead of $-5$. (In APL, a raised hyphen indicates an algebraic negative sign and an ordinary hyphen is used for subtraction.) Also unlike most high level languages, there is no algebraic hierarchy in APL. So $2x3+4x5$ is 56 and not 26. However, as in other high level languages, parentheses can be used to override the right to left convention: $(2x3) + 4x5$ is 26.

All the expressions shown up to now have been of scalar values, that is, single numbers. APL also allows vectors as constants. A vector is an ordered set of scalar values, something like an array in FORTRAN or BASIC. So to figure the average of the two scores of the four members of your bowling team:

\[
\begin{align*}
&0.5 \times 160 & 109 & 300 & 240 & \text{USER} \rightarrow \\
& + 203 & 157 & 254 & 165 & \text{USER} \rightarrow \\
& 181.5 & 133 & 277 & 202.5 & \text{APL}
\end{align*}
\]

where player one bowled 160 and 203, player two 109 and 157, and so on. The first thing APL does is to add the two vectors (scores) in parallel to get 363 266 554 405. Then each one of the four sums is multiplied by $0.5$ to produce: 181.5 133 277 202.5, the average of those two sums. All of this was done without an explicit loop or any program in the evaluated input mode. (Note: To do an operation, either the size of the two

Table 1: APL Operators. This is a complete listing, abstracted from the sources in the bibliography of this article, of the APL operators implemented in a typical large scale system such as an IBM/360 or IBM/370. The IBM 5100 machine is reported to run the full set of APL functions by emulating a 360/370 architecture in microcode and using close to 200 K bytes of interpreter ROM. A practical small system APL would necessarily be a subset if the interpreter is to be kept to a small size.

Monadic Scalar Operators

$+$ Identity: Returns the right operand as though the operator had not been there.

$-$ Minus: Returns the negative value of the right operand. (Appears above normal position of minus sign as in $-^3$.)

$\times$ Signum: Returns 1 if the right operand is greater than zero, 0 if it is equal to zero, and $-1$ if it is less than zero.

$\div$ Reciprocal: Returns the reciprocal of the right operand.

$\ast$ Exponential: Returns $e$ raised to the right operand.

$\oplus$ Natural Logarithm: Returns the LOG base $e$ of the right operand.

$\mid$ Floor: Returns the greatest integer less than or equal to the right operand.

$\lceil$ Ceiling: Returns the least integer greater than or equal to the right operand.

$!$ Absolute value: Returns the absolute value of the right operand.

$\lceil$ Factorial: Returns the factorial of the right operand.

$\circ$ Pi times: Returns $\pi$ times the right operand.

$\bowtie$ Not: Returns a 1 if the right operand is 0, 0 if the right operand is 1; an error condition results if the operand is not logical (1 or 0).

$?\, Roll$: Returns a random number between 1 and the operand.

Monadic Mixed Operators

$\cdot$ Ravel: Converts a higher dimensioned array into a vector.

$\downarrow$ Index generator: Returns a vector of consecutive integers between 1 and the right operand.

$\rho$ Shape: Returns the length of a vector or the dimensions of a higher dimensioned array.

$\uparrow$ Grade up: Returns a vector that when used to index the right operand will sort it into ascending order.

$\downarrow$ Grade down: Returns a vector that when used to index the right operand will sort it into descending order.

$\varepsilon$ Execute: Returns the value of an expression represented by character data as though the characters value of the right operand had been entered during evaluated input.

$\mathbf{\Sigma}$ Matrix inverse: Returns the inverse of the matrix specified in the right operand.

$\odot$ Monadic transpose: Returns a matrix such that the rows of the right operand are the columns of the new matrix.

$\otimes$ Reversal: Returns a vector (if the right operand is a vector) where the elements of the vector are in the reverse order of the right operand.

Dyadic Scalar Operands

$+$ Addition: Returns the sum of the right and left operands.

$-$ Subtraction: Returns the difference of the right and left operands.

$\times$ Multiplication: Returns the product of the right and left operands.
Another type of constant is the character type. 'A' is a character scalar constant and 'ABCD' is a character vector. A character vector in APL is roughly equivalent to the character string as implemented in languages like Extended BASIC, PL/1 or XPL.

Any legal left operand can be subscripted by using the brackets.

```
33 443  34 [1 3]
```
gives a two element array

```
33  34
```

In this case a three element array is reduced to two by choosing elements 1 and 3.

A variable, whose name can be up to 31 characters long, is assigned a value by the assignment arrow.

For example:

```
D←0 0 9
A←1 2 3 4
B←5 6 7 4
C←A+B
D←[1 2]+C[3 4]
```

```
6 8 10 0
```

Notice that an assignment suppresses the printing of a value. In this example D is given the vector value 0 0 9. A is given the vector value 1 2 3 4, and B is given the value 5 6 7 4; C is the sum of these two vectors. The first two elements of D are assigned the last two of C. Character data can also be assigned to a variable, such as

```
MESS←'This is a message'
```

```
This is a message
```

Some of the operators listed in table 1 are very important to APL programs. One of these is the monadic iota, known as the index generator, which creates a vector of consecutive integers from 1 to the value of the operand. This operator can be used to eliminate many loops from programs. For
example, if you wanted to calculate the cosine of a number using the Taylor series:

$$1 - \frac{x^2}{2!} + \frac{x^4}{4!} + \ldots + (-1)^n \frac{1}{n!} 2n-2 \left( \frac{2n-2}{2} \right)!$$

(instead of using the $2^\text{X}$ function) this expression would do it, where $N$ is the number of terms to be calculated.

$$+/- (1*-1 +tN) \times (x*) \quad \text{USER} \rightarrow$$

$2x-1+ (tN)! \quad \text{USER} \rightarrow$

The subexpression $2x-1+ (tN)!$ will generate $N$ even integers, while this same expression is used to calculate factorials. The powers and the factorials are divided in parallel and multiplied by the $1^{-1} 1^{-1} \ldots$ generated by $(1*-1 +tN)!$ The $+/-$, called a plus reduction, sums up each one of the elements of the vector which contained the quotients of the powers and factorials. Another example of plus reduction would be to average the vector $2345$:

$$(+2 345) : 4 \quad \text{USER} \rightarrow$$

$3.5$

Any other dyadic scalar operator could have been used; for example, instead of the built-in factorial operator, the factorial of a scalar $J$ could be calculated by:

$$x/\!\!\!\!J \quad \text{USER} \rightarrow$$

Two other operators that eliminate loops are the grade up and grade down operators, which function similarly. They are monadic only. The grade up gives a vector of the subscripts to the given vector so that if the vector is subscripted by its grade up it will be sorted in ascending order. For example:

$$A \leftarrow 6 4 7 3 5 \quad \text{USER} \rightarrow$$

$$4 2 5 1 3 \quad \text{USER} \rightarrow$$

$$A \leftarrow \{4\}A \quad \text{APL} \rightarrow$$

$$3 4 5 6 7 \quad \text{APL} \rightarrow$$

Suppose the scores of the players on your bowling team were in a vector subscripted by player number (as in previous examples); then if you wanted to display the ranking of players, best to worst, simply do a grade down: $\langle k$.

One of the most interesting operators of APL is the execute operator, sometimes represented as $g$ or $c$ which takes a character vector and performs operations as if the characters had been input during evaluated input.
For example:

\[ e \cdot '1+1' \]

\[ 2 \]

\[ A \cdot '1' \]

\[ B \cdot '1' \]

\[ eA, '+' , B \]

\[ 2 \]

The comma is the catenation operator, which takes the vectors and forms a new vector of the old two joined together, so \[ '+' , B \] forms \[ '+' , B \] and \[ A, '+' , B \] forms \[ '1+1' \]. This is then evaluated by the execute operator which gives the numerical result of 2. Catenation can also be used on numeric vectors:

\[ A \cdot 1 2 3 \]

\[ B \cdot 5.5 4.7 3 \]

\[ 1 2 3 5.5 4.7 3 \]

To create an APL program (function) you must leave the executive or evaluated input mode, and enter the function definition mode. To do this, type the del (\(\boxplus\)) and the name of the function you wish to create. For example, to create a function called NEW type:

\[ \boxplus NEW \]

to which APL would respond:

\[ [1] \]

You would then type the first line of the function, and continue until all the function is entered, or until you want to leave the function definition mode, which you can do by typing another del. Here is a sample function:

\[ \boxplus NEW \]

\[ N \cdot 0 \]

\[ N \cdot N+1 \]

\[ N \cdot \]

\[ \rightarrow (N \# 10)/2 \]

\[ 'FINISHED' \]

\[ 1 \]

\[ 2 \]

\[ 3 \]

\[ 4 \]

\[ 5 \]

This function starts at line 1 by initializing the counter \( N \) to 0, then it proceeds to line 2 where the counter is incremented. At line 4, \( N \) is compared to 10, and since they are not equal a result of 1 is produced, which allows the 2 to pass through the compression operator (see table 1). The \( \rightarrow \) is the symbol for branching, so branch to 2 in the above example takes control back to line 2, where \( N \) is incremented again. The loop continues until \( N=10 \), in which case \( N \# 10 \) returns a value of 0. This causes the compression operator to return a null value. Branching to a null value is the same as branching to the next line in the function, which in this example prints out FINISHED. Since there are no more lines to execute, execution of the function stops, and APL prints out six spaces like normal. The output of this function would look like this:

\[ 1 \]

\[ 2 \]

\[ 4 \]

\[ 5 \]

\[ 6 \]

\[ 7 \]

\[ 8 \]

\[ 9 \]

\[ 10 \]

\[ FINISHED \]

This program is not a very useful one, since the iota could be used to get essentially the same result, but suppose you wanted to change this function to output a table of numbers and their squares. First you would reenter the function definition mode, and type \([3]\) to say that you wanted to change line three. You would type in:

\[ [3]N; 'N\#2 \]

The semicolon separates things to be printed on the same line. You decide you want a header on the output, so you type \([1.5]\) to insert a line between 1 and 2. Then you list the function by typing \(\square\) (the box is called a quad, and is also used for input and output within an expression).

\[ [1] N \cdot 0 \]

\[ [1.5] 'TABLE OF SQUARES' \]

\[ [2] N \cdot N+1 \]

\[ [3] N; N \# 2 \]

\[ [4] \rightarrow (N \# 10)/2 \]

Everything looks OK, so you close the

Continued on page 123
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In the past, graphics systems available to the experimenter have been expensive and complicated or have forced him to settle for limited resolution. The simple circuit described in this article will provide resolution of 128 by 128 dots for under $20 and four times that resolution for just over $20. It requires the use of an oscilloscope as the display device, but it need not use an expensive scope.

We can create images on the screen of an oscilloscope by using dots. By placing many dots close together, we can form lines and shapes or even letters and numbers. The location of a dot on the screen is specified to the oscilloscope by a pair of voltages, one voltage being applied to the scope’s vertical input and the other to its horizontal input. The computer provides the voltage values by outputting two binary words to a pair of digital to analog converters (known as DACs). The converters produce output voltages that are proportional to the numeric value of the words. Because an 8 bit word will allow the DAC to produce any one of 256 voltage values, it should be possible, using high precision 8 bit DACs, to position a dot anywhere in a 256 by 256 field.

By providing a rapid sequence of many binary word pairs, we can generate a large number of dots that all appear to exist on the screen at the same time. By repeating the sequence many times a second, we can display a steady, nonflickering pattern of dots. Each time we repeat the sequence we “refresh” the display.

Because the time required for the computer to perform a refresh operation will depend, at least in part, on the number of dots being displayed, there will certainly be an upper limit to the total number of dots that we can display without a noticeable flickering of the screen. That limit is determined by such factors as the speed of the computer, what the computer is doing besides refreshing the display, how the numbers are obtained (i.e., whether they are computed or read from a buffer in memory), the persistence of the oscilloscope’s phosphor, and what flicker frequency the user considers noticeable. For example, using the routine described later in this article on an 8080 system with a 1 MHz clock (about half the speed of an Altair 8800) and using a medium persistence phosphor in the display, I find that I can display about 512 dots before flicker begins to appear.

The Circuit

The circuit of figure 1 uses components that are all readily available. Most can be bought through the suppliers who advertise in the back pages of BYTE magazine. The MC1408 digital to analog converters can be supplied by any Motorola distributor and are manufactured in several different levels of precision. The precision determines the exactness with which the output voltage will correspond to the binary input. The -L8

<table>
<thead>
<tr>
<th>Integrated Circuit</th>
<th>Type</th>
<th>+5 V Power</th>
<th>Ground</th>
<th>-V (-7.1)</th>
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<td>74100</td>
<td>24</td>
<td>7</td>
<td>-</td>
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<tr>
<td>IC2</td>
<td>74100</td>
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<td>-</td>
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<tr>
<td>IC3</td>
<td>MC1408L7 or MC1408L8</td>
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<td>2</td>
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Figure 1: Schematic for the Beer Budget Graphics System. This graphics system uses the computer's main memory as a refresh source, with a continuously executing program to put the position information out to the X and Y inputs of the oscilloscope. Both the X and Y outputs change "simultaneously," limited only by the amplifier slew rates of the oscilloscope and the MC1408 settling times. The driver program enables interrupts once per scan in order to allow a keyboard controlled drawing mode commanded by user inputs.
version should be used if a 256 by 256 resolution is desired. The -L7 version may be used for a 128 by 128 resolution, but attempts to use it for higher resolutions will result in unevenly spaced dots. For low resolution applications (64 by 64 or less), the -L6 version provides an economical choice.

This circuit is simple enough to breadboard using a socketboard array such as I did. Later, I made a permanent board as a double layer printed circuit with fake "plated through" holes of wire jumpers. It may also be constructed using wirewrap techniques. Leads, especially those associated with the digital to analog converters, should be kept short; and I recommend that the lines going to the oscilloscope be shielded. A good ground connection to the oscilloscope is essential.

The data bus is assumed to come from an 8 bit parallel output port that can sink 6.4 mA per bit line. I do not recommend driving this circuit without additional current buffering directly from the system data bus unless there are relatively few other devices on the bus. A dotted line in the drawing shows where a 17 line interface to an existing latched 10 port might be made, further simplifying the circuit.

The strobe lines are active low and the entire logic 0 transition should take place while the data inputs to the latches are stable. The inverters provide current buffering for the 74100 clock inputs as well as the appropriate logic 1 load signal.

The digital to analog converters in the configuration shown in the schematic produce a negative output voltage. As the numeric value of the binary word becomes greater, the output voltage becomes more negative. Note that with the MC1408 DAC the A8 input is the least significant bit and A1 is the most significant bit.

Choice of an oscilloscope is not very critical. I have been using a battle-scarred Heathkit 10-102, which, until they stopped producing it, was the bottom of their line. The oscilloscope must have both X and Y inputs. If you have direct-coupled inputs, you may find them preferable at times, though for most applications AC or DC coupled inputs can be used. Unless it is severely limited, bandwidth should not be a problem: 1 MHz or greater in both channels should be more than adequate.

In normal operation, the horizontal coordinate is outputted first. The XSTROBE line is used to load that coordinate into the first latch of the horizontal channel. Note that it does not yet appear at the input of the horizontal digital to analog converter. The vertical coordinate is then outputted and loaded into the vertical latch by the YSTROBE line. This strobe signal also loads the horizontal coordinate into the second horizontal latch. Thus, the vertical and horizontal coordinates are both applied to their respective converters at the same time.

If you find that the dots seem to vibrate or move about on the screen, you are probably picking up 60 Hz hum. Double check the ground connection to the oscilloscope and use shielded cable if you are not already doing so. Streaked or smeared dots suggest excessive reactance on the lines going to the oscilloscope or severely limited bandwidth of the oscilloscope itself. The direction of the smearing gives you a clue as to which channel is being affected. Reducing the refresh rate may help to control this problem if all else fails.

Some Software Considerations

In many graphics applications such as game programs or interactive graphics, the computer is not merely being used to refresh a display but is also called on to perform other functions, in effect, at the same time. To allow maximum freedom for the computer to execute these other functions, the display refresh routine should be designed to operate quickly rather than, say, to save memory. Rewriting a dot output routine so as to save a few microseconds may not be a petty exercise if there are 512 dots to be refreshed 20 times a second. Such a savings might be obtained by using JUMP instructions instead of CALLs or, if you are outputting from a buffer in memory, defining the limits of that buffer only in terms of the most significant address byte so you don’t have to perform a time-consuming 16 bit comparison to find out if you’ve reached the end of the buffer.

It is also important to distribute the display refreshes evenly to avoid annoying flicker of the screen. If you decide, for example, to refresh the display 30 times a second, it will do no good to perform all 30 refresh operations in the first half of that second. This would probably be a good application for a programmable interval
timer which would generate an interrupt when it is time to refresh the display.

Note that it is possible to use the software to control dot brightness. By causing a particular point on the screen to be refreshed more often than other points, we can generate a brighter dot at that point. This may be done as simply as storing that dot in several locations in the buffer.

The routine detailed in listing 1 was the first program that I wrote for the graphics circuit. It is written for use with an 8080 instruction set and is basically a picture drawing routine. It has a 512 dot buffer, a blinking cursor, and it recognizes six commands: move cursor right; move cursor left; move cursor down; move cursor up; deposit a dot (at the cursor location); and, clear display. Because this routine uses a fixed buffer size, the clear is performed by sweeping all 512 dots into a pile in the lower left hand corner of the display (coordinate: FF,FF). Each command is indicated with a point on stack.

Other Ideas

Can a pair of digital to analog converters connected to a computer be used for applications other than graphics? Absolutely! An obvious idea would be waveform generation, but how about musical instrument synthesis? One converter could be connected to a wide range voltage to frequency converter such as the Raytheon 4151 and the other converter could provide envelope information. Passive components could tailor the output of the 4151 to suit the instrument being synthesized. Just about any continuous range phenomenon can be put under the control of the computer using a digital voltage to frequency converter.

Notes:

- All constants are hexadecimal;
- @HL in commentary indicates the contents of memory location pointed to by HL pair;
- *next to address indicates the instruction contains an address which must be recomputed if the program is relocated;
- *X indicates ASCII character X;

Note that 16 bit data format for the 8080 stores the low order byte in the lowest address, thus the hexadecimal value 8006 (for example) is seen in the listing as 06 80.

For 8 bit converters, the increment or decrement instructions at locations 0248, 0250, 0255, and 025A must be replaced by NOP instructions.
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Since one of the reasons I built a personal microprocessor was to play video games, I needed some type of high resolution graphics display capability. After examining the current unavailability of a low cost commercial product to perform this task, I decided to build my own unit. The main reason, besides cost, was that I wanted a 256 by 256 dot matrix (as you'll see below, I actually got 256 by 208). Since my system already contained a television display generator board for character information, I decided to build a graphics display unit which would utilize existing synchronization, blanking, and timing pulses. For storage of the data to be displayed, I started with a standard programmable memory board populated with 8 K eight bit bytes of 500 ns access time 2102 integrated circuits.

My design goals for this project were to:

- Utilize all possible circuitry existing on the television display interface board.
- Have the graphics display work in parallel with the existing alphanumeric character display.
- Have the ability to use the graphics display region of memory for ordinary programming purposes if the display is suppressed.
- Use direct memory access techniques (DMA) so that the graphics display data appears as ordinary programmable random access memory as far as the computer is concerned.

I was able to meet all these goals for a total cost of $25 in integrated circuits, above the cost of the existing display generator and memory boards of my system. If your system does not have an 8 K programmable memory board available, you will need to purchase one. Remember, when the graphics display is not in use, the memory can be utilized as if it were an ordinary programmable memory region; so the investment will also pay for itself in terms of raw memory power for your non graphics applications.

If your system does not have a television display generator board, the synchronization, blanking, and timing pulses can easily be generated using counters. I would suggest reading Don Lancaster's new book, *TV Typewriter Cookbook*. Chapter 4 contains...
an explanation and schematics of the circuits to generate the required pulses.

The graphics display unit functions as an interface between the processor, the 8 K memory board, and the television display generator, to provide the graphics capability. A block diagram of this interface is shown in figure 1. The graphics display unit has two modes of operation, display mode and update mode. In display mode, the unit cyclically accesses all addresses of the programmable memory board using direct memory access, then converts the output from parallel to serial, sending it to the television display generator to be combined with any alphanumeric information and displayed on the monitor or TV set. Since this operation must occur in parallel with normal processor functions, the address bus of the memory must be isolated from the processor's address bus. The output data from the memory must also be isolated from the system's data buses. In the update mode, the

---

Photo 2: With a high resolution display, games need not be kept simple. Here is an example of a much more complex game display on the author's system, again modeled after the commercial games often found in entertainment centers. To set up such a display typically requires software to create the background maze, keep track of all the movable pieces, and of course program the logic of the game simulation.

---

Figure 1: System Diagram. The graphics display unit interfaces to three elements of an existing system: The processor and its buses, the television display generator, and the 8 K programmable random access memory. The graphics display unit is normally in the display mode, where it continually displays data contained in the programmable memory module. If the processor references a location within the programmable memory's address space, the graphics display unit enters the update mode either immediately or during the next vertical blanking pulse depending upon the setting of a switch. In the update mode, the processor commands the memory and the display looks at random output bits, which are of course ignored during the blanking period.
The processor is given control of the memory's address bus and allowed to read or write data. The update mode should only be entered while the television display generator is sending a vertical blanking pulse. This prevents the update from causing a spurious blip on the screen. However the penalty for observing this requirement is that the processor may have to wait for nearly a complete television frame time, about 13.5 ms maximum in the author's system. A memory wait this long is impossible for processors such as the 6800 which do not have a memory ready mechanism, in which case an alternate mechanism such as an input port bit line could be used.

A more detailed block diagram of the functions of the graphics display unit is shown in figure 2. This design is composed of three functionally distinct areas: the three state buffers and their control logic, the counters, and the shift registers. The block diagram and details of this article assume also that the processor has a split "in" and "out" memory data bus as is utilized in the Altair 8800 or Digital Group designs.

The state of the buffers is determined by the mode in which the graphics display unit is operating. In the display mode, the buffer, block (2) in the figure, allows signals to pass while buffers of blocks (1) and (3) must be in a high impedance state. This gives the graphics display unit's counters control over the programmable memory's address bus and blocks the output data from entering the processor's data input bus. In the update

Figure 2: Detail Block Diagram. As in all "top down" system designs, the design progresses by filling in more and more detail. Here is a block diagram of the actual graphics display unit. This figure shows a detailed functional arrangement of the interface as constructed by the author. In the display mode, the graphics display unit continually cycles through all addresses in the programmable memory, outputting serial video levels to the television display generator, for mixing with existing character graphics information. In the update mode, the graphics display unit allows the microprocessor to control the programmable memory unit's address and data lines for normal access. The mode switching is automatic based upon whether or not the address sent by the processor is within the display's address space.
mode, the buffers (1) and (3) allow signals to pass while the buffer (2) is in a high impedance state. This gives the processor control of the programmable memory's address bus and allows memory to be connected to the processor's data input and address buses. The gated write strobe pulse is also enabled in this mode. Note that the processor is the only source of data written to the memory, so there is no switching of the processor data output bus which drives the inputs of the memory banks.

The mode control logic determines the proper mode of operation at any given time. It does this by monitoring the three most significant bits of the processor's address bus to determine if it is referencing a location in the programmable memory region assigned to the graphics display. If it is not referencing graphics memory, then the graphics display unit will remain in the display mode. If the processor does reference a location in the graphics display region of address space, then the television display generator is checked to see if it is generating a vertical blanking pulse. If it is, and if the graphics display is set (using S1) to prevent visual noise ("sparkle") caused by updates, then the display is changed into the update mode and the memory access takes place as if the processor were addressing an ordinary location. However if the television display generator is not in the vertical blanking period, and the graphics display is set via S1 to avoid arbitrary data during updates, then the processor is placed in a wait state until the next vertical blanking pulse is initiated, at which time the update mode is again entered. Note that this feature will only work with processors incorporating a memory ready line for slow response memories; an alternate mode of operation in which updating has priority over display must be used for processors which cannot wait.

The counters control the memory address bus during display operations, continually cycling through all locations with a full cycle taking 1/60th of a second (16.67 ms). These counters must be in synchronization with the existing counters in the television display generator. Most such television display generators contain two sets of counters. One set counts the character's position on the line. Each character is typically 8 bits wide, and there are typically 32 characters per line for a total of 256 dots per horizontal line. The other set of counters counts the number of horizontal lines which have been generated (TV scan lines, not character lines). In a typical television display without interlace there would be a maximum of 256 horizontal lines. On the television display generator board, there are pulses which clear these counters. These pulses should be used to clear the corresponding set of counters in the graphics display unit. The pulse which clears the line counters has an added significance: It also determines how many of the possible 256 horizontal lines will actually be visible on the screen. Due to overscan on a conventional television screen, the actual number of lines visible is never 256. A typical number of visible lines for a television display generator such as my Digital Group product is 208. This means that the visible display is actually a 256 by 208 dot matrix. Note that this leaves 1536 bytes of the 8192 bytes in the 8 K byte memory module free for normal programming purposes (see figure 4). To determine how many lines your particular television display generator displays, examine the logic which controls the clearing of the line counters and determine the value of the counters just prior to the clearing pulse.

The shift registers convert the parallel data from the programmable memory into a time varying string of video levels in

Photo 3: Not all outputs need be game oriented of course. Here is an example of a graphic output which could easily be used for engineering purposes: plotting the two dimensional behavior for some function. Here the author has calculated a sine wave using a BASIC package and appended various character graphics captions. The basic X-Y axes and the character graphics can be generated typically by a table lookup with some calculation; the actual points of the curve can be generated directly from the function calculation by calculating integer positions. In either case, to conveniently program the display, a set of bit manipulation subroutines is required to read and write individual bits, given the coordinates within the matrix.
Figure 3: Schematic Diagram. Taking this “top down” hardware system design one level further for a specific case yields this schematic diagram of the interface as implemented for a Digital Group system and Digital Group television display generator.
Each element of the block diagram in figure 2 is shown here in the form of actual circuitry and wiring. The memory matrix is shown as a generalized box with 8 bank selection inputs for each 1K bank within the module.
The load or shift input to the graphics display unit shift registers is controlled by the least significant address bit generated by the graphics display's counters. This bit changes state each time that a new byte is accessed in memory. The timing here is critical. The shift register which was loading data must disable its parallel inputs before the change in the address lines affects the data output from the memory. For the 2102-1 integrated circuits this time is a minimum of 50 ns. This shift register must also change from the loading state to the shifting state prior to the next clock pulse from the television display generator. This may require slightly delaying the clock pulse from the TV display generator. In my system, it required approximately 20 ns delay in the clock line, provided by using a pair of inverters in series. A data selector is used to pick the output from the shift register which is currently shifting data.

Figure 3 shows the implementation of this system for a Digital Group 8080A system, using the block diagram of figure 2 to guide the detailed design. In my description which follows, no attempt is made to explain the schematic in detail. Instead, the various components are related to the functional blocks of figure 2.

IC1, IC3 and part of IC5 make up the buffer, block (1) in figure 2, which isolates the processor's address bus from the memory in the display mode. IC2, IC4, and part of IC5 form the buffer, block (2) of figure 2, which isolates the graphics display unit counters from the memory in the update mode. IC6 and IC7 form the buffer, block (3) of figure 2, which isolates the processor's data input bus from the memory in the display mode. (The processor's data output bus is always connected to the input side of the memory, since it is the only source of data written in the memory.) IC13 and IC14 buffer the output from the memory circuits to provide the required output drive current.

IC8 and IC9 are the character counters. Note that the three least significant output bits of IC8 are left unconnected. This in effect divides the output by 8. Since each byte from the memory contains 8 bits of synchronization with the video level information generated by the existing television display generator. Two shift registers are required so that one may be loading data while the other is shifting data out. To insure that the graphics display unit video information is in synchronization with the video of the television display generator, the clock pulse for the television display generator's shift register should be used for the graphics display generator's shift registers.

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**Table 1: Integrated Circuit Power List.**

**Programming Note:** Addresses evenly divisible by hexadecimal 20 (decimal 32) in this address space allocation are the beginnings of a 256 bit (32 byte) raster scan line.

Using SHL(I, J) and SHR(I, J) to indicate the 16 bit left and right shift operations on I, by J positions, then given 16 bit integer coordinates X (horizontal coordinate from upper left) and Y (vertical coordinate from upper left down), the byte address offset of the required bit within the displayed memory region is:

\[
AB := \text{SHL}(Y, 5) + \text{SHR}(X, 3)
\]

Similarly, the rotation factor required to place a mask bit opposite the desired bit of a picture byte is given by:

\[
\text{ROTFAC} := X \text{ AND } 7
\]

(If it is assumed that an 8 bit right rotate is used and the mask starts out with a hexadecimal 80 value.)

Figure 4: Memory address space allocations for the graphics display. This figure charts the specific hexadecimal and split octal address locations for the 208 lines and free area in the author's system. Each line is represented by 32 eight bit bytes. Each byte specifies 8 consecutive dots on the screen, one for each bit. The zone at the end of the map contains the invisible section of the 8 K region devoted to this memory and display subsystem.
information, a new byte is required only after 8 bits are displayed. This assumes that a count pulse is received for each bit displayed. IC10 and IC11 are the line counters. They count the number of scan lines which have been displayed.

IC15 and IC16 are the two shift registers. Note that the clock input to these integrated circuits passes through two inverters in series. This provides the 20 ns delay required to allow the shift registers to change state from the load mode to the shift enabled mode. The output of the shift register which is shifting out data is selected by IC17 to be sent through a NAND gate to the television display generator where it is combined with the existing video display signal. Switch S2, also connected to the NAND gate IC21b, provides the capability to blank the video display from the screen. If this switch is omitted and the wire from IC21 pins 3 and 4 connected to one bit of an output port, programmable blanking of the graphics can be achieved.

IC12 is a BCD to decimal converter which is used to select one of the eight programmable random access memory banks on the 8 K memory card. This integrated circuit converts the contents of address bits A10 to A12 into a bank enable signal which drives the eight 2102s of each 1 K bank within the memory card.

IC18, IC19, IC20 and IC21 provide the mode control logic. The board address selection jumpers are connected to locate the memory at the desired position in address space. The jumpers as shown locate the visible portion of memory in addresses 8192 to 16,383 (hexadecimal 2000 to 3FFF, split octal 040/000 to 077/377). Note that in the case of a television display generator with less than 256 lines visible, the upper portion of the memory range is available for program storage. In the 208 line case of my system, the 1536 invisible bytes are located at hexadecimal addresses 3A00 to 3FF, split octal addresses 072/000 to 077/377. Figure 4 shows the layout of memory and its relationship to the displayed data. The low addresses in memory define the top of the image; the high addresses in memory define the lower portion of the image.

Since the processor is granted access to the memory only during the verticalblanking pulses in the scheme just described, programs which have critical timing may not work properly. For example, software for a cassette interface has timing requirements asynchronous to the video display and would not work properly if referencing data in the display region of memory. Switch S1 in figure 3 is provided to allow the processor access to memory at any time, without waiting. Thus when loading the display memory from a cassette tape, the conflict between the graphics display wait time and the needs of time critical software is resolved (at the expense of “sparkle” in the display during the loading). For processors which cannot wait for slow memory, S1 should be eliminated and the enable input, IC19 pin 5, should be grounded.

In making the connections from the graphics display to the television display generator and memory board, make all wires as short as possible, certainly not longer than 10 to 11 inches (25 to 28 cm). Depending upon the existing loads on the signals you are tapping, buffers may be required to drive the lines. The power bus should be heavily bypassed with .01 μF capacitors from +5 V to ground.

In Conclusion

This graphics display generator can be built very inexpensively, taking advantage of existing circuitry in the form of memory modules and a television display generator. When you’ve got it up and running, the world of visual imagery will be available to you on your television output, as is demonstrated by the examples seen in photos 1 through 3.

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A Tip for Using Wiring Pencils

R W Burhans
Avionics Engineering Center
Ohio University
Athens OH 45701

One of the problems in using the Vector or other brands of "wiring pencils" is the poor visibility of the fine #36 wire viewed against the typical background of Vector Blue circuit board material. Older types of light green epoxy fiberglass boards give somewhat better contrast and the lower quality epoxy paper board is very easy on the eyes due to its light color. Of the various colors available, the red wire has the best contrast with respect to the newer blue board materials, but even this is sometimes not good enough. The assembly of prototype hardware with this technique can be greatly improved by laying down a layer of yellow insulating tape where the pencil wrap wires are to run. We have used 3M brand yellow coil insulating tape. This is almost exactly like 0.25 inch (0.635 cm) wide tape recorder splicing tape. The yellow tape is placed on the circuit board after the common grounds and positive power buses are hard wired to the socket pins using bus strips or heavy gauge wire. Then the task of trying to see the fine wrap wires becomes much easier for the remainder of the assembly. An example showing the underside wiring of an Omega-VLF receiver interface for use with a JOLT microprocessor is shown in photo 1. [More about the Omega microprocessor interfaces will appear in a future issue of BYTE.] Small strips of the yellow insulating tape are cut and pasted to help hold the wires in place for semipermanent prototype circuits. In general we like to use hard soldered connections for prototype work where the microprocessor interface hardware is used in mobile, marine, or airborne equipment. In such applications, the effects of vibration are a major reliability consideration, hence the need of solder as a "glue" for the wiring. A combination of top of board jumper wiring and the Vector wire wrap and solder technique results in less eye strain during assembly when the yellow insulating tape is used to improve the wire visibility.
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Many people find games one of the most interesting applications of a computer system. These range from simple games such as Tic Tac Toe, Blackjack and Ping Pong to very complicated games such as Space War. All of these have one thing in common; they are much more fun when played using a video graphics display. With such terminals you can provide instant response and provide a pictorial playing area that cannot be duplicated on any type printing terminal. Can you imagine attempting to play an elaborate game on a Teletype machine? Unfortunately, the typical high resolution graphics display normally costs thousands of dollars and is completely beyond the budget of the average person.

The GT-6144 is our answer to this dilemma. By settling for a bit less resolution than is available in expensive graphics terminals we can generate graphic displays on any monitor (or a standard TV set to which a video input has been added).

In this design, the display screen is divided into an array of cells 64 positions wide by 96 positions high. Each cell is individually addressable and may be selectively turned on or off by programmed commands from the parallel interface to your computer. With a little imaginative programming (and lots of memory) fixed or

Joe Deres
Southwest Technical Products Corp
219 W Rhapsody
San Antonio TX 78216
moving images may be displayed on the screen for added enhancement to game programs. Photo 1 shows Star Trek’s star ship, the “USS Enterprise,” generated with the GT-6144 by running the program of listing 1 using data of listing 2 in an SWTPC 6800 Computer System. It takes only 2 μs to load a single cell of the display memory; much faster than most contemporary personal computers can generate the information. The system features a power up screen blanking circuit which in addition may be enabled, or disabled at any time through program commands from the computer system or hardwired switches. In addition, an image reversing feature allows you to select between white on black or black on white images by a simple one word command generated by your computer’s program. The system will operate on either 50 Hz or 60 Hz power lines with American standard 525 line or European standard 625 line television sets or video monitors.

The GT-6144 design incorporates a 6,144 bit static programmable memory which eliminates the requirement that it be used with a specific computer system. The terminal will operate with any computer system whose parallel TTL level interface outputs an 8 bit data word and data ready strobe. The hookup problem then reduces to making sure that each bit line at the interface runs to the corresponding bit at the input to the GT-6144.

The unit is available as a kit which is complete less the chassis and does not include the required video monitor or modified television set. Instructions for the addition of a video input jack to a typical television are included with the kit, and a switch installed on the back of the TV set will allow one to select between terminal and normal television operation. You may use the same television set or video monitor used by the CT-1024 terminal system. In fact, control commands from your computer allow you to display graphic, CT-1024 alphanumeric, or even a combination of the two, all on the same display device. The mixing of graphic and alphanumeric video is engineered to work with an SWTPC CT-1024 terminal. The video from other alpha-

Listing 1: A GT-6144 Demonstration Program. This Motorola 6800 program, written to illustrate the operation of the GT-6144, contains routines to erase the screen, to write a pattern using a table of commands, and to select various options under control of a simple interpreter driven by the terminal keyboard. The routine is shown in assembly language format, with an origin at location 0000. This program must be run in programmable memory without write protection since several data items are located within the program text. Relocation of the program at arbitrary addresses other than its present page 0 origin will in general require modifications of symbolic code and reassembly to eliminate direct addressing at several points. There are several gaps in the addressing sequence used, reflecting the fact that the program was hand assembled. The data used to generate the picture seen in photo 1 is summarized in listing 2.

<table>
<thead>
<tr>
<th>Address Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000 00 00</td>
<td>START</td>
<td>RMB</td>
<td>2</td>
<td>Pointer to data;</td>
</tr>
<tr>
<td>0020 00 20</td>
<td>RMB</td>
<td>2</td>
<td>Pointer to PIA address of GT-6144;</td>
<td></td>
</tr>
<tr>
<td>0004 80 0C</td>
<td>PIA3</td>
<td>RMB</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>0005 00 05</td>
<td>PIA3</td>
<td>EQU</td>
<td>PIA3+1</td>
<td></td>
</tr>
<tr>
<td>0006 FE 00 04</td>
<td>OUTGR</td>
<td>LDX</td>
<td>PIA3</td>
<td></td>
</tr>
<tr>
<td>0009 A7 00 00</td>
<td>STAA</td>
<td>G</td>
<td>OX</td>
<td>PIA3(data) := A [send data to GT-6144];</td>
</tr>
<tr>
<td>0008 C6 3F</td>
<td>LOAB</td>
<td>$E77</td>
<td></td>
<td></td>
</tr>
<tr>
<td>000D E7 01</td>
<td>STAB</td>
<td>X</td>
<td>1X</td>
<td>PIA3[control] := code for low strobe;</td>
</tr>
<tr>
<td>000F E6 00</td>
<td>LOAB</td>
<td>G</td>
<td>$X := PIA3(data) [dummy op for timing];</td>
<td></td>
</tr>
<tr>
<td>0011 C6 3F</td>
<td>LOAB</td>
<td>$E7F</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0013 E7 01</td>
<td>STAB</td>
<td>X</td>
<td>1X</td>
<td>PIA3[control] := code for high strobe;</td>
</tr>
<tr>
<td>0015 2B</td>
<td>RTS</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

* The following subroutine sends the contents of accumulator A to the GT-6144 and generates the active low “data ready” strobe at the peripheral control pin of the PIA.

<table>
<thead>
<tr>
<th>Address Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>0016 B6 3C</td>
<td>ENTER</td>
<td>LOAB</td>
<td>$A3C</td>
<td></td>
</tr>
<tr>
<td>0018 B7 80 07</td>
<td>STAA</td>
<td>SB007</td>
<td></td>
<td>Disable control interface echo option;</td>
</tr>
<tr>
<td>001E C6 FF</td>
<td>LOAB</td>
<td>$E7</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0020 E7 00</td>
<td>STAB</td>
<td>OX</td>
<td>XIA3[direction] := code for output all bits;</td>
<td></td>
</tr>
<tr>
<td>0022 C6 3F</td>
<td>LOAB</td>
<td>$E7F</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0024 E7 01</td>
<td>STAB</td>
<td>X</td>
<td>1X</td>
<td>PIA3[control] := code for high strobe, and point to data register;</td>
</tr>
<tr>
<td>0026 BD 00 A2</td>
<td>JSR</td>
<td>ERASE</td>
<td></td>
<td>clear the screen with subroutine;</td>
</tr>
<tr>
<td>0029 FE 00 DD</td>
<td>JSR</td>
<td>SHOW</td>
<td></td>
<td>fill screen with USS Enterprise or other suitable data table;</td>
</tr>
</tbody>
</table>

* The following subroutine, with entry at PUTGRPX, is used to run through a data table stored beginning at the address **START**:

<table>
<thead>
<tr>
<th>Address Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>0030 FE 00 00</td>
<td>NXTDATA</td>
<td>LOAB</td>
<td></td>
<td></td>
</tr>
<tr>
<td>0033 08</td>
<td>INX</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0034 FF 00 00</td>
<td>PUTGRPX</td>
<td>LOX</td>
<td>START</td>
<td>if @START = FF [leave when data = FF];</td>
</tr>
<tr>
<td>003A A5 00</td>
<td>LOAB</td>
<td>$OX</td>
<td></td>
<td></td>
</tr>
<tr>
<td>003L 27 16</td>
<td>CMPA</td>
<td>$FF</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
| 0040 B8 00 | ADDA | $0 | | *
| 0042 BD 00 06 | NEWXSPOT | JR | OUTGR | *
| 0045 FE 00 09 | STAB | LOX | START | *
| 0048 0B | INX | | | *
| 0049 FD 00 06 | STX | START | | *
| 004C A6 00 | LOAB | $OX | |
| 004E B1 FE | CMPA | $FF | |
| 0050 27 DE | BEQ | NXTDATA | | [as horizontal position if FE]; *
| 0052 B8 00 | ADDA | $0 | * |
| 0054 20 EC | JMP | | | *
| 0056 39 | ENDPUT | | | return to caller; |

* The following function subroutines are used to set up the PUTGRPX, routing, by modifying two bytes of code and setting up the initial pointer in START at location 0000;

<table>
<thead>
<tr>
<th>Address Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
</table>
| 0057 B8 40 | ADDA | $40 | | [is defined prior to entry]; *
| 0059 B7 00 41 | STAA | DISP+1 | | [is defined prior to entry]; *
| 005C 17 | TBA | | | *
| 005D B9 80 | ADDA | $B8 | |
| 005F B7 00 53 | STAB | DISP2 | |
| 0062 FF 00 00 | STX | START | |
| 0065 B9 00 31 | STAB | PIA3 | |
| 0068 39 | RTS | | | return to caller;

* DELAY is a routine to generate a delay in processing, the parameter (approximately calibrated in seconds) is passed to the B accumulator; routine uses A and X.

<table>
<thead>
<tr>
<th>Address Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
</table>
| 0070 B6 00 | DELAY | LOA | $0 | A := 0 [outer loop count]; *
| 0072 CE 00 00 | NEWLNR | LOX | $0 | X := 0 [inner loop count [loop calibration]]; *
| 0075 08 | DELLOP | | | |
| 0076 CF FF | CPX | | |
| 0079 27 02 | BEQ | OUTER | | then go to OUTER loop check; *
| 007A 20 F8 | FILL | DELLOP | | else enter inner loop; *
| 007D 4C | OUTR | INCA | | A := A + 1; *
| 007E 27 CF | BRA | OUTER | | |
| 0081 27 02 | BRA | DELAYDON | | then go to DELAYDON; *
| 0083 29 EF | BRA | NEWLNR | | [to new inner loop]; *
| 0083 29 | DELAYDON | RTS | | return to caller; |

* The ERASE subroutine in locations 0000 to 000C is used to clear the GT-6144 screen prior to establishing a new picture; it does this by addressing each display location in turn and setting a null state.

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Listing 1, continued:

<table>
<thead>
<tr>
<th>Address</th>
<th>Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>00A0 00</td>
<td>HPOS</td>
<td>RMB 1</td>
<td></td>
<td></td>
<td>horizontal position data byte;</td>
</tr>
<tr>
<td>00B0 00</td>
<td>VPOS</td>
<td>RMB 1</td>
<td></td>
<td></td>
<td>vertical position data byte;</td>
</tr>
<tr>
<td>00A2 96</td>
<td>ERASE</td>
<td>LDAA HPOS</td>
<td>START</td>
<td></td>
<td>[entry point, outer loop for horizontal position];</td>
</tr>
<tr>
<td>0181 40</td>
<td>CMPA</td>
<td></td>
<td></td>
<td>#00</td>
<td>if HPOS $40 (is it end of outer loop)?</td>
</tr>
<tr>
<td>00A6 27</td>
<td>BEOU</td>
<td></td>
<td></td>
<td></td>
<td>then go to OUT (erase is done).</td>
</tr>
<tr>
<td>00A8 01</td>
<td>NO</td>
<td></td>
<td></td>
<td></td>
<td>[two do nothing NOPs];</td>
</tr>
<tr>
<td>00AA B0 00</td>
<td>JSR OUTGR</td>
<td>define horizontal coordinate;</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>00AD 96</td>
<td>A1</td>
<td>LDAA VPOS</td>
<td>START</td>
<td></td>
<td>[inner loop for vertical position];</td>
</tr>
<tr>
<td>00B1 27</td>
<td>BEOU</td>
<td></td>
<td></td>
<td></td>
<td>then go to SPEC and restart inner loop;</td>
</tr>
<tr>
<td>00B3 8B</td>
<td>ADDA</td>
<td>#10</td>
<td></td>
<td></td>
<td>convert coordinate to vertical command;</td>
</tr>
<tr>
<td>00B5 8D 00</td>
<td>JSR OUTGR</td>
<td>define vertical coordinate and value;</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>00B7 9C</td>
<td>INC</td>
<td>VPOS</td>
<td></td>
<td>#00</td>
<td>VPOS = VPOS + 1;</td>
</tr>
<tr>
<td>00B8 20</td>
<td>BRA</td>
<td>ERASE</td>
<td></td>
<td></td>
<td>reiterate inner loop;</td>
</tr>
<tr>
<td>00BD 86</td>
<td>SPEC</td>
<td>LDAA #00</td>
<td>START</td>
<td></td>
<td>enter loop for horizontal position;</td>
</tr>
<tr>
<td>00C1 7C</td>
<td>INC</td>
<td>HPOS</td>
<td></td>
<td>#00</td>
<td>HPOS = HPOS + 1;</td>
</tr>
<tr>
<td>00C0 20</td>
<td>BRA</td>
<td>ERASE</td>
<td></td>
<td></td>
<td>reiterate outer loop;</td>
</tr>
<tr>
<td>00C6 66</td>
<td>OUT</td>
<td>LDAA #00</td>
<td>START</td>
<td></td>
<td>(two do nothing NOPs) ;</td>
</tr>
<tr>
<td>00C8 97</td>
<td>A0</td>
<td>STAA VPOS</td>
<td>STOP</td>
<td></td>
<td>(inner loop for vertical position);</td>
</tr>
<tr>
<td>00CC 39</td>
<td>RTS</td>
<td></td>
<td></td>
<td></td>
<td>return to caller;</td>
</tr>
</tbody>
</table>

* The SHOW routine is used to define the parameters of DISPLAY, |
  * pointing to the inner loop for horizontal position and its data table, |
  * then to call DISPLAY; since the vertical and horizontal |
  * positions are parameters, the picture can be located at arbitrary |
  * places within the display of the GT-6144; |

* The OPTFUNC routine is reached after the display is set up |
  * on the screen and is used to interpret several commands |
  * from the terminal keyboard in order to toggle some of the |
  * options of the display unit. |

* Each individual command is implemented by defining a constant |
  * in the A accumulator, then jumping to EXECUTE in order to call |
  * OUTGR and modify the state of the GT-6144; |

* The coordinate of a particular location is |
  * determined by the binary number in low order |
  * bits B5 to B0. When bit B6 is 0, a rectangle |
  * will be removed at the desired coordinates; |
  * when B6 is 1, a white rectangle will be |
  * generated. 0 in bit B7 causes the data |
  * holding flip flops in the terminal to store the |
  * present data. |

* The SHOW routine is used to define the parameters of DISPLAY, |
  * pointing to the inner loop for horizontal position and its data table, |
  * then to call DISPLAY; since the vertical and horizontal |
  * positions are parameters, the picture can be located at arbitrary |
  * places within the display of the GT-6144; |

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  * present data. |

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  * pointing to the inner loop for horizontal position and its data table, |
  * then to call DISPLAY; since the vertical and horizontal |
  * positions are parameters, the picture can be located at arbitrary |
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  * on the screen and is used to interpret several commands |
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  * options of the display unit. |

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  * in the A accumulator, then jumping to EXECUTE in order to call |
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* The coordinate of a particular location is |
  * determined by the binary number in low order |
  * bits B5 to B0. When bit B6 is 0, a rectangle |
  * will be removed at the desired coordinates; |
  * when B6 is 1, a white rectangle will be |
  * generated. 0 in bit B7 causes the data |
  * holding flip flops in the terminal to store the |
  * present data. |
the terminal. The vertical coordinate of all other characters that have this same horizontal coordinate can then be loaded by themselves since the horizontal position is latched in the terminal’s holding flip flops. This second method is used by the programs accompanying this article.

Since there are 96 characters to be accessed in the vertical direction at least seven address lines must be used. Seven lines give the possibility of addressing 2^7 (128 decimal) locations giving us 32 extra undefined locations. These extras can be used as control commands for controlling blanking on and off, reverse screen, etc. The format for control commands for the GT-6144 display generator is found in figure 2.

When writing programs care should be taken to optimize them for speed and memory conservation. All of the above functions can also be under hardware control by using SPST push button switches.
Photo 2: Here is a picture of the GT-6144 as constructed using the printed circuit board and parts supplied with the Southwest Technical Products kit. The logic diagrams of figures 1 to 3 are complete and based upon the original blueprint supplied by the author. Home brewers can use the design information of this article to wire up the circuit described here, or as a starting point in designing a customized version.

HORIZONTAL COMMAND FORMAT:

INTERFACE BIT → 7 6 5 4 3 2 1 0

<table>
<thead>
<tr>
<th>0</th>
<th>D</th>
<th>HORIZONTAL POSITION H</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 ≤ H ≤ 63</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

DATA BIT:
1 = BRIGHTEN A CELL
0 = ERASE A CELL

FORMAT INDICATOR, VALUE 0

VERTICAL COMMAND FORMAT:

INTERFACE BIT → 7 6 5 4 3 2 1 0

<table>
<thead>
<tr>
<th>1</th>
<th>VERTICAL POSITION V</th>
</tr>
</thead>
<tbody>
<tr>
<td>0 ≤ V ≤ 95</td>
<td></td>
</tr>
</tbody>
</table>

FORMAT INDICATOR, VALUE 1

Figure 1: Data Formats for the Parallel Interface to the GT-6144. The GT-6144 has two data formats. The horizontal command format is used to set the sense of the data to be written and load a 6 bit integer horizontal coordinate. Once the horizontal coordinate has been set up, the vertical command format is used to pick a vertical line with a 7 bit integer less than decimal 95 in value, and write the data value (“on” or “off”) selected with the horizontal command.

How It Works

The entire screen of this video display has been arranged for 96 lines of 64 characters per line. In addition to the 96 lines of video data the television or monitor also requires the terminal to generate vertical and horizontal sync pulses. The GT-6144 consists of two major sections. The timing sections (figure 3) generate the necessary sync pulses, while the memory section (figures 4 and 5) takes care of storing the necessary information and recalling it while a frame is being generated.

The timebase oscillator as indicated in the schematic is responsible for initiating the horizontal sync pulse and for starting the chain of events that will generate one line of video data to be displayed. The circuit itself is a phase locked loop employed as a frequency multiplier. A 555, IC1, is used as an astable voltage controlled oscillator. The 2N5139 transistor Q3 and T1558 field effect transistor Q1 along with capacitor C5 form a sample and hold circuit which feeds IC1’s voltage control input through the TIS58 field effect transistor Q2. The sample and hold in this case is being used as a phase comparator providing an output voltage proportional to the phase difference of the 60 Hz power line and the multiplied output frequency of the 555 oscillator IC1. The
The actual amount of frequency multiplication is equal to the amount of frequency division between the output of the oscillator IC1 and the 60 Hz input reference frequency. As you will see later the value of the frequency divider is 264 and since our reference is 60 Hz so that:

\[ f_o = (60 \text{ Hz}) \times (264) = 15,840 \text{ Hz} \]

which is very close to the horizontal oscillator frequency of a standard television set.

The output of IC1 is fed via inverter IC23c across a jumper to IC17 sections b and c, where among other things a 4 \( \mu \text{s} \) horizontal sync pulse is generated. From here the pulse is routed to IC15b where it is ORed with the vertical sync pulse which will be described in detail later.

The falling edge of this sync pulse at the output of IC17c triggers IC16a, a one shot which puts out a positive pulse on pin 4 adjustable by potentiometer R20 from 10 to 30 \( \mu \text{s} \) in length. The delay pulse creates a lag between the start of a line and the beginning of data, thus giving an adjustable left margin. Pin 4 of IC16a inhibits dot oscillator IC16b through AND-OR-INVERT gate of IC10a.

IC16a resets 7493 counters IC19 and IC13, the 16 bit counters which address one of the horizontal positions on a line. Since we are just starting a new line we must first clear the counter to prepare for incoming data. At the end of a high to low transition of pin 4 of IC16, the 7493 vertical position counter IC6 is incremented; and if there is a ripple carry, IC7 is incremented as well. IC6 and IC7 together keep track of the vertical scan lines presently in use: Together these two counters provide a unique binary code for each of the 96 \( * 2 = 192 \) video scan lines generated by the GT-6144.

Now for those of you who are familiar with television circuits, you probably know that we need more like 264 lines and not 192 for a complete frame. When a count of 192 (the 193rd line) is reached, IC15a sends out a clock pulse to IC4a and to IC9c which resets the line counters. When IC4a is clocked pin 6 goes low, giving a blanking pulse to prevent any video data from being transmitted from the GT-6144. When pin 6 of IC4 is low, pin 5 is high and enables decoders IC11a and IC11b. When the line counters reach a count of 32, IC11a triggers and remains so for 8 lines until count 40 is reached. The low output on pin 6 during this time is the vertical sync pulse, which goes to IC15b as mentioned earlier. At count 72 IC11b triggers clearing flip flop IC4a which unblanks the video and resets line counters IC6 and IC7 for the generation of another line of displayed data. The above circuitry gives us a total of 192 + 72 = 264 scan lines.

**Figure 2: Data Formats for the Control Commands.** The unused states of the vertical command format described in figure 1 are used to perform control operations. The control format and operations are shown here. Note that in the program of listing 1, the contents of bits 3 and 4 are assigned zero value arbitrarily since they are "don't care" inputs in control commands.
Figure 3: Timing Logic. This figure shows the design of the video timing chain which governs the operation of the GT-6144. The original diagram of the circuit has been partitioned into three figures for this article, with connections between figures indicated by symbolic names and references to the connecting figure. Power connections for the integrated circuits in figures 3, 4 and 5 are listed in table 1, and the three jacks used for interconnection are summarized in table 2.
very hard if not impossible to see with most oscilloscopes. This clock is used to toggle flip flop IC4b which regulates the transmission data from memory to the video output. When IC4b is clocked by the dot clock, the data input on pin 12 from the memory is latched until another clock pulse appears.

The second major portion of the GT-6144 (figures 4 and 5) consists of the memory and its associated components.

When no data is being loaded into the terminal by a computer, appropriate outputs from both the horizontal and vertical counters are used as address lines for the memories. IC18 and IC37 and the necessary inverters form the decoders that select the appropriate memory integrated circuit (ICs 27, 28, 29, 31, 32 or 33) depending on the location being addressed. Note that IC31 to IC33 can be enabled when CB0 = 0 while IC27 to IC29 can be enabled when CB0 = 1, therefore adjacent rectangles alternate back and forth between the two halves of memory. The data outputs of IC27 to IC29 are “wired OR” as are the outputs of IC31 to IC33. AND-OR-INVERT gate IC10b selects which data will be transmitted to the video output depending on the state of CB0.

The desired display for our graphics terminal is 64 cell positions across and 96 cell positions down. This gives a total of 6144 possible character positions which means that at least 13 address lines are needed since $2^{12} = 4096$ and $2^{13} = 8192$. Since some computers are not capable of sending out a 16 bit word, the most logical position (bit 7 is 0) IC30b will trigger, causing the data present to be latched into the flip flops. During this time the memory is unchanged. If the data present is a vertical position (bit 7 is 1) IC30b will not change state but IC39a or IC39c will, depending on the state of the latched low order bit 0 on pin 5 of IC41b. If IC41b pin 5 is 0, IC39c will go low. When the counters come around such that CB0 is 1 (the opposite side of the memory currently accessed by the video timing chain), IC40c will change state causing the data selectors IC24 to IC26 to select the address lines formed by the data from the computer rather than from the counters. IC18 will select and enable the correct memory integrated circuit and after a small time delay caused by C13, R31 and IC15c, a low write pulse will be routed to the enabled memory. When the DATA READY goes back to its high state the write pulse will immediately disappear and after a small delay caused by R36, C17 and IC38b, the memory circuit will be disabled and the data selectors will return to addresses taken from the terminal’s video timing chain. Note that the data is written in one half of the memory while the terminal reads and outputs data from the other half. The other half of memory works exactly as above but has BO equal to 1.

Text continued on page 54
Figure 4: Input Logic. This figure contains the input control logic used to store the horizontal command information and decode the vertical command or control command information.

NOTE:
UNLESS SPECIFIED OTHERWISE-
RESISTOR VALUES ARE IN OHMS.
CAPACITOR VALUES ARE IN pF.
DIODES ARE IN9/4 / IN4148.
Figure 5: Memory Logic. This figure contains the logic associated with the memory of the GT-6144. The 6144 bits of information used for the graphic output are contained in six 2102 memory integrated circuits.
When the computer sends out data where the high order bits B5, B6 and B7 = 1 (the control command mode), IC42 pin 8 goes high so that no changes will be made in memory. Appropriate data lines from the computer are fed to the 7442 decoder IC14. IC39b disables the decoder in all but the control command mode. Depending on the data in low order bits 0, 1 and 2 of the input to the GT-6144, the proper output of IC14 is brought low to control the appropriate control function. The outputs of IC14 are latched in the 74279 circuit IC2. Pin 4 of IC2 controls the screen reversing function. IC34 prevents the screen from being reversed except immediately after a vertical sync pulse. While in the reversed mode the blanking pulse is removed, giving a totally white screen (except for characters). This switching is done in IC3b. IC2 pin 7 controls the CT-1024 video data. When IC3 pin 4 is high CT-1024 data is enabled and disabled when pin 4 is low. Pin 9 of IC2 performs a similar enabling or disabling function for the graphics video data. Video data from IC3 pin 6 is routed to IC15d where it is mixed with the appropriate blanking pulse. The outputs of IC15b and d are then mixed in 2N5129 transistor Q4 to give the required composite video output.

As shown in figures 3 to 5 the GT-6144 unit should work on a video monitor or modified television set. Because of rigid FCC requirements, the circuit has been designed to be connected directly to the video input circuit of a television. This typically requires the addition of a jack and if normal television reception is desired as well, a switch to select the operating mode.

The data outputs from your computer must be at TTL low state for a logical 0 and TTL high state for a logical 1. The DATA READY line must stay at logical 1 normally and go to 0 only after the data from the computer to be loaded into the terminal is guaranteed valid. The DATA READY strobe should stay low for at least two microseconds and the data must stay valid during this time. Cable lengths from the computer to the terminal should be as short as possible.

If desired the video from a SWTPC CT-1024 can be mixed with the video from the GT-6144 to give an alphanumeric or graphic display (or both) on the same TV or video monitor. No extensive modifications need be made to the CT-1024 but four wires do need to be added through J2.
OUR FD-8 FLOPPY DISK SYSTEM interfaces to anybody’s microcomputer system via a single PIA chip!
If you don’t use PIA’s, then one 8 bit bidirectional data port and one output only control port is all that’s required — that simple! If you don’t have a bidirectional port then separate input and output ports will do.
Full sector buffering in 3K of RAM contained on the controller card itself eliminates any dependence upon processor speed.
Each drive is contained in its own cabinet with power supply. Up to 4 drives may be daisy chained together and selected under software control from a single controller card.
Both single and double density, single or multiple drive units are available.
Complete F DOS software for both 8080 and 6800 systems is provided at no additional charge. Including: disk driver subroutines, variable length file management system, disk assembler/editor, and integration with basic.

MSI introduces the PR-1 PROM Programmer and verification module for use with microprocessor systems.
The PR-1 interfaces to any microcomputer system via a single PIA chip. The unit is designed to program 1702A PROMS. Complete software for PROM programming is provided with the system at no additional charge.
MSI software products including our mini assembler, disassembler, and basic are now available on KC standard cassettes. Please specify either paper tape or cassette when ordering.

For the past 6 years MSI has been a leading manufacturer of microcomputer data handling systems for medical laboratories, so we’re not new to the business. Four years ago we introduced the first floppy disk system for programmable calculators, which is still in production today. We manufacture CRT terminals, PROM programmers, and a large selection of instrumentation interfaces.
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Equipment & Supply Corp.
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(312) 634-0076

Midwest Scientific Instruments
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Some Graphics Background

Computer graphics has come a long way since its inception as a laboratory curiosity. It is now a widely used tool for human information digesters. There is the old saying: “One picture is worth one thousand words” and thus information packed into computer generated pictures is now used by such diverse people as engineers, doctors, business people, and choreographers. We are now at the point where TV compatible graphics displays are affordable by hobbyists, experimenters, and other randomly assorted computer freaks.

Graphics hardware has also evolved far from the early dedicated processors and point by point plotting oscilloscopes to today’s high resolution plasma displays (the so-called flat TV screens), computer generated holograms, and intelligent multicolor vector displays. The vast majority of commercially available graphics, however, is still based on some kind of single color cathode ray tube. Even among the monochrome displays there are two different families of design, the storage tube design, and the continuously refreshed design. The purpose of this article is to present some background information on the philosophies represented by these two types of CRT systems, since they are important differences and have a large effect on the type of graphics each is capable of producing.

Storage Tube Graphics

Storage tube techniques can well be described as drawing on a paper pad with indelible ink. A line, once drawn, cannot be erased, except by tearing off and throwing away the entire sheet of paper. In other words, once completed, individual sections of a picture (also called subpictures, or glyphs) cannot be electronically deleted or moved without destroying and then redrawing the entire picture. The need to redraw the entire screen might not be so bad, if it were not for the “erase flash,” and the usually slow speed with which the graphics terminal communicates with the computer. The erase flash is a bright wink that always occurs when you wipe off the screen of a storage tube. The slow speed is a mixed blessing, actually. These terminals are almost always used remote from the computer, and use simple asynchronous serial data lines, usually around 300 baud, to talk to the computer, just like a raster scan video display terminal. Using an ordinary telephone line for cheap communication, it can take several minutes to draw a reasonably complex image at 300 baud. At the very least, animation graphics, like Space War or LIFE, would prove cumbersome, and disappointing due to communications line limitations. These terminals are best suited for high resolution still lifes such as charts and schematics. Accessories to produce hard copy from the screen are usually available. Storage tube terminals have the advantage of being quite useful at great distance from the processor. They are also comparatively simple in design and cheap to build. The exception is the price of the storage CRT, which can run over $1000 in “onesies” for a large high resolution tube, probably explaining why they are not often seen in amateur computing circles.

Continuous Refresh Graphics

The continuously refreshed or graphics processor type of display is like the storage tube display only in the way in which it draws a line or vector. There the similarity ends. In this system, vectors disappear almost as fast as they are created. An image appears of constant intensity because it is redrawn or refreshed many times a second. This illusion, called flicker fusion, is the same principle by which the TV and movie industry simulate continuous motion. If an image flickers fast enough, the brain perceives it as continuous. Obviously, if there are many lines in the image, there has to be a very fast link between the display and the memory where the image data resides, in order to refresh the screen in the usual 1/30 second (or 1/60 second for TV without interlace). Since drawing a previously created image is just a matter of shipping the picture information off to the display, and therefore requires no great amount of com-
Perhaps the most dramatic example of the need for high resolution graphics is demonstrated by these pictures of the famous "original" lunar lander program written for the Digital Equipment Corporation GT-40 and supplied with that unit as a demonstrator. These pictures were made by the author using University of Wisconsin facilities, and illustrate a couple of typical frames from the interactive graphics version of lunar lander.

Photo 1: The lunar module is controlled by a light pen, and is seen initially high above a lunar plane.

Photo 2: Eventually, if all goes well, the pilot (with his or her magic wand control stick) lands the lunar module near the golden arches of a famous fast food chain, orders some food, takes off and leaves.

Photo 3: Of course, if mistakes occur, there is a crash. This picture shows the flying lunar lander above a lunar mountainside with "rocks" and the remains of previous crashes of the module by inept pilots.

With the 256 by 256 graphics capabilities of the newer display output devices for televisions, the personal computer is getting close to the resolution needed to do the lunar lander simulations shown here, at a far lower price than was previously possible.
### Table 1: Some graphics display devices listed for comparison.

<table>
<thead>
<tr>
<th>Professional Systems of interest to individuals</th>
<th>ISC</th>
<th>SWTPC</th>
<th>Cromemco TV Dazzler</th>
<th>MiniTerm Assoc</th>
<th>Merlin</th>
</tr>
</thead>
<tbody>
<tr>
<td>Feature</td>
<td>Dec/GT-40</td>
<td>Raster scan</td>
<td>Raster scan</td>
<td>Raster scan</td>
<td>Raster scan</td>
</tr>
<tr>
<td>Design Type</td>
<td>Tektronix 4006-1</td>
<td>Refresh vector</td>
<td>DMA</td>
<td>Hardware</td>
<td>Hardware</td>
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<tr>
<td>Interface</td>
<td>DEC GT-40</td>
<td>Raster scan</td>
<td>DMA</td>
<td>Hardware</td>
<td>Hardware</td>
</tr>
<tr>
<td>Point Plotting</td>
<td>GT-40</td>
<td>Intecolor</td>
<td>Hardware</td>
<td>Software</td>
<td>Software</td>
</tr>
<tr>
<td>Vector Graphics</td>
<td>GT-6144</td>
<td>DMA</td>
<td>DMA</td>
<td>Software</td>
<td>Software</td>
</tr>
<tr>
<td>Resolution</td>
<td>Low</td>
<td>64 x 64</td>
<td>Low</td>
<td>Software</td>
<td>Software</td>
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<tr>
<td>Drawing Speed Limitations</td>
<td>1024 x 768</td>
<td>200 µs per vector (fixed)</td>
<td>64 x 64</td>
<td>Software</td>
<td>Software</td>
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<tr>
<td>Character Generation</td>
<td>High</td>
<td>256 x 256</td>
<td>High</td>
<td>Software</td>
<td>Software</td>
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<tr>
<td>Blinking</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>Remote Operation</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>Altair Bus Plug in?</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>Multicolor?</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>Is Animation Possible?</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>Hard Copy (Not Photos)</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>Built-in Display?</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>ROM Software in System</td>
<td>Not applicable (used with large systems)</td>
<td>Only a bootstrap</td>
<td>Only a software</td>
<td>Only a system monitor</td>
<td>MERLIN monitor</td>
</tr>
<tr>
<td>Price (Kit price if available that way)</td>
<td>Medium</td>
<td>High</td>
<td>Medium</td>
<td>Medium + $630</td>
<td>Medium + $630</td>
</tr>
<tr>
<td>Kit or Assembled</td>
<td>Assembled</td>
<td>Assembled</td>
<td>Kit</td>
<td>Kit</td>
<td>Kit</td>
</tr>
<tr>
<td>Design Class</td>
<td>High price</td>
<td>High price</td>
<td>Complete system</td>
<td>Integral plug in for color graphics</td>
<td>Medium resolution black box</td>
</tr>
</tbody>
</table>

**EDITOR’S NOTES**

This table is by no means complete. It is intended to cover a spectrum of different systems with different prices and different user orientations. If each column is considered to be a class of product, then the device shown is a typical member of that class. The rationalizations for selection are roughly as follows:

- The DEC GT-40 and the Tektronix 4006-1 are included for comparison purposes only to contrast prices of commercial equipment intended for use with large scale installations. The GT-40 virtually requires a minicomputer, and is a very flexible (if now slightly outdated) system widely used by graphics hackers at university and research institutions. The Tektronix product and related products are within the range of a moderately wealthy private computer hacker, but are hardly products for mass consumption. The 4006-1 is also widely used in the university and research communities.
- The ISC system is an example of a complete system — computer, video display (color) keyboard, and systems software in ROM – which is available in kit form at a price within the range of an individual.
- The Southwest Technical Products GT-6144 is a low resolution, low price stand alone product, intended to be absolutely the least expensive approach to the graphics output problem. The intention is quite well fulfilled. It does require a television or monitor, however, as do all the amateurs’ products except the ISC system.
- The Cromemco TV Dazzler is the first Altair bus compatible product available to amateurs at a reasonable cost.
puting, we needn't bother the main processor. Instead, we offer the display direct access to the memory where the image is kept. There are two ways to do this; the first is to allow the display to cycle steal, or have “direct memory access.” This is the way many high performance commercial systems, like the DEC GT-40, work. This method does not allow the display to be far removed from the computer and its memory. In the GT-40, for example, the input to the display is about six inches from the memory board.

The other approach is to give the display its own memory for the image, and its very own simple processor to keep track of what is going on with the display. The central processor then is allowed access to the display memory, and need only concern itself with the display when it wants to change the image. Thus the display can cycle through its own memory as it pleases, and the CPU can modify the image at a rate determined by economy and necessity. This is the method used by the typical homebrew or commercial video display used by BYTE readers. The local memories which have been used in these devices range from delay lines, shift registers, and programmable random access core or semiconductor memories for alphanumerics, up to dedicated disks for multicolored high resolution applications which require vast amounts of storage.

The primary advantage of continuously refreshed graphics is high speed. This is the mode in which animation work is most often done. Since the images are stored in memory they are very easily manipulated at high speed. The resolution can be made equal to or better than storage displays.

The currently popular personal systems displays use the refresh graphics method in combination with a video raster scheme. Instead of directly drawing vectors on a screen, they can only mark points that lie along the closely spaced parallel horizontal lines that make up a normal TV raster. The effect is to limit the maximum resolution to about one third that of commercial vector displays. There is also an additional software burden on the processor whenever it is desired to simulate vector and character hardware.

The chart accompanying this article as table 1 summarizes the characteristics of several representative graphics display devices. Take this table with a grain of salt, though, because today’s specs are tomorrow’s history. I expect that the features of amateur raster scan devices will eventually come close to the commercial continuous-refresh display, except, of course, for price.

---

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**ALTAIR 8800 OWNERS**

We recently received the following letter:

RUN 10 7 8 1 5 3

GENTLEMEN:

I just wanted to tell you that I think your clock fix kit is really great! I was having trouble running BASIC and after installing your kit four of my kits ceased that weren't running came back to life and now all helpfully me to write this letter on the computer. Enclosed is another order for a clock kit. This is for the second kit that I'm now in the process of building.

Sincerely

Lucy L. Smith

How well does your Altair run?
A Clock Fix Kit is only $15 postpaid.

---

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Sincerely

Lucy L. Smith

How well does your Altair run?
A Clock Fix Kit is only $15 postpaid.
The Pennywhistle 103 Acoustic Coupler is the first professional quality modem available in kit form. The Pennywhistle may be used either as an acoustic coupler (with the telephone handset) or it may be wired directly into the telephone. In either case, the Pennywhistle will operate in both the half-duplex (unidirectional) or the full-duplex (bidirectional) modes.

Without critical speed requirements for the recorder and it is able to communicate directly with another modem and terminal for telephone “hamming” and communications for the deaf. In addition, it is free of critical adjustments and is built with non-precision, readily available parts.

One of the most significant problems associated with modems is that there is often difficulty in determining the difference between a signal of the proper frequency and one of its harmonics. The Pennywhistle 103, however, employs a three-stage active filter which prevents noise and harmonics from getting through.

The Pennywhistle kit includes everything needed for the entire unit. All electronic components mount on a 5” by 9” printed circuit board. The kit also includes all chassis parts, speakers, speaker grilles, muffs and line cord.

But just as important, the Pennywhistle is backed up with a complete documentation manual. This manual describes - in detail - what a modem is and how it works. All theory of operation discussions are keyed to a block diagram and schematic. This manual also contains a thorough set of assembly, test and adjustment instructions as well as directions for hooking the Pennywhistle up to an audio source.

The Pennywhistle 103 modem kit is $109.95 (plus $2.50 for postage and handling) and is available from M&R Enterprises, P.O. Box 61011, Sunnyvale, Ca. 94088. California residents add 6% sales tax. Allow approximately four weeks for delivery.
Introducing A Remarkable New Microcomputer:

The Astral 2000

You're reading this ad, so you're obviously interested in getting a microcomputer. You're probably also a bit confused by the number of different microcomputer kits around today. So, think about the things you want in a microcomputer. Ease of assembly, quality power supply, well designed cabinet and interconnect scheme, peripheral and memory options for an expanding system.

Some Kit!

Although we have called the Astral a "kit", it actually arrives over 70% assembled. The power supply, processor board and RAM board are fully assembled, burned in and tested before shipment.

There is no complicated wiring harness. In fact, there is no front panel wiring harness at all. The front panel plugs directly into the backplane. Additional circuit boards are inserted through the rear of the chassis directly into the backplane.

Complete System

The Astral 2000 is shipped with power supply, cabinet, front panel components, mother board, processor board and one 8K RAM board. The processor is 6800-based and operates in serial and in parallel. Both RS-232 and 20mA current loop are provided by a serial I/O socket on the processor. This processor is shipped with our own 16K monitor ROM and has provisions for "cycle-stealing" DMA. The memory board contains 8K of low power, 500ns static RAM and uses less than 1.6A at 5V.

Lots Of Options

A computer isn't much fun if you can't talk to it. But you can talk to the Astral with the VID-80 video terminal board for only $189.95 unassembled ($245 assembled). The VID-80 has a selectable line length of 64, 72 or 80 characters per line. It displays 16 lines of upper case characters but gives you the option of installing a lower case character ROM as well.

We also have somewhere for you to put your programs. Our 8K EPROM board ($59.95) is designed for the 5204 and will allow in-system program storage even during power-down. This board is assembled with all components except the EPROMs, however sockets are provided for the memory chips.

We've solved program loading, too. The I/O tape interface unit ($49.95) plugs into the I/O socket on the processor board and allows programs to be loaded from any inexpensive, non-digital tape deck. But if tape cassette isn't fast or big enough, a floppy disk with an Astral bus-compatible controller will be available for under $1,000 in the last quarter of 1978.

A New And Powerful BASIC

A unique and powerful version of BASIC with features never seen before in an 8K version has been designed especially for the Astral system. Astral BASIC contains all the features of competing BASICs and then some; Astral BASIC is also very fast.

With the User Selectable Floating Point package, the user chooses the degree of precision from the four choices of 6, 9, 13 or 16 digits. Fewer digits use less memory and is faster, however higher precision are useful for scientific and mathematic applications.

The Astral BASIC's DO statement is unique; it has never appeared in any other version of BASIC. The DO statement is a simple and flexible way to subroutine without the restrictions of formal subroutines. DOs can be nested, too — of course — Astral BASIC has all the other standard subroutine procedures as well.

The Trace Mode is another feature rarely found in other BASICS. The Trace Mode is used in program debug to list statement line numbers as executed. This feature may be programmed to Trace On only for routines still needing check-out. Pressing the escape key halts the trace and returns control to the terminal.

The Astral BASIC string facility permits variable length strings of unlimited length and includes the ability to search for a substring within another larger string, a particularly useful feature for word processing applications.

Powerful program editing capabilities allow loading, listing and saving of programs. Blocks of statements may be deleted or renumbered. The RENUMBER statement may be used to increment all specified line numbers and it automatically adjusts the numbering of any GO TOs, etc.

Another feature never seen before in an 8K version is the popular PRINT USING statement. PRINT USING permits floating "$", "+" and "-" signs as well as floating commas, so numbers such as $1,000,000+ can be printed in the standard accounting format.

The Astral 2000 is $935 partially assembled ($1250 fully assembled) plus $14 for shipping and handling ($18 for Canadian orders). Additional 8K RAM boards are $245 each. California residents add 6% sales tax. The Software Package includes Astral Basic on magnetic tape cassette or paper tape, the game of Star trek, complete documentation and a free one year subscription to the Astral Newsletter, all for $35. For more details, send a self-addressed, 8½ by 11 stamped envelope to M&R Enterprises, P.O. Box 61011, Sunnyvale, Ca. 94088. Allow approximately 8 to 12 weeks for delivery.
Product Description:

The MERLIN Video Interface Adds a Visual Dimension to Your Altair or IMSAI

MERLIN (trademark of MiniTerm Associates) is a new concept in peripherals modules for mainframe microcomputer systems. It is a combined hardware and software package which provides a keyboard video interface with 20 lines of 40 ASCII encoded characters, graphics with a resolution of 100 by 160 points, and read only memory software for Monitor and Editor programs. The entire price of this unit, $249 plus $34.95 for the ROM software, is within the budget of many small systems users. In fact it is hard to find a combination of the features MERLIN has which even approaches the cost effectiveness of this two card Altair and IMSAI compatible plug-in system. Output is an EIA standard video signal to drive a TV monitor or modified television set.

MERLIN'S two boards provide far more than just an ASCII and graphics interface. A sophisticated DMA controller allows MERLIN to display information from any part of the computer memory. Also, since the display starting address is software controlled, the memory segment displayed can be changed with every screen refresh.

The number of ways in which the memory selected can be displayed boggles the mind. And since the display mode is software controlled, it too can be changed with every refresh. One useful mode option saves memory by beginning a new line whenever a carriage return is detected – eliminating the need for spaces to the end of a line. This enables typical text or program source code listings to be stored in 30 to 50% savings of memory space depending on the actual text data involved. Another mode selects white or black characters. Control characters can be inverted or blanked – great for storing "invisible" information on screen for some games. Carriage returns are displayed as boxes or blanks and the cursor winks or remains steady. The dense graphics mode enables 2 K words of memory to be displayed as 160 dots horizontally by 100 dots vertically, or if memory is in short supply, 1 K bytes can be used to display as 80 dots horizontally by 100 dots vertically until your next birthday.

What is missing when you purchase a main frame computer from the catalogues of MITS Inc or IMS Associates? Asking that question has recently started several companies purveying products to the small systems market. The identification of gaps in a product line, then independently filling these gaps is a highly respected tradition in the computer field, a tradition which has hardly changed as the market widens through microcomputer technology. An example of a creative and innovative product idea which augments and enhances an existing computer product line is provided by the new MERLIN board manufactured by MiniTerm Associates, Bedford MA. The following article is edited from materials supplied by MiniTerm.
The POLY 88 Microcomputer System

The POLY 88 Microcomputer System brings to the user, in one compact package, the capability of developing programs and hardware as well as enjoying the interaction with computers. The POLY 88 System uses a video monitor for display, a keyboard for input, and cassette tape for storage. The system will connect to a hard-copy terminal. POLY 88 hardware consists of CPU circuit card with onboard memory and I/O, video display circuit card with keyboard input port and graphics capability, and mini-cards that connect to the CPU board via ribbon cable for cassette or serial interface.

Central Processor Card features 512 bytes of RAM (random access memory), plus sockets for up to 3K of 2708-type PROM or ROM (read only memory), vectored interrupt, and real time clock, as well as an optional serial input-output port featuring software-controlled baud rate.

The Video Terminal Interface circuit card will generate 16 lines of 32 or 64 characters or 48 x 128 graphics grid on a standard video monitor or slightly modified TV set. It also includes an 8 bit parallel keyboard input port, allowing the board to function as the complete computer interface. The POLY 88 Chassis and backplane/motherboard is Altair compatible, and will provide 6 amps of power to five cards. Only two switches are mounted on the front panel—a lighted on/off switch, and a push-button, which, in addition to resetting the system, indicates a halt condition in the processor.

The firmware Monitor is integral to the POLY 88 System. This 1024 byte program in ROM allows the user to display data on a TV screen, enter data into memory using a keyboard, read and dump data to the cassette interface in a standard format, and single step through a program while displaying the contents of each of the 8080’s internal registers.

The monitor provides many of the standard driving routines to greatly simplify the job of programming. The monitor forms the basis of an ever-increasing software library available to POLY 88 owners.

Options from PolyMorphic Systems include a board with 8K of additional RAM, a versatile prototyping board (“The Ideaboard”), and an Analog Interface. Also, many “Altair-compatible” products on the market are compatible with this system. Prices: Basic kit including chassis, CPU and video cards — $595, $795 assembled. Cassette option — $90 kit and $125 assembled. 8K of RAM — $300 in kit form or $385 assembled. We also sell the video and other “Altair-compatible” circuit cards separately.

Dealers: This system sells itself. All prices and specifications subject to change without notice. Prices are USA only. California residents add 6% sales tax.

Prepaid orders shipped postpaid. BankAmericard and Master Charge accepted.  

- [ ] Please send more information  
- [ ] Order and check enclosed  

Name ____________________________
Address ____________________________
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BankAmericard ______________ Expires ______________
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Signature ____________________________

PolyMorphic Systems (805) 967-2351  
737 South Kellogg Avenue Goleta, CA 93017
If you are worried about loading all those great bytes into your machine with toggle switches, don’t. MERLIN provides a parallel input port to which most keyboards may be directly tied and sufficient regulated power to run them. MERLIN also has a serial input port which may be used for binary data from tape signal conditioners, switches, thermocouples or other arcane hobbit paraphernalia. The serial output port is also uncommitted, and the pair can be used to implement a cassette IO interface.

Best of all, you need not be a software genius to use MERLIN. Monitor and Editor functions as well as general purpose subroutines, selectable IO drivers and keyboard and display drivers are also stored in MERLIN’s optional on-board MBI ROM. (If you are a software genius and have a programmer you can substitute up to 2 K of your own 2708 EROM or 1 K of 2704 EROM.) Provided with the MBI ROM are also 128 words of scratchpad programmable memory to hold MERLIN’s vital statistics and Monitor stack. Linkage through this scratchpad to user defined routines creates a system which can be expanded virtually without bound. (As though the ten user defined keystroke executed functions built into the monitor weren’t enough!)

Monitor functions provided by the MBI ROM include the ability to fill any portion of memory with a given hexadecimal value, the ability to sequentially modify memory contents, and hexadecimal dumps to the display. Processor registers may also be examined or modified. ASCII text may be input to memory, blocks of memory may be copied, the beginning and end of the display area and display format may be set, and user programs may be executed with up to three breakpoints. The breakpoints enable the user to return control to the Monitor after executing only part of his code. Once in the Monitor the user may examine or modify memory or registers before executing more of his program.

The Editor functions can be invoked by keystrokes or called from user programs. The functions include:

- Control of cursor movement (up, down, right, left, home, two tab sets, and tab).
- Either characters or lines may be inserted, deleted, or replaced.
- Scrolling can be automatic at any line number or under manual or program control. Scrolling may be page up or page down or absolute.
- Automatic scrolling can provide wrap-around at the end of the defined display area (up to 64 K), so that using the “clear display after cursor position” and “copy block” functions provides an easily implemented “infinite” display area.
- Finally, this ROM contains direct linkage to a second optional 2 K ROM and forthcoming cassette-modem interface ROM. MERLIN’s second ROM contains extended Monitor/Editor functions plus general purpose graphics control subroutines.

A soon to be announced optional board for MERLIN will increase capabilities to include color graphics, and with 320 horizontal by 200 vertical resolution for black and white graphics. Miniterm Associates is located at Box 268, Bedford MA 01730.
The Data Domain

We are proud to announce we are now dealers for the Digital Group.

Processor Tech IMS Cromemco CSC Vector OSI

111 S. College Av
Bloomington, Ind. 47401
Phone (812) 334-3607

Continued from page 16

run APL, SNOBOL, LISP, PASCAL, ALGOL, TRACT™ etc), and with the falling prices of memory, will do exactly that. I know several personal computer hackers who have pretty nearly filled up a 64 K memory address space. If a person has a choice between a system that costs $1000 with 16 K of memory and the same system with 32 K at an incremental cost consistent with the new 16 K chips’ estimated costs, the extra $300 to $500 at the store may be well worth it; and as the technologies improve, more and more memory will be potentially possible for the same dollars.

And there lies the problem. With memory getting cheaper and cheaper, we are running out of address space in the 8 bit LSI processor! The typical 8 bit or 16 bit LSI processor addresses 65,536 bytes and that’s all. For many purposes, such as creating data base structures with large buffered data areas internally, it would be extremely convenient to have much larger main memory areas. For instance, in a super text editing system allowing 50 K bytes for buffer areas limits one to about 18 standard manuscript pages in memory at any given time (assuming no paging to expensive electromechanical magnetic media). With memory becoming a very cheap commodity, one would like to have as much of it as possible on line for such applications. Similarly, in setting up information management systems for the home user, the more memory the better, since the resource can be used both to speed up computation by using table concepts, and to minimize IO.

Given this desire for lots of memory, and the limitations of 16 bits, the search for alternatives is bound to occur. One place that this can come out is in newer LSI processor designs. For example, consider the Motorola 6800 as it is presently implemented. It resides in a 40 pin package, but the simplicity of its interfacing requirements leaves two pins unused at present. In a hypothetical “improved” version, the design could be modified to support 18 bits of addressing, or a maximum of 256 K bytes (262,144 bytes) with some changes in the internal architecture. The simplest internal change would be to use the uncommitted bits of the status register (bits 7 and 6) as “bank selection” bits to implement extended external memory by the traditional “bank switching” trick. Of course, it’s hardly likely that this design change will happen, so the extension to memory sizes above the address range of the machines will have to be accomplished by the individuals designing the computer products which employ LSI central processors.

Bank switching kluges can be done externally to a processor as well. In a personal computing system with ROM software of compilers or interpreters, one way would be to partition a 32 K segment of address space into two 16 K regions along the boundaries of the 16 K chips, with bank switching used to alternate such extended regions of memory. Again, in a hypothetical case, consider a 4 bit mapping vector for each 16 K half of this region of addressing. The 4 bit bank selection could point to 16 banks of 16 K bytes or 256 K bytes, with the core of 32 K bytes retained for system monitor and IO functions. But these are just conjectures of ways to accomplish the extension of mem-

Articles Policy

BYTE is continually seeking contributions from individuals who are applying personal systems, or who have knowledge which will prove useful to our readers. Manuscripts should have double spaced typeset written texts with wide margins. Numbering sequences should be maintained separately for figures, tables, photos and listings. Figures and tables should be provided on separate sheets of paper. Photos of technical subjects should be taken with uniform lighting, sharp focus and should be supplied in the form of clear glossy black and white or color prints (if you do not have access to quality photography, items to be photographed can be shipped to us in many cases). Computer listings should be supplied using the darkest ribbons possible on new (not recycled) blank white computer forms or bond paper. Where possible, we would like authors to supply a short statement about their background and experience.

Articles which are accepted are typically acknowledged with a binder check 4 to 8 weeks after receipt. Honorariums for articles are based upon the technical quality and suitability for BYTE’s readership and are typically $25 to $50 per typeset magazine page. We recommend that authors record their name and address information redundantly on materials submitted, and that a return envelope with postage be supplied in the event the article is not accepted.

65
Authors take note: A tutorial on the architecture of stack machines, the reasons for using such machines, and what it is like to program such a machine would be excellent article material for BYTE magazine.

Enter the Stack Machine

The real reason we need to use more memory than 64 K is our need to use high level language to program sophisticated information constructs. Traditional LSI processor designs to date have merely been adapted versions of widely used designs to the constraints of LSI technologies. A 6800 is simply an 8 bit approximation of what minicomputers have always been, and minicomputers are just miniature versions of the earlier, larger machines. Sure, improvements in architecture have been made, such as use of subroutine linkage stacks with built-in pointers, but all the present LSI processors are cut of the same mold. If we are running out of room in address space with the present designs because of a need to run high level programming languages and intricate information systems written in these languages, why not use the need for larger address space as a superficial spur for a high level language oriented general purpose processor itself?

There is a whole technology of machines oriented towards high level languages, a technology principally seen in the commercial products of the Burroughs Corporation and experimentally in computer science and software engineering contexts. This is the technology of the high level language machine, or stack machine. This is a processor designed to have a machine language which is very close to a high level language consistent with structured programming concepts. This is the world of the computer whose instruction set includes control structures like the IF instruction, the THENDO instruction, the ENDELSEDO instruction, the ENDEF instruction, and data constructs appropriate for a high level language. The grapevine currently jingles with rumors that such a machine will soon be on the market, possibly labelled “Z90”, and I know of at least one university laboratory version intended for reduction into LSI masks. High level languages are what make general purpose computers useful to the largest number of people, so eventually I expect to see stack machines in LSI form, intended for general purpose computers.

Use of stack machines sure won’t cure the address space saturation problem, but if one has to add some extra bits to the memory address bus, why not include a real improvement in the processor architecture at the same time as the new design is created?

Publisher’s Notes

Personal Computing 76 in Atlantic City:

Something for Everyone

by Virginia Peschke

Personal computing enthusiasts were treated to a huge, successful convention in Atlantic City on August 28 and 29. BYTE will have a complete pictorial report next month, but briefly: More than 80 manufacturers and suppliers had booths to display their latest products and exchange ideas with users; dozens of technical talks and several seminars provided information on every phase of personal computing; and a huge supply of valuable door prizes was distributed to many lucky attendees.

The speakers at the Saturday night banquet were all greatly entertaining. As a grand finale, John Whitney showed his technically amazing and esthetically beautiful movies of animated computer graphics with musical accompaniment. Though everyone had had a full and exhausting day, John’s movies held us all spellbound until almost one in the morning, and various persons inspired by the show were engaged in conversation until much later.

For those of us who aren’t true computer hackers (I’m a jade carving nut myself) the choice of Atlantic City as a site was indeed fortuitous. Though it’s somewhat difficult to get to from some parts of the country, once there the computer hacker is relieved of the usual domestic problem; that is, how to keep the family entertained. Atlantic City offered so much for the people who didn’t wish to spend much time at the show that the computer buff was unlikely to hear “We’ve been here an hour, when can we go?” First, there was the superb sand beach with a warm, gently rolling ocean, the amusement park, the boardwalk train, and the great selection of restaurants and shops. Where else could one find, within several blocks of each other, dealers in crystal paperweights, archaic Chinese jade, oriental rugs, Spanish lace, magic tricks, health foods, and many other things too numerous to list? No, families were not bored and hackers were free to spend all the time they wanted exchanging information.
**What's New?**

**Space Voyage**

The most complete space simulation game ever offered to micro users. Your mission is to rid the galaxy of the enemy using your warp engines, phasers, photon torpedoes, short and long range scanners, warp drive, shield, warp power, and damage control. Beware of enemy attacks, supernovas, space storms, and other disturbances. To duplicate this game on BASIC would require a lot of work, but your 6800 needs only 4K to run this exciting program.

$10.00

**Floating Point Package**

Using this package you can do arithmetic operations with a significant digit length and an exponent range of at least $-99 + 99$. ADD, SUBTRACT, multiply, and divide are implemented in 32 bits. We include free I/O driver program.

$5.00

**Scientific Package**

All the scientific functions you need: SIN, COS, TAN, ARCSIN, ARCCOS, ARCtan, exponential, LOGX, LOG2X, hyperbolic, and more. Must be used with the Floating Point Package above (not included).

$10.00

**Micro Basic Plus**

PRINT, INPUT, READ, DATA, RES, Dosomes, GOSUB, ON, GOSUB, ON, GOSUB, ON, LET, LET, IF, FOR, NEXT, REM, END, and 2 DIM arrays. RUN, LIST, SCR, EXT, ON, END, TAB, SPC, ABS, SGN, EOP, multiple statements per line, simple load and dump. A 4K system leaves room for programs (50 lines).

$3.95

**Program of the Month Club**

For $2 you get a one year membership and receive monthly bulletins describing our newest programs. Up to 12 programs are included each year. Membership is a great way to keep up with new programs and applications. You get our Random Number Generator free if you join now.

$2.00

**Cassettes**

Several programs are now available on "Kansas City" standard, HiROM formatted audio cassettes. No instructions or listing included, must be purchased separately. CT-1: Space Voyage $8.95, CT-2: Klingon Capture $6.95, CT-3: Handmade $4.75, CT-4: Mastermind and Switch $6.95, listings $3.95 each.

**INFORMATION**

Our source listings contain comments throughout, label table, hex code dump, complete instructions, and sample output. External references (to HiROM routines) are easily modified. When ordering add $1 postage and handling under $10, $2 for first class mail, 4% sales tax (ind., residents). Personal checks will clear bank. Many other programs, for Information send SASE.

---

**Terminal Systems Division - Dayton**

We have a number of new and challenging opportunities involved with the hardware/software design and development of real-time financial terminals. Immediate needs are at all levels in the following areas:

**Programmer/Systems Analysts**

These positions require knowledge in the areas of microprocessors and minicomputers based on real-time operating systems. Responsibilities will be to participate in the design of software development and write test software for mini and micro based real-time operating systems in a distributive network.

An opportunity also exists for participation in the architectural design of an Automated Health Care System.

Candidates should have a BS/MS degree in Computer Science or Math and at least 3 years programming experience. Experience with assembly and COBOL languages is necessary.

**Software System Design**

These positions require the ability to provide technical expertise and leadership in the area of real-time terminal control and batch operating systems. Responsibilities will be to translate and interpret the state-of-the-art in operating systems to an assigned terminal control project and to select, influence and affect broad technical directions in software. Will be responsible for coordinating complex distributed processing operating system software development which will support applications coded in high level languages and run in both microcomputer and minicomputer mode environments.

Candidates should have an MS degree in Computer Science, Systems Engineering, or Math, and 7 to 10 years programming experience with at least 5 years in operating system design and development.

These positions are at NCR's Terminal Systems Division in Dayton, Ohio. If you qualify and are interested in these opportunities, submit your resume and salary requirements to: Robert L. Opalek, Manager Employment Department Terminal Systems Division-Dayton NCR Corporation Dayton, Ohio 45479

An Equal Opportunity Employer
A CASE OF Duplicity?

Finally arriving home from work after another hard day, seeing my August issue of BYTE in the mailbox immediately calmed my nerves. I settled into my semi-automatic reading chair, placed my copy in the scanner, punched up a beer and sausage combo on the console and prepared to better myself. Greedily I began. Not waiting to flounder about, I immediately flipped to "In This BYTE." The highlights leaped at me. Another fantastic array of information! (Up to this point, I had read every issue of BYTE cover to cover and this one promised to maintain the trend.)

I read to the blurb about the Zilog Z80 and no farther. Expecting to find information to delight and astound me, I started flipping toward the article. One page farther and the ad for the "super chip" whet my appetite and set me flipping furiously. My expectations only rose as I skimmed for page 34 and the "Microprocessor Update: Zilog Z80," Page 25. (Just nine more.) Flip. Flip. Page 32. Flip. Page 30!!! Flip back, Page 32. Flip. Page 30???

I tore my BYTE from the scanner, and manually searched for page 34, but nowhere could I find it. It seems my copy jumps from page 32 to 49, and again from page 80 to 97. The fact that there were doubles of pages 17-32 and 97-112 didn't seem to make up for my loss.

I fell back, dejected, just as my chair served me my beer. But the force of me collapsing backward thrust my beer into the vibrating unit which promptly shorted out, flinging me headlong across the room.

I am now in traction in the county hospital. I am also very dejected because now I have all this time and still can't read about the Z80. Could you find it somewhere in your heart to fill this emptiness.

Deplorably yours

W R MacLeod
GTE Automatic Electric Labs
4501 W North Av
Melrose Park IL 60160

Mr MacLeod received the following reply:

Dear Mr MacLeod

Enclosed you will find a complete August issue of BYTE. We hope you enjoy reading the article "Microprocessor Update: Zilog Z80," during your stay in the county hospital. If it appears to be an extended stay, please let us know if we may forward the September and October issues to you.

The staff at BYTE wishes you a quick recovery.

[Please add any necessary correction or replacement information here.]

COMPUTER PHREQUENCY

BYTE No. 13 (September 76), page 12, letter from Melvon G Hart, W0IBZ, "Attention Hams!..." Try 3.865 MHz (LSB) on Thursdays at 2300 GMT. You will find several computer-phreque/amateurs there.

Carl K Zettner, WSHFG
108 Moss Dr
San Antonio TX 78213

HUMANE COMPUTING?

I am working on a survey of the humanistic use of computers and would like to get in touch with other people who are interested in this field. I want to learn about what can, and is, being done to make the use of computers as humanized as possible. More specifically, I want to know:

- What are the potentially humane applications of computers?
- What are the important ingredients in humanized computer systems?
- What is currently being done in the field of humane computing, both in terms of theory and practice?
- Which individuals and groups are actively doing this work?
- What are their particular goals and objectives?
- What are the results so far?
- What are the major factors determining their successes and failures?

I would like to hear from anyone who can contribute to answering such questions. They should write to me describing their thoughts, fantasies, plans and experiences related to the humane use of computers. Besides corresponding with people, I hope to actually visit and talk to as many contacts as possible. All the material I collect in this way will go towards the publication of a survey of humane computing.

Andrew Clement
789 W 18th Av
Vancouver BC Canada V5Z 1W1

Humanistic needs some precision in definition, but it will be interesting to see what you find. Readers interested in working with Andrew are urged to correspond.

MORE COMMENTS ON COMPUTER TYRANTS

I am a student at San Bernardino Valley College and am majoring in computer engineering. Recently, I was leafing through some back issues of BYTE that had been given to me by a friend. I came across an article in the February 1976 issue by Ed Rush entitled "Could a Computer Take Over?" [page 76].

In his article, Mr Rush points out all the speculation that various science fiction writers of today had written into their stories about the probabilities of a computer taking over some or all of future society. He suggested that all those who have any knowledge of the operation of an information processing system would be the first to confess this point. Not true.

I have only been working with computers for two years, but I have also been an avid science fiction fan. The idea of the computer as a world dictator makes me think of the naivete of modern society. Those who do not want society to progress to an easier more controlled future have set the computer up on a pedestal as the ultimate enemy. Science fiction writers have taken this concern and have written upon it.

The true enemy is not the computer. The same people who tend to put down the computer are precisely the same people who

Letters

ZEROING IN

I think the point has again been missed in the great 8080/6800 controversy. Reader Cochran (August 1976) compares the IO structure for what seems to me the millionth time. Really now, what would it take to convert one bus to the other? A couple of AND gates maybe. And who cares if the 6800 has a few less memory locations out of 65536?

The major difference is the purpose behind the two instruction sets. While the 8080 is superior at handling structured data, the 6800 is better at arithmetic. The former has an overloaded accumulator while the latter has an overloaded index register.

The single accumulator of the 8080 requires many transfers to temporary storage. This is most frustrating when doing calculations that involve intermediate results. Unfortunately, the arbitrary nature of the instruction set makes improvement difficult. Zilog's Z-80 is a slight improvement, but only compounds the inconsistencies already present.

The 6800's major fault is its lack of index register capability. However, improvement by adding instructions is easy. There should be an instruction to push the index register onto the stack and one to pop it off. An instruction to compute a 16 bit address by adding the accumulators to the index register is essential for reentrant programming.

Both the 6800 and the 8080 need improvement. Because the 6800 has a cleaner architecture, it has greater potential. So when Motorola comes out with a replacement chip, I'll be first in line. [Not if I get there first. . . . CH]

Stephen Ma
Glenn Fawcett
5170 James Walk
Vancouver BC Canada V5W 2K4

Grapevine, Austin TX, has it that the new MC6809 product [the Motorola answer to Z-80] will have: Two 16 bit true index registers, block move, block search, and perhaps even some 16 bit arithmetic to enhance pointer manipulations and address calculations at run time.
can appreciate its power. They are not afraid of the computer itself, but are afraid of those who control the computer.

The computer operators and programmers of the future will control the world, IF world power goes to the computer.

Richard G Castle
21951 Vivienda Av
Colton CA 92324

The neat thing, though, is so many different makes and models of computers doing most of the computing for individuals! Try to make that situation into a tyranny.

SUPER STAR TREK: TREK76

BYTE is fantastic and I'm now in the process of scouring up enough money for a subscription. In your January 1976 issue there was a letter from Richard Wexler and he wanted info on STAR TREK programs. I have almost all the bugs out of an advanced game called TREK76 which should be just what he wants.

TREK76 is written in standard FORT-RAN so it should run anywhere. Commands are entered in English sentences and the game is semi-real time; the Klingons attack and have the same armament as the Federation. Once all the bugs are out of it (hopefully over the next few months) TREK76 will be one of the best STAR TREK games around. Anyone interested should contact me (school address is: Box 5739, University of Rochester, Rochester NY 14627 from September to May).

I'm a game freak so anyone with games to exchange just let me know. Also, I'm looking for a listing of a BASIC game called TREK73.

Dave Warker

SOME THOUGHTS ON "IGNORANCE IS BLISS"

The "Ignorance Is Bliss" television drive circuit (July 1976 BYTE, page 38) looks like a simple answer to a common need.

However, be sure to check whether the television circuitry is isolated from the power line. If not, use an isolation transformer for the television at any time that it is connected to the terminal. Otherwise, plugging in the television the wrong way will put 115 volts AC across the electrolytics if the logic supply is properly grounded, and will put 115 volts AC on the logic ground if it isn't connected to an external ground.

Also be sure that your television antenna has a good lightning arrester to take care of the voltage surges caused by nearby lightning strikes. This is especially important because the electrolytics cannot withstand as much voltage as the small, high voltage capacitors you could use with an RF modulator.

After you make certain that you are ready to use the terminal safely, you might consider that electrolytics aren't known for especially good high frequency characteristics. If you get a horizontal smear in the display, put a small (0.01 μF or so) bypass capacitor in parallel with each electrolytic.

Robert F Miles
242 Abingdon Rd
Lenoir NC 28645

Thanks for shipping away at "ignorance."

NEEDED: BENCHMARK COMPARISONS

One question which I have had for a long time concerning microcomputers is throughput. I have been using a PDP-8/E now for quite a while. Many of my programs (such as LIFE) were limited by speed. It seems to me that the 8 is considerably faster than many micros; but there are other things which I cannot adequately compare. For instance, there seems to be a lot more ways to address memory in a 8080 (or Z-80). How do these chips compare, in "benchmark" programs, to the minis?

How fast can the BASIC software for the 8080 count in a loop, such as =1 to 20000? The PDPS/E, under the TSS timesharing system, managed it in about 20 to 40 seconds. Another computer I have used, the HARRIS Slash Four, did =1 to 10000 in

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MIKOS
419 Portofino Dr.
San Carlos, Calif. 94070

Check or money order only. Calif. residents 6% tax. All orders postpaid in US. All devices tested prior to sale. Money back 30 day Guarantee. $10 min. order. Prices subject to change without notice.
about 15 seconds. At the same time it was supporting other users.

Simply counting makes for lousy benchmark programs, though. I would appreciate an article on the subject.

James Wiebe
208 N Jefferson
Hillsboro KS 67063

The benchmark slot has not been adequately filled with articles in BYTE, as James' letter points out. Authors take note: A general background article on the theory and validity of benchmarking, applied to microprocessor technologies, would be most useful to readers in evaluating processors.

DOCUMENTATION NEEDED

I am searching for a company that was at one time located in Derry, New Hampshire. The name of the company was/is Data Input Devices Inc.

They built a TV typewriter terminal unit that my friend ($800 Altair owner) bought at a hamfest.

We are hoping to get schematics from either the company (if it still exists) or from a prime consumer of the unit if we can find that out.

Any leads will be much appreciated.

Tom McMurtrey
WA4FYN
244 Roosevelt Av
Florence AL 35630

Can any readers help here?

A QUESTION OF COMPATIBILITY

Is it possible to successfully use the Altair 16 K static RAM (215 ns) in the IMSAI 8080 in lieu of the IMSAI 4 K RAM and still obtain the a) low power, b) memory (1 K blocks) write protect, c) power fail memory save benefits?

How about the MKRA-D 16 K RAM in the IMSAI 8080?

I am seeking workable solutions to configuring a 64 K processing without using up (16 of 22) all the available slots while still getting the advantages offered by the processor manufactures on their smaller memory boards.

A B Clark
15425 SW 88th Av
Miami FL 33157

Has anyone in the BYTE readership tried this particular combination of modules? We have no data with which to give an answer to this question.

NEED AN ACCURATE HP-45 TIMER?

I have long been interested in the timing capabilities of the HP-45 and have watched for information on it. Last month EDN published how to add the crystal to make an accurate timesbase, and said that HP was selling crystals for $14 plus $1 for shipping. Upon contacting HP I found they have them, but you have to know where to look. After some research and a few long distance phone calls I was able to make some arrangements to obtain a supply of crystals from the manufacturer. I would like to make these available to interested BYTE readers for $12 plus $1 shipping.

Enclosed is the article from EDN and also an explanation I received that differs slightly on how to install the crystal. This may be because of the two different versions of HP-45s. I have hooked one up for someone using the HP sheet and it works fine. The other way may work as well. I shall try it soon.

Mark S Egbert
1514 S 320 E
Orem UT 84057

PHOBIA

One of my pet phobias is people who short out capacitators. In BYTE #12, page 96, figure 1, the keyboard switches directly short out the 1 μF capacitor and this is, no doubt, the cause for the "oil film" referred to in the last paragraph on page 97. Just imagine the surge current that flows when a switch is closed. This is not good for the capacitor and is positively damaging to the switch.

Webb Simmons
1359 Alcala Pl
San Diego CA 92111

Well, maybe. A capacitor of 1 μF, charged to 5 volts, holds Q=C*V = 5*10^-6 coulombs of charge. If the contact closure produces a spark, which can be detected on an AM radio, then it is a safe bet to say that the contact event takes place in from 10 to 100 microseconds (in order for significant harmonics to be detected in the 500 KC to 1500 KC AM radio band). Thus 5 microcoulombs are being discharged at an average rate of 0.5 amperes in the 10 microsecond case, 50 milliamperes in the 100 microsecond case. Peak values might be considerably higher, possibly pitting the contacts. This off the cuff analysis does not take into account the effect of the resistance in wires and capacitators, and is conditional on these contact conditions being able to generate measurable RF from a sparking contact.

KUDOS, GRAPHICS, STATE OF THE ART

This letter of mine is in response to several items in your July letters column [pages 90-94]:

1. I would also recommend James Electronics (IGs). Delivery is usually less than a week.
2. With regard to the graphics display circuits:
a. For the circuit you asked for I would recommend that consideration be given to making it 256 X 512, allowing it to simulate a standard 16 X 64 character terminal or display module.
b. Any such circuit would not be inexpensive. It is not clear to me whether you are asking for a plug-in module, or a stand alone device to communicate through an IO port. Mr Hyde definitely wants a stand alone device. I doubt that a module would be noticeably cheaper than buying a Cromemco Dazzler (TM). The savings due to giving up color would be easily offset by the additional addressing, and they can get quantity discounts that the individual hobbyist cannot.

A stand alone device would cost more yet: The electronics would be more complex, possibly justifying a dedicated microprocessor, and even worse, you then need a power supply, cables, a box and all the other things which so rapidly run up the cost of a good looking (and reliable) homebrew project.

3. I am afraid that the hobbyist is never going to get noticeable quantities of true state of the art items. Announcements in magazines such as Electronics are at least six months (if everything goes well, which it usually doesn't) ahead of volume deliveries. After that, there is at least another six-month wait to design an item into a hobbyist kit, and get that into production. The probability approaches 1 that one of these steps will meet an unforeseeable "dead end.

Finally, the cost of truly new items (4 K RAMs, not cheaper floppy's) is far more than the hobbyist can afford. 1 K RAMs cost a darn sight more in thousand quantity five years ago than we are currently paying for one. I worked with 93410a (256 bits, 50 nsec) when they were $20 apiece in hundreds, and they're now $1.95 in onesies. As this happens to 4 K's we'll start seeing them.

Anyway, congratulations on a worthwhile and continually improving magazine.

Frank Richards
414 Bradford Way
Norristown PA 19401

AUTHORS, TAKE NOTE

Ever since BYTE #1, I've been waiting for more conceptual articles like "Write Your Own Assembler." How about some more articles on . . .

• Random number generators, and the testing and demonstration of randomness in various random number generation schemes.
• Executive software structures, what kinds exist, advantages and disadvantages of various methods, etc.
• Human engineering factors and pointers concerning computer peripheral placement, panel and console design, etc.

James F Gentry

NEEDED: USED COMPUTER INFO

I am a charter subscriber to BYTE. I have enjoyed every issue from #1 to date. Your publication has expanded greatly my knowledge of software. Mostly I have learned that I have much to learn.

Like everyone who has been bitten by the computer bug, I wanted very much to have a system to play with. I had almost decided to embark on the purchase and assembly of either a 6800, or an 8080 system kit (with faint echoes and moans from the wife), when I chanced upon the purchase of a full blown 16 bit computer through a local government surplus outlet. The only problem with this was that some of the interconnect cables
were missing and there was NO INFORMATION.

The unit I have is a DATA 620 system, housed in two 19 inch wide, 6 foot tall racks. It consists of a CPU, two power supplies, a bootstrap loader panel, tape I/O and reader (used to load the program, I believe), a general purpose I/O (purpose unknown), and two core memory units (organized as 2048 words of 16 bits each unit, 4 K total CORE).

This unit was in use at the Manned Spacecraft Center in Houston (use unknown). I believe it was in use circa 1961. It was probably built around that time because it uses all discrete logic, no integrated circuits. It uses -10 volt load source, +6 volt logic bias. The machine was made by a company called Data Machines Inc, Newport Beach CA. This company is/was a subsidiary of a company called Decision Controls Inc (address unknown). As you can see I have more questions than data. Although a chance investment, I thought it a good buy.

It is my deep hope that you or one of your readers might be able to supply me with some information. I have written to Newport Beach c/o the postmaster, but no such company is in existence out there, and no forwarding address. Any help you can give me in this matter would be greatly appreciated.

Godfrey C Leggett
185 Marceline
Beaumont TX 77707

We publish this letter in the hope that some reader will provide information helpful to Mr Leggett in his pursuit of a personal system.

VA COMPUTERS NEEDED

I have recently become aware of the world of personal computing and am anxious to become part of it. Like many others, however, I am not prepared to lay out the money for a microprocessor, I/O device, memory, permanent storage capability, etc. If there were microcomputer kits, as there are television kits, which were part of a Veterans Administration approved correspondence course, the door would be open for thousands more. Could you put me in touch with anyone having such a course or spread the word to the microcomputer kit industry about this seemingly untapped, eager pool of potential customers? Thanx.

Steve Packard
44 S Greenfield Av
Hampton, VA 23666

IBM SELECTRIC 10

The letter from Dr James Lang in the August BYTE on the desirability of using the IBM typewriter for a console device hit close to home — after I design the interface for this Selectric 735 I’m typing on, that’s what I will have. Please note — this isn’t just any old Selectric, but the one with all the solenoids and switches already under it. These machines are now available on the
The first complete small computer.

As you thumb through this magazine, you'll see a lot of ads for small computers. For $600 you can find a pretty good box with a power supply, four slot motherboard, CPU module, and all the expected lights and switches.

But you know what? It won't work. That's because in order to make the computer go you have to buy memory—normally both read-write (RAM) and read-only (PROM), interfaces to the outside world (parallel, serial, and cassette), keyboard, video display module, and software.

Add this all up and it's going to cost you at least $1,400 for a complete system. Got the picture?

Now listen to this. The remarkable new Sol-20 Terminal Computer will give you all of the above...plus more!...as standard equipment for just $995, in kit form. This is because the Sol-20—like no other small computer—was designed from the ground up to be complete.

Here's what the Sol-20 includes as standard equipment:
- 8080 microprocessor.
- Video display circuitry.
- 1024 words of static, low-power RAM.
- 512 words of preprogrammed PROM.
- Custom 85-key solid-state keyboard.
- Audio cassette tape interface.
- Both parallel and serial interfaces and connectors.
- Power supply.
- A beautiful case with solid walnut sides.
- Software that includes a preprogrammed PROM personality module and a cassette with BASIC-5 language plus two sophisticated computer video games.
- Full expansion capability with all S-100 bus (Altair/IMSAI/PTC bus) products.

It's a handsome terminal or computer that will even look good in your living room or office. Small systems start at just $475.

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The Sol-20 expandable system.
Processor Technology

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Now available from the following dealers

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- The Byte Shop
  1514 University Ave.
  Berkeley, CA 94703
- The Byte Shop
  2559 South Bascom Ave.
  Campbell, CA 95008
- The Byte Shop
  2227 El Camino Real
  Palo Alto, CA 94306
- The Byte Shop
  509 Francisco Blvd.
  San Rafael, CA 94901
- The Byte Shop
  2989 North Main St.
  Walnut Creek, CA 94596
- The Computer Store of San Francisco
  1093 Mission Street
  San Francisco, CA

**Florida**
- Microcomputer Systems Inc.
  144 So. Dale Mabry Hy.
  Tampa, FL 33609

**Illinois**
- The Chicago Computer Store
  517 Talcott Road
  Park Ridge, IL 60068
- itty bitty machine co., inc.
  1316 Chicago Ave.
  Evanston, IL 60201

**Indiana**
- The Data Domain
  111 South College Ave.
  Bloomington, IN 47401

**New Jersey**
- Hoboken Computer Works
  56 Second St.
  Hoboken, NJ 07030

**New York**
- Audio Design Electronics
  487 Broadway, Ste. 512
  New York, NY 10013
- The Computer Corner
  200 Hamilton Ave.
  White Plains, NY 10601
- The Computer Mart of Long Island, Inc.
  2072 Front Street
  East Meadow, L.I., NY 11554
- The Computer Mart of New York, Inc.
  314 Fifth Ave.
  New York, NY 10001
- Synchro Sound Enterprises
  193-25 Jamaica Ave.
  Hollis, NY 11423

**Oregon**
- The Real Oregon Computer Co.
  205 West 10th Ave.
  Eugene, OR 97401

**Rhode Island**
- Computer Power, Inc.
  M24 Airport Mall
  1800 Post Road
  Warwick, RI 02886

**Washington**
- The Retail Computer Store
  410 N.E. 72nd
  Seattle, WA 98115

**Wisconsin**
- The Milwaukee Computer Store
  6916 West North Ave.
  Milwaukee, WI 53213

Processor Technology Corp. dealerships are available only to qualified retail computer firms.
used market for prices ranging from $500 to $1000, depending on model and condition. This machine cost $1 K, as it was a new machine bought from one of the used mini houses. I am working on an interface to connect this gadget to my IMSAI 8080.

This interface will be compatible with most 8080 software; that is, the code will be ASCII-7, with port selection and flag bits jumper-selectable. I also intend to make the interface compatible with most, if not all, of the available options for the 735 and 731. (The 731 is the narrow version of the 735, with an 11 inch writing line instead of 13 inches.) I have heard that the 735 has been replaced in the IBM lineup by something else — this may be the reason they are showing up in the used computer shops. Whatever the reason, it’s nice to be able to get good machines at reasonable prices.

Philip M Spray
3006 N E 26th
Amarillo TX 79107

Avoid mechanical kluges — buy one with the actuators built in.

ARTICLES NEEDED: GETTING SENSOR DATA INTO COMPUTERS

I have really enjoyed BYTE, especially articles such as the Suding and Lerseh contributions in the July issue. I wonder if you will be doing some articles on connection to the analog world. This seems to be an important region that has been shortchanged in your publication.

I would like to see transducer data such as thermocouples, thermistors, and RTDs for temperature measurements, strain gage data for stress, pressure, etc; optical and/or magnetic transducers for velocity, etc. I would also be interested in explanations about signal conditioning (bridges, channel amplifiers, zero set and scaling amplifiers), A to D and D to A techniques and methods (such as ramp DAC, successive approxima-
tion, and tracking A to Ds). For a micro, or any other computer, to “feel” what is going on in the physical world, these sensors that collect ignition pulses, temperatures, load pressure data, etc, are very important.

C Southard
2519 Meadowbrook Dr SE
Cedar Rapids IA 52403

TIMMMBBBBERRRR!

Enclosed you will find my check and subscription to BYTE. I’ve only been able to find a few copies in this area and I found each of them very interesting and informative. Having just gotten our Altair 8800 up and running I thought you and your readers might be interested in hearing about its unique application. Presently, we are using an 8800 at this Lumber Mill to monitor our daily production. We have a lumber sorting machine that incorporates CMOS technology in its control system. Through the use of limit switches the machine measures every board as it sorts it coming out of the sawmill. It displays the measurement data on a set of seven segment LEDs built into the control panel. That is where we tapped in our interface, designed for us by Warren
Stardup, a partner-technician with Microcomputer Systems Inc, which is based in Tampa FL.

The interface converts the TTL at the display to serial and relays the data via 20 mA loop back to the office where the computer is located. Currently, we are using a video display with data in memory being dumped on cassette every hour, in case of power failure and loss of memory. A hard copy printer is on order. In the future I plan to scan the logs just before they are cut, compute that versus what comes out at the sorter, thereby giving me a readout of the recovery I get out of each log. Thought this might be of interest to you. Keep up the good work. Your magazine is refreshing!

Tommy Staten
HC Hodges Lumber Co
Panama City FL 32401

THE EMULATION BLUES

I read with interest Don Keek's letter in the August issue of BYTE concerning the emulation of a PDP-8 instruction set on one of the popular microcomputers. As author of several emulation programs for various computers, I feel obliged to comment on my experiences. I have written two emulators for the PDP-8, one implemented on the Control Data 6400, a 60 bit scientific computer, the other on the PDP-8 itself. The self emulation has value in a trace-type diagnostic programs for the machine being emulated. This will be an invaluable aid to diagnostic programs for the machine being emulated. This will be an invaluable aid to

SOME THOUGHTS ON MISCELLANY AND TAPE MODULATIONS

I just finished reading the August issue of BYTE pretty much cover to cover and as usual found it interesting. I wanted to write last month but didn't get around to it and I have a few tid bits (BYTES) of information and complaints to throw out.

One minor bug in BYTE is I wish you could have put the issue date at the bottom of each page. It makes it rather hard to reference some of the older articles that I Xeroxed from a friend's earlier issues.

I thoroughly enjoyed “Jack and the Computer Repair” [July 1976 BYTE, page 46] by Suding [July 1976 BYTE, page 46] is very interesting. The ratio of his two frequencies is 1 to 1.4. Many of us do not have access to counters or oscillators. Crystals and common chips are cheap.

If a 1 KHz crystal oscillator is divided by 32, the result is 31.25 kHz. If this is sent to a divide by 14, and a divide by 10 chain, then the result is 3125 and 2232 Hz. Switch between the two with an inverter driven by the data, gate it into an integrator, and one gets the triangular wave to drive the tape head. This should eliminate stability problems in the two frequencies and should still be within the telephone line frequencies for acoustic couplers for phone transmission. Many of us would like to be able to use cheap cassette recorders if possible. Suding implies that his filters can be tuned over at least one octave, and maybe two. If this is true, R25 and R26 should be reduced in value and padded with resistors.

However, if considerable variation is possible in frequency, and a long period of each tone is put on the tape before the program, say 30 seconds each, and a voltmeter were connected to IC37 pin 7, then the filters could be tuned by volts to the frequencies actually present, and the only requirement on the cassette is that the speed be within plus or minus five percent for the time the program is running.

I regret that I do not have the equipment to try this system, but I am willing to discuss it with anyone.

Cecil H Royce
25 S Marion
Oak Park IL 60302

The point about 3125 Hz being compatible with the phone network may be debatable; would any telephone engineers care to elaborate? There is a standard set of modem frequencies available, in integrated circuits yet.

A point about standards which should be repeated: The way to approach the subject is to document what is being done by manufacturers, with discussions about the virtues (or faults) of the systems. This way, the user (and other manufacturers) are aware of the state of the art as practiced in manufacturable systems. So far, there are two tape interface definitions documented in BYTE for audio use; more will come.

DIVIDE AND CONQUER (INSTABILITY)

"Why Wait?" by Suding [July 1976 BYTE, page 46] is very interesting. The ratio of his two frequencies is 1 to 1.4. Many of us do not have access to counters or oscillators. Crystals and common chips are cheap.

Martin Buchman's Video Disk article and Burt Hashizume's writeup on the Zilog Z80 were also very interesting. The Z80 will most certainly become the most popular micro as soon as the power of the processors magni-

ofude the power of as the 8080 and 6800. I really like the maskable and unmaskable interrupts and arithmetic shifts features of the 6800 and Z80. Does anyone know an easy way to do an arithmetic shift right using the 8080? But Zilog has outdone themselves with the 8089 (a machine language version to the basic instruction) and search instructions. The mode 2 interrupt is also the way I prefer to do vectored interrupts, but there are also two other ways (modes) if you are fussy.

John Baird's comments on the information revolution are beautiful. We all know that BYTE can do what no technical trade journal can do: Convey practical, down to earth, State of the Art, easy to understand ideas. The technical journals have mostly become a place for doctorate fellows to shelter a highly technical snow job just to meet their degree requirements. Deciper and remove the high level math and the guy usually has little information to pass on. BYTE is the source of innovative design ideas (hardware and most certainly software).

I was a little upset at Dr Suding's "Why Wait? Build a Fast Cassette Interface" article in the July issue. His article would lead you to believe that frequency shift keying (FSK) is the only way to fly. Of course any article written by an author writing about a product he is trying to sell is usually a little biased. Dr Suding is correct with his filters and tune up notes. Tweek this ... Tweek that. Sure Manchester employs "harmonically related frequencies," and frequency discrimination techniques just won't hack it. He has one good point: "Imagine reading 300 baud for 15 minutes to discover a noise pulse had destroyed data, requiring re-recording." This problem exists no matter what recording technique is used. The best solution is to use short data records; say 64 bytes (also a good format for listing). Then if your cassette has backspace capability you simply lose one record and try again instead of a complete rewind. Using character, record and file gaps is a worth while consideration for a well managed file system. Try to keep the record size fixed to whatever corresponds to your single line list device, at least the source statements. A file is a collection of records, either a program or subroutine.

Back to FSK versus PSK: First of all Manchester is really phase shift keying (PSK) using square waves instead of sinusoids. Both FSK and PSK require an extra start bit or sync bit equal to a one. Even using the Suding FSK there is no physical way to go from DC (no flux changes at the start of a cassette record) to a 2975 Hz signal, a 0 without first going through 2125 Hz, a 1. Dr Suding needs to review his Fourier transforms if he believes that only 2975 Hz frequencies exist in the FSK waveforms. The PSK (Manchester or similar) method requires the first bit sent to be defined arbitrarily as a 1. From thereon one definition of Manchester may be a zero phase shift meaning the state of the data (ie: a 1) and a 180 degree phase change in the signal means complement the
data state (ie: 10). Another definition is a low to high transition in the center of a bit cell is a 1 and a high to low transition at the center of a bit cell is a 0. In any case the Manchester code consists of two pulse widths: full bit cell and half a bit cell width. A digital demodulator needs then to discriminate a 1/2 bit cell pulse from a 1 bit cell wide pulse. This is usually done with one or more delay elements (one shot or delay line) set at a 3/4 bit cell reference point. The Manchester or similar codes potentially have a faster data rate than FSK.

For example, say the upper recording limit on a cassette was 2 kHz. The Manchester data would be recorded at a 1000 bits per second rate. The two pulse widths of 1 msec (half bit cell) and 2 msec (full bit cell) would be involved. One bit cell only requires 1/2-1 kHz cycle or 1-2 kHz cycle per bit cell. The FSK technique using filters I doubt seriously would be able to respond to a 1-2 kHz cycle pulse. It would certainly require a bunch of 2 kHz cycles (the modulating frequency is obviously not to be less than the carrier). Even if it could detect a 2 kHz signal in 4 cycles, say, then Manchester beats the FSK 4 to 1 in recording density (speed).

Also since there is always at least one flux change per bit cell using Manchester or similar self clocking code, the demodulator can correct for variations in tape speed by adjusting its 3/4 cell reference either using a phase locked loop (PLL) (see “Improved Cassette Interface Circuit” by Hal Mauch, page 8, April 1976 BYTE) or a programmable counter or even a software tracking routine.

A software routine could count the number of elapsed clocks since the last flux change (per bit cell) and use Manchester or similar self clocking code, to be realized what is called a sampled phase locked loop. The only readback hardware need only be a limiter similar to Dr Suding’s.

Several computers currently being marketed have similar self clocking code, the demodulator can correct for variations in tape speed by adjusting its 3/4 cell reference thereby using a phase locked loop (PLL) (see “Improved Cassette Interface Circuit” by Hal Mauch, page 8, April 1976 BYTE) or a programmable counter or even a software tracking routine.

One way around the tape interface problem is the obvious one, a point raised in your letter which we emphasize here: With the proper general purpose signal conditioning hardware to convert AC coupled signals into TTL digital levels and vice versa, nearly any modulation method can be generated and decoded using simple algorithms. Several computers currently being marketed use such generalized hardware backed up by software in PROM monitors. These include the new Apple computer, BABY by STM Systems, etc.

SOFTWARE

People want software. There are about 1,000 computer programs in the public domain. They are available to anyone — including hobbyists — at cost. These programs include all of the common computer languages. They obey the instructions of most terminals.

There is no need to reinvent the wheel — again, and again, and again.

The above programs may be readily translated into 8080, 6800, F-8 6502 microprocessor instructions. There are no restrictions on revising these programs. There are no restrictions on distributing them. They are in the public domain.

Why don’t you do yourself, your customers, your subscribers, and thousands of others a grand favor, and write for information from

 Documents Office
 Kiewit Computation Center
 Dartmouth College
 Hanover NH 03755

Edward L Tottle
 2993 Wyoming
 Baltimore MD 21222

HOW TO WIN AN ELECTION

As a professional software engineer (a fancy term for a programmer), I receive a great many computer related publications each month. I am six months behind in reading Communications of the ACM, two issues behind of Computing Surveys, four back of Computer Design; and I don’t even want to think of how far of Scientific American. But every month, as soon as it appears in the mailbox, BYTE gets read from cover to cover.

In the free market, there is one sure way to show one’s appreciation for a product. Enclosed is my renewal for three more years of BYTE. Keep up the good work.

HOWARD L TURETZKY
HYDRA
1575 Ivanhoe St
Denver CO 80220

PS — This letter was typed on an IBM Selectric 10 writer driven by an Altair 8800, so blame all the typos on the computer.

FLEXWRITER FLEXIBILITY

Dear Sirs,

I SAW A NUMBER OF COMPLAINTS ABOUT THE LACK OF REASONABLE PRICE 10 DEVICES AVAILABLE WHICH WILL PRODUCE HARD COPY. THIS LETTER IS BEING TYPED ON A FRIDEN FLEXWRITER I PURCHASED FOR $200 USED. THERE ARE MANY AVAILABLE FOR LESS, AS YOU CAN SEE IT HAS AN ATTRACTIVE TYPE FACE AN BOTH UPPER AND LOWER CASE, IT HAS A PAPER TAPE PUNCH AND READER, BUT A VERY POOR TYPIST. IT RUNS ABOUT 10 CPS. ALTHOUGH IT IS NOT CONNECTED TO A COMPUTER AT THE PRESENT IT HAS CONNECTIONS FOR DATA INPUT AND OUTPUT. I AM SURE SOMEONE COULD WORK OUT THE PROBLEMS OF CONNECTING IT UP. THE PAPER TAPE IS A SEVEN TRACK TAPE.

Sincerely,

LAWRENCE F. PIERCE
Have you ever gone to a party and been entertained with some party game which the host introduced to impress his guests and salvage an otherwise boring evening? American life is built upon a succession of gimmicks. We feel we have to be entertained to exist and cannot just have a good, dull time. An example is the success of television as the universal babysitter and now all these overly expensive television games.

Excuse my “Holier Than Thou” attitude, but I’m no different than the rest of the population, including having one of those stupid TV games. What I’m trying to lead up to is to introduce a microprocessor driven vector graphics display controller which can be built for $60 or less.

Some history is in order. About eight years ago, I was at MIT for a conference and spent some time touring the campus. In the corner of one room in an otherwise deserted computer center was a large, intensely involved and vociferous crowd. Above the usual crowd noise were heard shouts of “Shoot your phasers now!”,” “Watch out for that meteorite!”, and “He’s in the space warp!”. Because I usually avoid crowds because of something my grandmother once said about the correlation between crowds, fleas, and bubonic plague, I fought off the urge to investigate further. But, after hearing, “His antimatter engines are done — blast him out of the sky!”, and tumultuous applause, my curiosity could take no more. It took about five minutes of pushing and shoving to make it through the 15 deep crowd to get close enough to see what was going on. There were two people sitting in aircraft type chairs holding what appeared to be small control consoles. They and the entire crowd were intently watching a 21
Figure 1: Raster Scan versus Analog Vector Graphics. For a given grid size and a figure covering a particular area (such as 4 by 4 or 8 by 8), the analog vector graphics method will give a better picture, where better is defined as a closer approximation of the figure desired.

a. Drawing a circle with a slant line through it is unrecognizable on a 4 by 4 grid of raster dots, but quite believable when drawn on a 4 by 4 vector graphics grid. A line drawing of the "ideal" circle with slash overlays the approximations for reference.

b. Drawing a circle with a slant line through it is a closer approximation on an 8 by 8 grid of raster splotches, but the 8 by 8 equivalent vector line drawing has a still closer approximation to the desired circle and line. A line drawing of the "ideal" circle with slash overlays the approximations for reference.

c. When it comes to detailed graphics, the vector method is a real winner. Here is a cartoon figure rendered on a 16 by 16 grid in both vector and raster scan dot matrix form. The contrast in effective resolution of the two methods is enhanced by the juxtaposition of the two versions in this overlay. Note that within the same coordinate grid, the vector graphic version is able to represent some limited alphanumerics, impossible to even attempt in the raster graphics version.
inch black and white TV screen upon which there was a scene depicting a star-studded space and two rocket ships. It became obvious very soon that they were playing "Space War," and the only rules were to shoot the other guy out of the sky (Do Unto Others...), while not getting wiped out yourself. There were certain limitations on fuel and armaments which made the game all the more interesting.

I stood and watched this for three hours until I jockeyed myself into position to grab a control console from an exiting player. All right, you guys, let's play Space War! I played for what seemed to be an instant on the time continuum; but it was obviously too long in the crowd's opinion because, when some little kid started pulling one of my socks down and I let go of the control console to retaliate, I was six deep in the crowd again before I regained control. I did eventually get another try, but I was already

a confirmed "Space War" freak. I was determined to have one of my very own that I could play until my heart was content.

The realization of this dream was, of course, to be postponed until just recently. It is now possible for the computer experimenter to put together a system with capabilities rivaling computers costing many times more. The LSI microprocessors which have become increasingly available at modest prices have started a boom in the home computer field with price wars inevitable. The major reason that these small computers have realized so much computer power is that designers have tailored their designs to utilize existing hardware which is available readily. Consider mass storage, for example. Talk to IBM or any "traditional" computer company about mass storage and your discussion will lead to a $30 K tape drive and controller with reams of wonderful tolerances and grandiose specifications. This will provide an unparalleled mass storage capability, but most people would be upset just considering the electric bill. The alternative was, and is, to incorporate the principles that make the "biggies" so good, but make it cheap enough so the average person would not go into cardiac arrest over the price. American ingenuity had the answer. Develop a sophisticated, yet simple modem on a cheap printed circuit board which allows the owner to use his kid's cassette tape recorder to store data. Thus came the invention of the $100 mass storage system.

There is a moral to all this. The initial success of the home computer system can, in large part, be directly attributed to inexpensive peripherals which utilize readily available surplus equipment or home entertainment devices such as tape recorders and televisions. The television typewriter, otherwise called an alphanumeric CRT display, is only $150 because it uses an already existing television.

**Raster Scan Graphics — Summary of Advantages and Disadvantages**

**Advantages**

1. No software refresh — computer can load a display once and continue other duties.
2. Fully digital — does not require any analog conversion or associated "tweaking" of components.
3. Requires no special display tube — uses television monitor.
4. Can be color — by using added storage, color or gray tones can be assigned to each element or group of elements.
5. No limit to total display quantity — since storage is provided for all points it is irrelevant whether they are shaded or not and does not affect display refresh time.
6. Inexpensive — in limited forms, raster scan uses inexpensive televisions or monitors.

**Disadvantages**

1. Not a pure line display — display is a connection of shaded squares and not line segments.
2. Must provide memory for total display — for a 256 by 256 point display, 8 K bytes of memory must be provided even if only one element is being displayed.
3. Must use either an external memory or direct memory access — the composite video signal necessary for raster scan requires a data output rate beyond the capability of the processor itself. Special controllers must be provided to either access standard program memory directly by DMA or scan an external display buffer which can be periodically changed by the processor to correspond to changing displays.
4. May require fast memory access — in DMA using cycle stealing, memories having access speeds of 250 ns or better may be required. (With a dedicated buffer memory or multipORT memories, 2 μs access is typically required.)

**Raster Scan Graphics**

There is an unfortunate lack of sophisticated peripheral devices beyond these few, and applications using these are limited. The Space War game previously mentioned requires a graphics CRT terminal upon which the players and playing field may be displayed. The home raster scan television, such as that borrowed for an alphanumeric CRT, can be used; but the display is overly complicated and will appear as a connection of blocks rather than pure line segments. There are many raster scan graphics systems now on the market but all exhibit this "block" phenomenon, which in the simplest terms is a function of the resolution. A low
resolution display will have a limited number of large blocks and a high resolution display will have a great quantity of small blocks. Making various blocks light or dark is what constitutes a picture. Figure 1 illustrates a circle drawn on a screen with 16 elements (4 by 4) versus one which has 64 (8 by 8) elements. The lower the resolution of the display medium, the less recognizable the display. For true graphics detail necessary in applications such as game boards and players, high resolution on the order of 256 by 256 is required. This leads to another interesting problem: display storage and addressing.

Raster scan graphics is nothing more than a sequential video display of mass memory. The “mass” in mass memory is a function of the resolution. If the display has a total of 64 elements, 8 bytes (8 bits each) of memory are required for storage. If the display were 64 by 64, there would be 4096 picture elements requiring 512 bytes of memory. It is important to remember that the entire 512 bytes is necessary regardless of the picture being displayed. Within this display storage, each bit has to have a unique X and Y address: For a 64 bit display X and Y could each be defined with 3 bits; for a 4096 bit display 6 bit X and Y addresses are necessary.

Most home computers are 8 bit machines and obviously work most efficiently with 8 bit manipulations. Taking full advantage of this and defining 8 bit X and Y display addresses results in a very respectable 256 X by 256 Y display grid containing 65,536 elements. This corresponds to 8 K 8 bit bytes of memory. [See the article by Thomas R Buschbach on page 32 of this issue for an example of such a design.]

Going from the memory to the screen is another problem and requires a special controller to translate the memory into video information. Horizontal scanning rate of a television is 15.75 kHz which is 63 µs. If a horizontal line is to be divided up into 256 elements, each must be scanned and output to the TV one every 250 ns. Even if addressing and output were handled 8 bits at a time, the rate will still be one byte every 2 µs. Very few microprocessors are capable of doing this. There are two methods of acquiring this data. First is to have a dedicated 8 K memory in the graphics controller which is synchronously scanned by the video output generator and asynchronously updated via the output ports of the computer. This method, though easiest from a design perspective, is the most costly due to the extensive memory used only for the graphics controller.

### ANALOG GRAPHICS — ADVANTAGES AND DISADVANTAGES

#### Advantages

1. **Does not require extensive memory** — total memory required is whatever is necessary to store all the beginning and end points of the line segments to be displayed. Blank areas do not require storage.
2. **High resolution and low cost** — a simple controller is designed around low cost DACs and an analog display does not exhibit “staircase effect” on diagonal lines.
3. **Uses available test instrument as display** — an inexpensive oscilloscope or other X,Y display may be used as a display medium.
4. **Does not require fast memory** — any storage medium having a byte access time of approximately 100 µs is adequate. Can use shift registers, delay lines, etc.
5. **Resource conservation** — gives the author some reason to use his 8008 system since he bought an 8080A.

#### Disadvantages

1. **Software refresh** — the processor must periodically rewrite data on the screen to keep it from fading. Refresh rate is a function of processor speed and the total number of line segments in the display.
2. **Uses analog circuitry** — all analog circuitry is subject to drift and to temperature and other external influences. These variations can be minimized through proper design and construction.

The second method which is used most often in the graphics industry is called direct memory access. 8 K of memory is still required for the 64 K element display, but it is attached to the computer. It is directly addressable at all times and not externally located in the graphics controller, so that when the graphics option is not in use, this 8 K is utilized as any other portion of memory. When using the graphics operation this 8 K will contain the bit pattern display of the screen and be shared between the processor and the graphics controller. Direct memory access means just what it says. The DMA controller directly addresses and reads memory when the processor is not doing so. In most microprocessors this sharing can be done either by suspending the processor operation with hardware DMA request and hold logic or by accessing memory on clock cycles when the processor is doing something else. Suspending processor operation is easiest from both a design and component standpoint but least effective when simultaneously running large programs. In a raster scan display, the processor would be shut down and memory read out 30 times a second to correspond to the non-interlaced update of standard television. The only time the processor would be allowed to run.
Therefore about 400 instructions (in an 8080A) could be run every frame. This is somewhat but they become involved. DMA amount of number crunching. Modifications to this method can extend processor time somewhat but they become involved. DMA utilizing "stolen" clock cycles or added wait cycles is the most effective technique since it does not significantly reduce processor calculation speed. Not all microprocessors are capable of doing this, though; and many more design constraints are involved. Another method which avoids waiting by the processor is to use a multiport memory with priority allotted to the processor. This leads to some picture breakup during updates but allows the processor to run at full speed.

Some such form of direct memory access is the much preferred system for high resolution raster scan graphics but can be very expensive when considering the quantity of memory necessary for display storage.

**Analog Graphics**

For those of you that haven't ordered a raster scan graphics controller after reading the previous dissertation, I would like to present the other side of the story: analog graphics. Usually the thought of anything analog associated with a digital computer is abhorrent to the purist. Remember, before there was digital there was analog; and even though it's hidden, analog's still there. The success of digital systems is based upon their ability to evaluate an action or output a value repeatably with no deviation from previous occasions, given constant input data. This is inherent in the machine structure, since it can only exist in either of two discrete states: 1 or 0, on or off, etc. Analog on the other hand can be influenced by external conditions such as temperature and power supply levels, etc, and is repeatable only within a more or less closely defined tolerance band. Industry has been tightening this tolerance band in recent years to such a point that analog circuitry becomes too expensive and digital methods are implemented. Too often, though, the "band wagon syndrome" prevails. Many applications which can be adequately accomplished using analog techniques have been converted to digital. In most cases this unnecessary conversion to digital can be very costly and requires expensive support equipment. The tolerance tightening which makes an industrial manufacturer use only digital does not exist for the home computer enthusiast. Many applications can be more cheaply done with analog. A prime example of this is graphics.

Analog graphics is a method which converts digital data stored in memory to voltage levels proportional to that value. Two of these digital to analog converters would be incorporated to provide two simultaneous outputs which represent physical X and Y coordinate locations on a display screen. The display's X and Y full scale deflection would be directly proportional to some analog constant times the digital value in the memory location being accessed. The display medium is an oscilloscope or similar two dimensional proportionally deflected display.

As was the case with raster scan graphics, analog graphics has both its advantages and disadvantages. The most pronounced advantage is the display method itself. Two bytes of memory converted to analog X and Y positions define the starting point of a line segment and two more set the analog values of the end point of that segment. When triggered by the controller a line will be drawn between these points. Four bytes define the entire line regardless of the length (within the limits of the screen dimensions of course). There is no need to define and store points along the line, only the beginning and end point. When using an 8 bit X and Y addressing system there are 64 K total locations between which line segments may be drawn. The path between any two points is direct line and need not coincide with an addressable point location. This results in an extremely high resolution display even though it is only 256 by 256. This means that in a diagonal line there is absolutely no "staircase effect" inherent in a raster scan display. This and relative low cost are the chief advantages.

The major disadvantage of this system is that it requires software refresh. When beginning and end points are sent to the controller a line is drawn — once! It will be seen briefly on the screen and quickly fade unless it is refreshed. The computer must do whatever it has to do and get back to the graphics driver program and write the same line segment again before it fades. This time between refreshes is a function of phosphor persistence, a characteristic of the CRT being used. 25 to 40 ms is usually the maximum and if exceeded will result in display flicker. (Storage tubes exist with longer time constants, but at much higher expense.) The number of lines which can be written and refreshed is a function of processor speed. The faster the processor, the
sooner it will be able to write a screen, do its own thing somewhere else, and return to start writing the screen again. All the displays in this article were driven by a slow 8008 processor (not an 8008-1) system and about 120 lines could be drawn before any flicker was perceptible. This was using a worst case programming technique (the one I'm best at) which I'll explain later. Faster processors would of course increase the number of lines capable of being displayed, but would have to have some delay loops in the software so as not to overdrive the graphics controller. The digital to analog conversion does take a little time.

An Analog Graphics Controller

The circuit for such an analog graphics controller is illustrated in figure 2. This circuit is based upon a design originally proposed by Hal Chamberlin in the first three issues of The Computer Hobbyist. Modifications and additions have been incorporated to allow more ease in calibration. The circuit consists of three major sections: digital input latches, digital to analog converters, and vector generators.

Since the graphics controller is software driven, possibly the software side is the easiest starting point. Positioning and drawing a line on the display is accomplished through four output commands from the processor. These commands are not some new processor instructions but rather decoded output strobes which transfer 8 bit position data from the accumulator to the controller's input latches IC1 to IC3. These four strobe commands are appropriately referred to as X-MOVE, Y-MOVE, X-STORE, Y-DRAW. In actuality, X-MOVE and Y-MOVE are the two bytes of data which define the starting location of a line segment while X-STORE and Y-DRAW is the end point of that line segment. There are four separate outputs necessary because we assume an 8 bit machine and 16 bits of XY positional data is needed to define a point on the screen. Obviously, in a 16 bit machine, this process could be reduced to two output instructions. Extra decoding is often not necessary. Many microprocessor systems like the Scelbi series provide extra decoding logic on the back plane wiring while not mentioning it. The usual clue is to check the IO decoder board in your system and look for an appropriate decoder chip such as a 7442 or 74154. Often only a couple of output strobes are utilized on the chip. In the case with the 7442 used in the Scelbi, the extra strobes allow quick unaggravated hookup to the four necessary for graphics.

IC4 and IC5 are 8 bit digital to analog converters. Their function is to convert the 8 bit position data into a current which is proportional to that value. IC6 and IC12 are current to voltage converters. The Motorola MC 1408-L8 consists of a reference current amplifier, an R-2R ladder, and eight high speed current switches. A resistor between a reference voltage and pin 14 is set to produce a reference current of approximately 2 mA. The R-2R ladder divides the reference amplifier current into binary weighted components which are fed to the switches. The output current from pin 4 will be proportional to the binary input to the converter. For example, if the binary input were equivalent to 128 decimal, then the output current would be (128/256) * 2.0 mA which equals 1.0 mA. The current to voltage converter is set to produce −2.5 V for a 00 000 000 binary input and +2.5 V for 11 111 111. Exact calibration procedure will be given later.

The heart of an analog graphics controller is the vector generator. This circuit does the actual drawing of the line on the display. Merely setting a starting location and jumping to an end point will not work. The beam's transition between the points would be so fast as to leave only a very weak trace if any at all. A vector generator provides a consistent drawing time of approximately 100 μs, allowing for a very bright trace.

Actually drawing a line segment is a simple series of events. First, the processor outputs sequentially the X and Y starting position coordinates with the X-MOVE and Y-MOVE commands. These values are stored in IC3 and IC1, respectively, and cause the digital to analog converters IC5 and IC4 to follow suit. Within 3 μs, IC6 and IC12 have settled out to a voltage representative of these coordinates. IC10 and IC11 are analog switches which route the raw X and Y voltages through the vector generator. These CMOS switches, equivalent to SPST, are in the off state when their control terminals are at a potential equal to VDD (−7.5 V) and on when it is at VSS (+7.5 V). IC19 is a voltage translator which converts TTL switching levels to those necessary for this CMOS device. An alternate circuit to replace the DM8800 is also provided.

In the quiescent state switches SW1 and SW3 are on and switch SW2 is off, as controlled by signals T1 and T2. This allows the output of the vector generator to be equal to the coordinate position of the beginning of the line segment. The trace is blanked at this time so the dot does not appear on the screen. Next, X-STORE then
NOTE: BUFFERING WILL BE REQUIRED WHEN USING A TYPICAL PROCESSOR DATA BUS.

VOLTAGE REFERENCE GENERATOR

CMOS SWITCH POWER SUPPLY

Figure 2: Schematic Diagram of a Vector Graphics Controller. This circuit will produce signals with a range of -2.5 V to +2.5 V for use in driving a standard XY oscilloscope with bandwidth greater than 100 kHz. The power supply wiring of digital...
NOTES:
1. Resistors are 1/4 W, ±5% unless noted otherwise.
2. All variable resistors are trimpots.
3. Capacitors are ceramic, 100 V minimum unless noted otherwise.
*Polystyrene or polycarbonate.

Integrated circuits used in this circuit is summarized in table 1. (Analog integrated circuits have their power wiring indicated in the diagram. These circuits are listed in table 1 but have no power connections indicated.)
Static Calibration

1. With all components except integrated circuits inserted and mounted, and presuming that you have no direct shorts, attach the controller to + and -15 V and +5 V and turn it on.

2. Using a meter, check to see that the right supply voltages are on the appropriate integrated circuit pins. Check to see that VRef is approximately 5 to 5.1 V and that the + and -7.5 V VDD and VSS supplies are correct. If substituting parts, don't use a zener any higher than 7.5 V since it could damage the CD4016s.

3. Insert only IC1 through IC3. Using either hard wire jumpers, switches or a computer program to drive the data bus lines B0 through B7, take note that when the bus inputs are all high, pins 5 through 12 of IC14 and IC15 are also high. Grounding all data bus inputs should result in low levels on these pins. It is a good idea to go down the bus one pin at a time to make sure that all input lines end at the correct DAC pins, otherwise the digital to analog conversion will be incorrect.

4. Turn power off. Insert the DAC IC4 and op amp IC6. Attach a meter to read the voltage at pin 6 on IC6. Set the bus input switches or programmed data value to provide a binary code of 10 000 000 (200 octal). Turn power on and adjust the zero pot (R3) on IC6 until the output at pin 6 reads zero volts. Change the input code to 11 11 111 (377 octal) and adjust the span pot (R6) until the output is ±2.50 V. Setting an input of 00 00 000 (0 octal) should result in -2.50 V out. The same procedure is used to calibrate IC5 and IC12. (Zero with R14, span adjust is R17.)

5. Turn off power. Insert IC16 through IC21. Temporarily, ground pins 1, 3 and 5 of IC20. Turn power on. Using either a pushbutton or cliplead intermittently ground IC20 pin 7 simulating a Y-DRAW strobe. A scope should be used to determine that IC16 pulses for about 10 µs and then triggers IC17 which lasts for about 100 µs. Control lines T1 and T2 should cycle between +7.5 V and -7.5 V corresponding to their TTL inputs.

6. Turn off power. Insert all the rest of the integrated circuits (be careful of the CMOS) and temporarily remove IC21. Reapply power and use the method in step 4, but take note that pins 6 on IC9 and IC15 are equivalent to IC6 and IC12 respectively. Turn off power, reinsert IC21. This concludes static checkout.

Dynamic Calibration

1. Unless you have super fast fingers on mechanical switches, a computer is necessary for dynamic checkout (while it is optional in static checkout). It is necessary to write a short program which outputs to the controller the full scale coordinates of a square with two diagonals (see figure 3).
was left from the last line segment, so it is possible to reduce software overhead considerably on continuous line graphs by just issuing a series of new endpoints.

Maximum drawing rate can easily be determined for those who wish to use a faster processor. Each voltage converter requires about 3 to 5 μs to settle out and a draw cycle takes 110 μs. This means that 5 μs at least must be allowed between input of the beginning and endpoints and 110 μs must lapse before starting the next line segment. With an 8008 such as I used, there is little possibility of driving the controller too fast, but with an 8080A system a delay loop may be necessary between segments. The next step is to do some cartooning with software.

Obviously before we can get too carried away discussing graphics software you must get your controller calibrated and working. The procedure outlined in "Notes on Calibrating This Graphics Controller" should result in the best chance for success.

**Now How Do I Use It?**

Now that the hardware of vector graphics has been conquered, you should be ready to write some simple display routines. Anyone owning a home computer system is always at a loss to justify it to friends and family who continually ask what purpose it serves. By using a little psychology and realizing that these people identify most often with Mom's apple pie, McDonald's and Star Trek, a little ingenuity can go a long way. Graphics goes a long way in impressing nonbelievers, especially when the computer is generating a picture of the USS Enterprise, shown in photo 1.

Drawing the Enterprise entails a program (see listing 2) which is very similar to that used for calibration (listing 1) except that the point list is longer so the program is written to accept variable length lists. There are many methods to program graphics. The easiest from the software point of view, but the worst for drawing speed and total number of lines, is to treat each line as an entity in itself. Four bytes would define the line segment as in listing 1's data table. This is required wherever it was placed on the screen, disregarding those displays which appear continuous as would be the case of a square or a triangle. As a specific example, 12 bytes are required to store the coordinates of a triangle when the three sides are treated as three line segments. Only 8 are required if a continuous drawing technique is incorporated. The problems arise when a display is made up of both disjointed and continuous lines. The program can be written to output one list of continuous

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This square is all that is necessary to check out the remainder of the controller interface. (The X, Y and blanking outputs of the graphics controller have to be connected to an appropriate display. Any XY oscilloscope with a 100 kHz frequency response and an external horizontal input capability will suffice. The controller has to be connected to the output data bus and four decoded strobe lines.) The software which draws the calibration square is quite simple and consists entirely of outputting a list of coordinates stored in memory. The program of listing 1 was written for an 8008 system but is easily adapted to others.

2. If upon first turning on the display you obtain a perfect square with the diagonal meeting in the corners, go have a martini and relax, you're done (see figure 1c). It is more likely that the displays will only vaguely look like a square. If the line segments are too long or are too short and don't meet in the corners, adjust the end match adjustment, R24, on IC17, until perimeter segments (disregard the diagonals at this point) meet in the corners.

3. Next, fiddle with the slope adjustment pots (R10 and R21) until the diagonals meet in the corners. Any problems in accomplishing any of this is probably a result of the following: Frequency response of the op amps is too low (don't use anything slower than a 301A); the RC time constant of the slope adjustment is inadequate; your CD4016 crapped out; or your program is outputting incorrect coordinates.
Photo 1: The author's Sanders 708, a surplus vector graphics display, shown portraying the Star Ship Enterprise using data of table 2 and figure 4. The lettering is not included in table 2.

Listing 1: An 8008 Program to Generate the Calibration Pattern. The listing uses original Intel 8008 mnemonics; the data table at the end of the listing contains two bytes of starting coordinate followed by two bytes of ending coordinate for each point in the pattern.

<table>
<thead>
<tr>
<th>Split</th>
<th>Octal</th>
<th>Octal</th>
<th>Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>001/000</td>
<td>066</td>
<td>001</td>
<td>START</td>
<td>LHI</td>
<td>H(TABLE)</td>
<td>Page address, data table;</td>
<td></td>
</tr>
<tr>
<td>001/002</td>
<td>066</td>
<td>040</td>
<td>LLI</td>
<td>LTABLE</td>
<td>LTABLE</td>
<td>Byte address, data table;</td>
<td></td>
</tr>
<tr>
<td>001/004</td>
<td>307</td>
<td></td>
<td>XFERLOOP</td>
<td>LAM</td>
<td>XMOVE</td>
<td>Perform XMOVE output;</td>
<td></td>
</tr>
<tr>
<td>001/006</td>
<td>060</td>
<td></td>
<td>INL</td>
<td>OUT</td>
<td>YMOVE</td>
<td>Perform YMOVE output;</td>
<td></td>
</tr>
<tr>
<td>001/007</td>
<td>307</td>
<td></td>
<td>LAM</td>
<td>XSTORE</td>
<td>XSTORE</td>
<td>Perform XSTORE output;</td>
<td></td>
</tr>
<tr>
<td>001/010</td>
<td>143</td>
<td></td>
<td>OUT</td>
<td>XDRAW</td>
<td>YDRAW</td>
<td>Perform YDRAW output;</td>
<td></td>
</tr>
<tr>
<td>001/011</td>
<td>060</td>
<td></td>
<td>INL</td>
<td>XSTORE</td>
<td>XSTORE</td>
<td>Point to XSTORE value;</td>
<td></td>
</tr>
<tr>
<td>001/012</td>
<td>307</td>
<td></td>
<td>LAM</td>
<td>OUT</td>
<td>YDRAW</td>
<td>Point to next YMOVE value;</td>
<td></td>
</tr>
<tr>
<td>001/013</td>
<td>145</td>
<td></td>
<td>OUT</td>
<td>XSTORE</td>
<td>XSTORE</td>
<td>Point to YDRAW value;</td>
<td></td>
</tr>
<tr>
<td>001/014</td>
<td>060</td>
<td></td>
<td>INL</td>
<td>XSTORE</td>
<td>XSTORE</td>
<td>A := L [check end address</td>
<td></td>
</tr>
<tr>
<td>001/015</td>
<td>307</td>
<td></td>
<td>LAM</td>
<td>XSTORE</td>
<td>XSTORE</td>
<td>low order];</td>
<td></td>
</tr>
<tr>
<td>001/016</td>
<td>151</td>
<td></td>
<td>OUT</td>
<td>XSTORE</td>
<td>XSTORE</td>
<td>Is end of table reached?</td>
<td></td>
</tr>
<tr>
<td>001/017</td>
<td>060</td>
<td></td>
<td>INL</td>
<td>XSTORE</td>
<td>XSTORE</td>
<td>If not then continue loop;</td>
<td></td>
</tr>
<tr>
<td>001/020</td>
<td>306</td>
<td></td>
<td>LAM</td>
<td>XSTORE</td>
<td>XSTORE</td>
<td>Restart pattern when done;</td>
<td></td>
</tr>
</tbody>
</table>

Notes:

XMOVE, YMOVE, XSTORE and YDRAW are output port assignments of the author's system, corresponding to the strobe lines of figure 2.

All constants in this listing are octal.

H(TABLE) is high order 8 bit field of address of TABLE; L(TABLE) is low order 8 bit field of address of TABLE. The two high order bits of H(TABLE) are ignored.
flicker. However, a surprising number of lines can be displayed before flickering occurs when using the separate line technique.

To write a stationary display routine, it is necessary to determine the coordinate points of the picture's vectors. Graph paper which has been ruled for 377 by 377 octal squares (or hexadecimal if that's your preference) is not easily obtained, so be ready to count squares and label ordinary graph paper. Figure 4 illustrates the technique of creating a display table using graph paper. The illustration is drawn first, using a ruler or other straight edge to provide the lines. A pencil is a must at this stage, since erasure is a very real requirement when working out any sketch. Once the drawing has been finalized, octal coordinates are added to the basic graph paper pattern. In the case of the Enterprise, I wanted to fill the screen, so I scaled the coordinates to use most of the display area in the horizontal (X) direction, and used the same scaling in the vertical (Y) direction. Then, the vector list is created by going over the drawing line by line and determining the four coordinates required. The small numbers near the line segments in figure 4 identify the octal addresses of these line segments in the vector table, table 2. When the data for a picture is all encoded from the graph paper, it can be loaded into your computer's memory. If your processor is an 8008, then the program of listing 2 can be loaded and executed; otherwise, you'll have to create an equivalent program for your own processor. (The data of table 2 remains the same regardless of the processor used.)

What's Next?

There is a fundamental problem with the home computer system or should I say the home computer experimenter. The systems keep getting bigger and more expensive.

Continued on page 120

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**Listing 2: An 8008 Program for Drawing Lengthy Pictures.** This program is similar to the program in listing 1 with the addition of a generalized end of data test. In operation, it will be the sole program active in the 8008, continuously cycling through the vector table which starts at location 001/050.

<table>
<thead>
<tr>
<th>Split Octal Addr</th>
<th>Octal</th>
<th>Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>001/000</td>
<td>056</td>
<td>001</td>
<td>START</td>
<td>LHI</td>
<td>H(TABLE)</td>
<td>Set up the memory pointer to the beginning of table;</td>
</tr>
<tr>
<td>001/002</td>
<td>066</td>
<td>050</td>
<td>LHI</td>
<td>LTABLE</td>
<td>LTABLE</td>
<td>Perform XMOVE output;</td>
</tr>
<tr>
<td>001/004</td>
<td>307</td>
<td>LAM</td>
<td>XMOVE</td>
<td>A := XMOVE value;</td>
<td></td>
<td></td>
</tr>
<tr>
<td>001/006</td>
<td>143</td>
<td>OUT</td>
<td>INL</td>
<td>YMOVE</td>
<td>YMOVE</td>
<td>Perform YMOVE output;</td>
</tr>
<tr>
<td>001/007</td>
<td>307</td>
<td>LAM</td>
<td>XSTORE</td>
<td>Point to XSTORE value;</td>
<td></td>
<td></td>
</tr>
<tr>
<td>001/010</td>
<td>147</td>
<td>OUT</td>
<td>INL</td>
<td>YDRAW</td>
<td>YDRAW</td>
<td>Perform YDRAW output;</td>
</tr>
<tr>
<td>001/011</td>
<td>060</td>
<td>LAM</td>
<td>OUT</td>
<td>A := YDRAW value;</td>
<td></td>
<td></td>
</tr>
<tr>
<td>001/012</td>
<td>307</td>
<td>OUT</td>
<td>XSTORE</td>
<td>Point to next value;</td>
<td></td>
<td></td>
</tr>
<tr>
<td>001/013</td>
<td>145</td>
<td>LAM</td>
<td>XSTORE</td>
<td>A := next value [may be XMOVE or END];</td>
<td></td>
<td></td>
</tr>
<tr>
<td>001/014</td>
<td>060</td>
<td>INL</td>
<td>YDRAW</td>
<td>If not then continue inner loop;</td>
<td></td>
<td></td>
</tr>
<tr>
<td>001/015</td>
<td>207</td>
<td>LAM</td>
<td>XSTORE</td>
<td>Else increment high order address;</td>
<td></td>
<td></td>
</tr>
<tr>
<td>001/016</td>
<td>151</td>
<td>OUT</td>
<td>INL</td>
<td>JMP</td>
<td>START</td>
<td>Else restart the program;</td>
</tr>
<tr>
<td>001/017</td>
<td>060</td>
<td>NOINCH</td>
<td>377</td>
<td>Is it END of data value?</td>
<td></td>
<td></td>
</tr>
<tr>
<td>001/020</td>
<td>110</td>
<td>JNZ</td>
<td>024</td>
<td>END</td>
<td>END</td>
<td></td>
</tr>
<tr>
<td>001/021</td>
<td>250</td>
<td>INL</td>
<td>001</td>
<td>END</td>
<td>END</td>
<td></td>
</tr>
<tr>
<td>001/022</td>
<td>140</td>
<td>JNZ</td>
<td>000</td>
<td>END</td>
<td>END</td>
<td></td>
</tr>
<tr>
<td>001/025</td>
<td>074</td>
<td>CPI</td>
<td>377</td>
<td>END</td>
<td>END</td>
<td></td>
</tr>
<tr>
<td>001/027</td>
<td>110</td>
<td>JNZ</td>
<td>005</td>
<td>END</td>
<td>END</td>
<td></td>
</tr>
<tr>
<td>001/032</td>
<td>104</td>
<td>JNZ</td>
<td>000</td>
<td>END</td>
<td>END</td>
<td></td>
</tr>
</tbody>
</table>

---

Photo 2: A scope trace of the X coordinate output of the circuit in figure 2 during the display of a typical picture. The trace is 3 V full scale and is approximately 15 ms long. The transition time from one voltage to the next is fixed by the hardware at 100 μs (approximately 1/150th of the horizontal width of this picture).
Conversion Patch

Regarding the September 1976 issue, the following points were phoned in by Bob Van Valzah, 1140 Hickory Trail, Downer's Grove II.

On page 58, in listing 4b of James Brown's article “How To Do A Number of Conversions,” a typographical error occurred at address 0021. The correct code and comment is:

```
0021 6F MOV A,L
```

Bob also points out that zero suppression works “too well” with the decimal routine as designed by author Brown: It suppresses a zero value completely. Bob suggests the following patch replacing line 44 (and pushing TENSTABL down in relative address space):

```
MOV A,C get NONZERO flag;
ORA A test and set flags;
RZ original return if some digits printed;
MV1 A,'0' output of an ASCII zero character and return if all blank so far;
JMP PUT
```

To use this patch, the reference to TENSTABL will have to be modified at location 0001.

Patch of a Patch

The suggested biorhythm program patch given on page 100 of your July issue contains an error. This patch will, in fact, initiate all cycles in phase beginning at one's birthdate; but, if used as specified, errors occur in the incrementing of dates on the chart. By deleting lines 130 to 470, the loop which reads data into the vector T(I) is deleted. Data must be read into this vector in order for the chart dates to increment properly. I therefore suggest that the following patch be added to the previous patch.

```
122 FOR I = 1 TO 12
124 READ T(I)
126 NEXT (I)
```

This may save problems for some of your readers.

Gary Sleater
302 E El Caminito Dr
Phoenix AZ 85020

The Price Is Wrong

According to IMS Associates, the price of the IMSAI floppy disk drive and interface controller mentioned on page 83-84 of BYTE's September 1976 issue is $1919 assembled, $1719 unassembled; additional drives without a cabinet are $1095. The prices quoted in “What's New?” are incorrect.

Here Are Design Equations

In Bruce Filgate's article, “A Morse Code Station Data Handler,” October 1976, we omitted the design equations for the NE567 tone decoder which should have been printed in figure 6, page 70. To remedy the situation, here they are:

```
Center Frequency: F = \frac{1}{(R1 * C1)}
Band Width: BW \approx 1070 * \sqrt{\left(\frac{V1}{(F * C2)}\right)}
```

where:

- R1, C1 and C2 are as defined in figure 6, page 70 of October BYTE
- V1 is the input voltage to the circuit
- F is the center frequency.

Refining the Plot

Author Richard Lerseth reports that he received a letter from J C Rucklidge, associate professor of geology at the University of Toronto, Ontario CANADA. Prof Rucklidge used Richard's article (“A Plot is Incomplete Without Characters” in July 1976 BYTE) to program character outputs from his system. In so doing, he verified the accuracy of the printed tables, but found one minor error in equations 16 and 17 on page 70. These equations should read:

```
X = XO + H * DHX + (V - 5.0) * DVX (16)
Y = YO + H * DHY + (V - 5.0) * DVY (17)
```

Caveat Programme

Past history has shown that occasional typesetting or logic bugs occur in programs printed in BYTE. Readers who find such bugs are urged to claim a bit of fame in this column by sending us the evidence, and suggested patches. Two examples have been documented here this month.

A Bug Way Back

Boyd S Miner, K4KEP, editor of Bits and Dits, the newsletter of the Carolina Computer and Radio Amateur Association, points out an error in the statement of amateur radio Teletype mark and space frequencies in the September 1975 issue of BYTE, page 32:

```
Don Lancaster puts out some real good articles but in "Serial Interface" in BYTE September 1975, page 32, he states that Ham radioteletype audio frequency shift keying (AFSK) 2125 is mark and 2925 is the space frequency. This "tain't so." The mark and space tones are multiples of 425 Hz. In fact they are the 5th and 7th harmonics.
```

Therefore the mark is 2125 as stated but the space is 2975, not 2925. At the time these standards came into being the FCC required 850 Hz shift.
A Note about Borrowing Routines from EDUCATOR

The EDUCATOR program from the Digital Group is an extremely effective way to learn what takes place within the processor when you are learning machine level programming.

The EDUCATOR-8080 article in the July 1976 BYTE [page 22] appears to contain at least two errors. I discovered these when attempting to use some of its text display routines.

The article neglects to mention that the user defined subroutine CHRPR (character print) has to add 200 (octal) to the code in the accumulator to get a valid ASCII character.

The subroutine CHEDT loops indefinitely on the first string of blanks. The HL register needs to be incremented after a string of blanks is output. I inserted an INX H (043 octal) between the present lines 000/310 and 000/313 appearing on page 26 of the July issue.

Since the listings published are obviously not exactly those used in the Digital Group software, the readers should be advised that further debugging may be necessary.

Dr Charles F Douds
281 Poplar St
Winnetka IL 60093
Clubs and Newsletters

**KIM-1 USER NOTES**

At the Midwest Regional Computer Convention held in Cleveland, a group of KIM-1 users had the opportunity to meet with Rick Simpson of MOS. The group agreed that there was a need for KIM-1 owners everywhere to be able to exchange ideas much like other user groups, and that a newsletter would act as a vehicle for that purpose.

*KIM-1 USER NOTES* will be published every 5-8 weeks. Cost for subscriptions will be $5 for the next six issues (including first class postage). This rate is for US subscribers only. Make checks and money orders payable to: KIM-1 c/o Eric Rehnke. No cash please. Write: KIM-1 USER NOTES, c/o Eric Rehnke, Apt No. 207, 7656 Broadview Rd, Parma OH 44134.

**South Florida Computer Group — I/O**

In the August issue 1-4 it was announced that Dr Bruce Cameron will be the new editor of I/O. Bruce is a research biochemist with Papanicolaou Cancer Research Institute (PCRI or PAP). All inquiries, news items, articles, etc., should be sent to him at 1155 NW 14th St, Miami FL 33136; or phone (305) 324-5572.

The group has in the past sent complimentary issues to interested individuals, other clubs, and firms; but the club’s mailing list has grown to such a point that now it’s necessary to charge a fee of $2 per year for 12 issues. This will not affect the exchange of newsletters with other clubs.

**Space Coast Microcomputer Club — Florida**

This club at present (August) consists of about a dozen individuals who are interested in microprocessor-based computer systems. A few are employed at the John F Kennedy Space Center, while others are affiliated with Florida Institute of Technology and Florida Technological University. Many members also belong to the larger computer clubs such as the Southern California Computer Society and the Chesapeake Microcomputer Club. The purpose of this club is to further the usage of small computer systems through the mutual sharing of ideas and resources.

Ray O Lockwood would be interested in hearing from you. His address is: 1825 Canal Ct, Merritt Island FL 32952, (305) 452-2159.

**The New Orleans Hamfest and Computer Fest**

On October 30-31, the New Orleans Hamfest and Computer Fest will be held at Archbishop Rummel High School, 1901 Severn Av, Metairie LA (a New Orleans suburb). This event is sponsored by the Jefferson Amateur Radio Club.

The Louisiana Council of Amateur Radio Clubs, the Louisiana ARRL Convention, MAR and other amateur radio groups are scheduled to meet. Banquets, noncommercial and other exhibits are being arranged. Call-in frequencies will be 146.34-94 and 3.95 MHz.

Reservations and latest details may be obtained by writing to Dominick “Nick” Tusa, WASRMC, chairman, New Orleans Hamfest, POB 10111, Jefferson LA 70181.

**Byte Back — Ohio**

Compute, Evaluate, Trade is the name of a new club in Ohio. Meetings are held in members’ homes on the first Saturday of the month. There are no dues, other than talent and a desire to exchange information. Business applications are their special interest. Charles E Tyzzer Jr is the contact person, and he may be reached at (513) 268-6551 x587. The mailing address is: POB 104, Tipp City OH 45371.

**Southern New England Computer Society**

SNECS was formed at a meeting held in New Haven CT in July. Those present came from parts of Connecticut bordering on Rhode Island as well as Fairfield and the Hartford and New Haven areas. They represented a broad range of hardware, software, business, educational, and hobby interest in computers. A newsletter is in the works, and it will be called YANKEE BITS. Anyone wishing more information on this group should write: SNECS, 267 Willow St, New Haven CT 06511.

**Ride the Data Bus — Michigan**

Data Bus is the official newsletter of the Southeastern Michigan Computer Organization. Subscription is only available to persons living more than 50 miles from Detroit, at $6 per year (unless you’re a member). Data Bus is also available on a newsletter exchange basis to other clubs. The editor is Jon Tara (313) 833-2847. The address is SMCO, Data Bus, 665 W Hancock No. 304, Detroit MI 48201.
Charlotte, North Carolina

A new club has been formed in the Charlotte NC area. Anyone interested in computer society may call Dr Michael Allen,

Purdue Has PUNCH

Michael A Troutman, PUNCH president, informed us of the official existence of the Purdue University Computer Hobbyist Club. Mike says they have a constitution and are fully recognized as a student organization. The club meets weekly in the digital lab of the Electrical Engineering Building. The group is also planning lectures by key speakers for every other month. Their resources (those of EE) include two 6800 systems (Motorola and SWTPC), an 8080 system, a KIM-1 system, several CRT terminals, Teletype, high speed paper tape reader and access to the EE Dept PDP-11/70 timeshare system.

Membership is limited to students, staff and faculty; however, for a small activities fee, anyone is welcome to attend meetings. All interested persons may write to PUNCH, Room 67, Electrical Engineering Building, Purdue University, West Lafayette, IN 47907.

Charlotte, North Carolina

A new club has been formed in the Charlotte NC area. Anyone interested in making contact with the Charlotte Microcomputer Society may call Dr Michael Allen.

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at (704) 597-2303 days; and Allen Grayson at (704) 366-7879 nights. Allen Grayson is interested in down to earth applications for computers. An example is the one he cited: A friend wrote a program creating a robot lawn mower. Now his friend sits back with his favorite beverage under a nice shade tree and watches his "robot" do the work.

Northern New Jersey

The Northern New Jersey Amateur Computer Group opens its membership to any interested person for an annual fee of $5. Meetings will be held from 6:30 to 11:00 PM the second Friday of each month at Becton Hall, Fairleigh Dickinson University, Rutherford Campus, Rutherford NJ. For further information, contact Murry P Dwight, Dwight Instruments Company, 593 New York Av, Lyndhurst NJ 07071. Phone: (201) 438-3334.

TRACE — Ontario, Canada

Toronto Region Association of Computer Enthusiasts has over 50 members in the greater Toronto, Hamilton, and Kitchener, Ontario areas. They meet once a month, usually on the first or second Fridays. For details concerning the club and newsletter, write: TRACE, Box 545, Streetsville, Ontario CANADA L5M 2C1.

Waterloo — Ontario, Canada

The Amateur Microprocessor Club of Kitchener-Waterloo, Ontario, has formed, with Charles Sooley acting as interim coordinator. The group has made some quantity purchases. For further information write: Amateur Microprocessor Club of Kitchener-Waterloo, Ontario, Canada, c/o Reading Room, Electrical Engineering, University of Waterloo, Waterloo, Ontario CANADA N2L 3G1.

Auckland, New Zealand

Info File of Mt Roskill has formed a group of N2 users and is asking help in getting off the ground. They need schematics, PC board layouts, and software. Newsletters would be appreciated. Write: Info File, POB 27-206-B, Mt Roskill, Auckland NEW ZEALAND.

Teen Hobbyist

Jeffrey Rice, 16, of 303 Wilson St, Elkins WV 26241, would like to join or form a computer club in his area, if there is any interest. Enterprising Jeff, a would-be computer hacker, is working two paper routes and holding a part time job assembling boards for a local microcomputer distributor. He is saving up to buy a 8800 or 6800 based system while attempting to educate himself in computer science. He writes that between the BASIC he’s learning on the PDP 8/E system, the minimal configuration COSMAC computer he is building, and as much literature as he can obtain, along with his “hands-on” hardware experience with his job, he’s doing OK. You can contact him at the above address.

Ottawa — Ontario, Canada

We have received word that a group calling itself the Ottawa Computer Club has formed. At the present time the only information we have is that the meeting schedule is posted at Pettazzoli College Residence, located at Rideau and Chapel Av, Ottawa, monthly. They are looking for new members, and if you would like to play Sherlock Ohms, we suggest you investigate.

Curriculum Developer Needs Inputs

Robert F Tinker has founded Technical Education Research Center, located at 575 Technology Sq, Cambridge MA, phone (617) 547-3890. He is interested in creating curricula in the emerging technologies of low cost electronics for student use. A newsletter, Hands On!, is proposed as a quarterly transmission line for practical laboratory oriented educational ideas with a bias toward the uses of electronics and computers.

Denver Amateur Computer Society

DACS Newsletter, Volume 2/1, has mushroomed. The July issue was expanded to 44 pages. Some of the changes include longer features, new products, users' reports, tips, and "Dear Nina," letters from wearied and/or wearisome wives to the editor. The club is also holding a contest to come up with a name for the publication; the prize is a year's free membership. Entries, along with subscription orders ($9) should be sent to Jim Clark, DACS Newsletter, POB 6338, Denver CO 80206.

RPI ACM Chapter (Capital District NY)

Jerry Irving of RPI writes: The Rensselaer Polytechnic Institute student chapter of the ACM is forming a special interest group for people who are interested in minis and micros. We have had one meeting to see how much interest there would be and found a great deal of it. The group will be open to anyone, not just students. Those in the
The capital district area of New York should be just a short drive from RPI. There are many minicomputers on the RPI campus and a number of people at the first meeting who are starting to build their own systems. This group is forming in order to supply a place for people to meet to compare their systems, exchange ideas, and give them the advantages of being in a nationally recognized organization. Once under way we will have regular meetings and try to have speakers and demonstrations as often as possible.

We plan on having our organizational meeting to set up the foundation of the group in either August or September. Anyone interested in coming or joining should write to the RPI-ACM, Amos Eaton Hall, RPI, Troy NY 12180, or call either Jerry Irving (518) 756-6827 or Will Strang (518) 274-8361 for information and directions.

The Computerist - NECS

The Computerist is an extension of the New England Computer Society. The club's newsletter is prepared on a text editor, and is printed by reduced photo offset. In

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Volume 1/1 the goals are set forth: To serve all computerist and computer clubs in the New England region, report on club meetings, print a monthly calendar of regional events. It will also provide up to date reports on new products, publications, local suppliers, mail order dealers, and the like. It will also include a classified section, and both commercial and individual advertisements. The Computerist is an independently produced publication, which is the official newsletter of the New England Computer Society, and is supported in part by dues and subscription. Subscription rate is $6 per year. Robert Tripp is the contact man; his address is POB 3, South Chelmsford MA 01824.

Communication Co-operative for the Deaf and Hearing Impaired

The Communication Co-operative is a nonprofit organization establishing a time sharing computer system in the Northwest. Its purpose is to provide data processing services in order to help support a communications system for the deaf. This enables it to offer flexible computer services at reasonable rates and tailored to the needs of any business. Some of the services offered to businesses are inventory control, mailing lists, billing, and purchase orders. They also offer a 24 hour emergency service for the deaf, using Teletypewriter, and make available national and local news stored in a file and accessed by the Teletypewriter. If you would like to learn more, write: Communication Co-operative, POB 182, W Linn OR 97068.

Byte Out of Maple Address

"Someone took a byte (or two) out of the address for MAPLE, and I don’t know whether all mail is arriving here," writes John Sikorski, president of "Microprocessor APL Enthusiasts," of the Clubs and Newsletters item on page 100 of September 1976 BYTE. The full address is:

MAPLE
Box 574 NUMS
303 E Chicago Av
Chicago IL 60611

Stamp Out Cybercrud

Have you every been victimized by one of a myriad computer based interpersonal putdowns? In Ted Nelson's book, Computer Lib/Dream Machines, you'll find an excellent essay on the nature of this "cybercrud." Have you ever wondered where to go for a basic starting point in your quest for information about computer applications and uses? Ted Nelson's book, Computer Lib/Dream Machines, is the place for you to begin.

Computer Lib/Dream Machines is for the layman — the person who is intelligent and inquisitive about computers. It is written and self published by a philosopher who is also a self confessed computer fan and an excellent teacher of basic concepts. (For those who have not yet heard, ivory towers are constructed out of real and substantial white bricks.) The most important aspect of this book is its inspirational data content. The machines we're all busy working on are deep personal expressions, and not the cold and inhuman monsters of the traditional stereotype. The book defines many of the terms and explains many of the techniques which can be used in the personal computer systems we're all busy constructing and programming. It performs this service in a way which adds color and excitement to this newest of art forms, the computer application. Computer Lib/Dream Machines is must reading for the beginner, and is also a refreshing self examination for the old hand at programming and systems work.

You can order your copy of Computer Lib/Dream Machines from BYTE's Books for $7. Send your order today to BYTE's Books, 70 Main St, Peterborough NH 03458. Help stamp out cybercrud.

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Ted Sage. "This book is designed as a text for a one-semester course in computer programming using the BASIC language. The programs used as illustrations and exercises are games rather than mathematical algorithms, in order to make the book accessible to more students. The text is written, with many excellent sample programs. Highly recommended." —The Mathematics Teacher 351 pp. $5.95 [8B]

Game Playing With the Computer, 2nd Ed.

Donald Spencer. Over 70 games, puzzles, and mathematical recreations for the computer. Over 25 games in BASIC and FORTRAN are included complete with descriptions, flowcharts, and output. Also included is a fascinating account of the history of game-playing machines, right up to today's computer war games. Lots of "how-to" information for applying mathematical concepts to your own game. 320 pp. 1976 $14.95 [85]

BYTE Magazine

If you are considering a personal computing system now or later, BYTE provides a wealth of information on how to buy it at an affordable price. Covers theory of computers, practical applications, and a row of "how-to" articles to help you build it. Monthly. 1-year sub $12.00 [2A], 3-years $30.00 [2B]

Games & Puzzles Magazine

The only magazine in the world devoted to games and puzzles of every kind—mathematical, logical, problematical, word games, crosswords, chess, gobimoko, checkers, backgammon, wargames, card games, board games, and more. Monthly. 1-year sub $12.00 [3A]

Games with the Pocket Calculator

Srivatsam Thagurasain and Harold Storkow. A big step beyond tricks and puzzles with the hand calculator, the two dozen games of chance and strategy in this clever new book involve two or more players in conflict and competition. A single impulse or four-figure answer is all you need to play. Large format. 50 pp. $2.00 [88]

Artificial and Computer


Computer Science: A First Course (2nd Ed.)

Forsythe, Keenan, Organick, and Steinberg. A new, improved edition of this comprehensive survey of the basic components of computer science. Contains a refreshing update of important areas such as: Programming, Software Engineering, Problem Solving, and other Computer Science Co-principal. An examination of exercises and problems has been increased. 876 pp. $16.95 [7D]

Mr. Spock Poster

Dramatic, large (17" x 23") computer image of Mr. Spock on heavy poster stock. Use two levels of overprinting. Comes in strong mailing tube. $1.50 [58]

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A Suggestion is Fulfilled

In last month's new products section, a touch tone frequency generator was suggested as a possible portable product to be used as a portable data terminal. Well, a company called Executive Devices has produced a product which incorporates such a frequency generator and can be easily used in the portable terminal mode. This battery powered hand held device generates the full 16 combinations of tones possible with the touch tone encoding technique, and interfaces with the telephone network through an acoustic coupler. There are two models available:

Pocket Data Terminal PDT-700 is $49.95, postpaid, and is the simple tone generator version. (Kit version $39.95.)
Pocket Data Terminal PDT-1000 is $89.95 postpaid, and is an extended

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--- INTRODUCTORY OFFER ---
The Computer Co. of the Future
feature model with a nonvolatile user programmed memory - of seven digits for automatic dialing of a frequently used number. (Kit version $69.95.)

Of course the auto dial product by itself won’t do much for people stuck out in a country telephone exchange with relays and stepper switches for dialing, but any computer equipped with an auto answer function to a telephone port can receive and decode the touch tone frequencies of this device. For the home hacker, this can be accomplished by tapping into the audio section speaker outputs of a commercial ATT approved phone answering device. The auto answer logic is built into such a phone answering device, so all the computer has to do is to test the cassette motor control line and listen through a bank of tone sensitive filters for the frequencies involved. According to verbal reports, several individuals are already at work automating such home functions as lighting control through remote ports accessed in this manner; there ought to be a market niche for the commercial answering equipment needed (to plug into an Altair or other computer main frame).

Real Time Programming, Anyone? (or How to Make a Perpetual Audio Visual Date Book)

COMPTEK, a company located at POB 516, La Canada CA 91011, has come up with just the thing needed to implement the application in the subtitle of this new products story. In order to implement a real time process such as an appointment book, some means of noting time and date digitally for each hour of the day, every day of the year, is required.

The way to accomplish this time measurement is to use this $98 real time clock board for the Altair or IMSAI computers. The board contains a conventional LSI clock chip, the National Semiconductor MM5318N shown in the photograph (the largest plastic package integrated circuit). The clock interfaces to the Altair in either a programmed I0 mode, or an interrupt I0 mode of operation. For clock interrupts, the board can be programmed to interrupt 60 times per second, once per second, once every 10 seconds, once per minute, once every 10 minutes (radio amateur take note), once per hour, or twice per day. Also programmable through the board are the fast setting modes of the clock chip.

The microcomputer system treats the clock as a peripheral, and reads the time directly in a 24 hour HH.MM:SS format, BCD encoded. For the user wanting to implement the date book, some software information management structures will of course have to be created to use it, but the hardware of this board is a key element which makes such a system possible. Imagine: your computer with its audio and video output devices nagging you to get up, go on vacation, keep the appointment with the dentist, etc.

Is This a Programmable Calculator or Computer System?

Here is the latest Hewlett-Packard innovation, the flexible disk drive for the desk top calculator. The disk drive plugs into the HP 9825 disk top programmable calculator, to provide mass storage capability far beyond the built-in data cartridge drive. The new product comes in two forms. The 9885M master disk drive is priced at $3900, and the 9885S slave (up to three of which may be used with one 9885M controller) is priced at $2500. The 9825 can handle eight of the 9885M units, making it possible for the extreme case of 32 disk drives run by one calculator. Since each disk holds 468,480 bytes of data, in the extreme, the calculator could have 14,991,360 bytes of on line random access storage — hardly a mere desk top calculator’s worth of mass storage.

The disk option will prove a most useful feature for this calculator, which is programmed in a high level language command system. The disk option extends the software of the calculator to include a directory feature for up to 320 named files on disk. All operations are done in a write-then-verify mode to ensure reliability.

Hewlett-Packard is located at 1501 Page Mill Rd, Palo Alto CA 94304.

Breadboard Kit Including Slit-N-Wrap Tool

Vector Electronic Co, 12460 Gladstone Av, Sylmar CA 91342, has introduced this new modular breadboarding kit containing 36 different parts. The list includes terminals sockets, perforated circuit boards, wire, tools and many other items designed for custom wrapped wire circuit construction. The kit is designed 41X by the company, and the total cost of parts for the kit is lower than the catalog prices when ordered separately.

The kit contains the P180 Slit-N-Wrap tool to wrap and strip insulated wire found on a spool. This tool is a must for wrapping of extended bus structures, since there is no time consuming stripping or measuring to be performed. I’m using the P180 to complete a bus structure of backplane connectors on my homebrew system which has been partially assembled for months due to the inconvenience of the cutting and stripping with conventional wire wrap... CH/

In addition, the kit contains ten 16 pin DIP sockets, five types of wrap posts, and Vectorboard socket cards with and without printed circuit pads and buses. Also included are extruded aluminum frames to support the circuit board as a chassis.

The price of this omnibus kit of Vector’s excellent products is $56.50, and it is available from stock. The 41X Multi-Conn Kit can be ordered directly from the factory (write to the attention of “Dept X”), Vector products are frequently found at retail computer stores, and retailers of the Vector line may find this an excellent “gift” product for the walk-in trade.

E&L Instruments Increases Memory and Interface Capabilities of Their MMD-1 Microcomputer with an Accessory Board

A new accessory board model MMD-1/MI with extra RAM memory, Teletype Interface, and audio cassette interface has been added to the E&L Instruments line. The MMD-1/MI simply plugs into the built-in card edge connector on the MMD-1 and mounts on top of the unit as shown in the photo.

A MMD-1/MI accessory board completely assembled and tested, sells for $200. In kit form with all parts for assembly, the price is $150. The MMD-1/MI has the following features:

• 2K byte programmable memory capability (1 K supplied).
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The Briefcase Computer Concept, Revisited

This neat little package of computing power, the DE68, made by the Digital Electronics Corporation, 415 Peterson St, Oakland CA 94601, is intended for use as a stand alone computer system in a briefcase. The system is completely self-contained, with the following characteristics:

- 6800 microprocessor.
- alphanumeric keyboard (96 character).
- miniature electronically controlled digital cassette system with 100 K byte on line capacity.
- 20 column wide alphanumeric display.
- 20 column alphanumeric printer (optional).
- 5.5 K byte PROM operating system with mnemonic translator, tape commands, memory manipulation features, breakpoints, single stepping of program segments, traces, etc.
- 1 K bytes of user programmable memory standard, optional expansion to 4 K, 8 K or 32 K.

This is a completely self-contained microcomputer system which could be equally well used as a personal computer, an educational tool oriented to assembly level programming, or custom applications interfaced through its I/O expansion connector (to the right of the processor card seen in the photograph). The DE68 price, completely ready to go as seen in the photograph, is $3500 (including the printer peripheral option) with delivery 60 days after receipt of order.

Star Trek in BASIC?

Atlantis Consultants, POB 8493, Salt Lake City UT 84108, has come up with two Star Trek programs, written in BASIC which are available now at $12.50 for the set. Included in the literature accompanying the programs, according to a letter from Earl Smith of Atlantis, are memory requirements, operational instructions, and tips and patches to help tailor the programs to any size system. These programs are accompanied by a one year warranty against programming and typographical errors.

Printed Circuit Board Hackers Take Note

Two new etched circuit board kits from Vector Electronic Co, 12460 Gladstone Av, Sylmar CA 91342, facilitate rapid production of quality circuit boards without expensive and time consuming processing with cameras and darkrooms. The kits, model numbers 32X-1 and 32XA-1, contain positive resist coated circuit boards, bare copper clad boards, and all materials necessary for fabricating circuit boards by the direct art/final etch process, and also by the positive photo resist process.

For direct processing, circuit patterns are applied directly on bare copper laminated circuit boards, using the acid resistant rub transfer artwork sheets and other art materials contained in the kits. The sheets have patterns for 40, 24 and 16 pin dual in line packages, flat packs, lines in 5 widths, pads in 7 diameters, edge contacts in 2 sizes, alphanumeric and numeric markings, and many miscellaneous coupling pad configurations.

The rub transfer patterns also may be used for making one to one size custom positives on the clear Mylar film supplied. This is then used to photo pattern the copper clad laminated boards coated with photosensitive etch resist. Vector's positive photo resist eliminates the need for photographic conversion of master artwork to negatives. The positive film is placed on the board, and exposed to a full or partial ultraviolet light source.

Exposure time requires approximately four minutes with either a GE "sun lamp," a commercial exposure lamp, or direct sunlight. A six ounce bottle of developer in solution accelerates about 600 square inches of sensitized surface.

The exposed and developed boards are etched in the ferric chloride solution and chemical tray supplied. The simple developing and etching process takes about 20 minutes. Following washing, the board is ready for use.

Vector etched circuit kits are useful for both engineering and experimental circuit board fabrication. Existing full scale artwork may be copied directly with the supplied tracing and artwork materials.

The Vector 32XA-1 kit will make seven printed circuit boards, and is priced at $28. The 32X-1 sample kit makes two boards, and is priced at $11.50.

Need a Fast Microcontroller?

Signetics Corp, 811 E Arques Av, Sunnyvale CA, has introduced a new high speed microprocessor component called the 8X300, which is "optimized for control operations." This is a Schottky bipolar processor with a simple two operand instruction set and a single instruction execution time of about 250 ns (operating on 8 bit data). The processor is available from stock at distributors for a quantity of 100 price of $86.75. No single quantity price was quoted, but based on comparable pricing strategies in the marketplace, we would expect the single unit price to a hacker to be below $250. What can a savvy BYTE reader do with a chip like this?

Well, look at the vector graphics problem, and consider design of an ROM programmed vector graphics processor. This machine is fast enough to do both the timing operations of a vector graphics generator, and the storage housekeeping for refresh. Build a custom machine for the 256 by 256 vector graphics application, with an intelligent refresh command language and a communications discipline for talking (as a peripheral) to your main microprocessor.

Take a look at the vertical microprogramming problem: emulating the instruction set of a known "nice" processor with lots of software. The 8 bit data paths of this machine, plus the high speed and internal scratchpad facilities should allow microprogramming hackers a very flexible alternative to the bit slice approach. According to the press release, it is "possible for 8 bit parallel data to be rotated or masked, to undergo arithmetic or logical operations, and then to be shifted and merged into any set of from one to eight contiguous pixels at the destination — all within one 250 ns cycle." A glance
Attention, Commercial and Industrial Graphics Users

Here is a state of the art graphics product designed for OEM customers only, the model 619 Storage Display Monitor made by Tektronix Inc., Beaverton OR. OEM only means that Tektronix is not interested in selling to “unsophisticated” users in this case. But as an example of a high resolution vector graphics display, all us individual users will be waiting with mouths watering for the introduction of smaller scale but high resolution units for personal systems. Here is what the state of the art price of $7125 (single quantity OEM) gets a systems engineer with graphics in mind these days:

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- 8080 MPU (The one with growing software support)
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FOR SALE: Complete VIATRON System 21, including print robot, comm adaptor, also many small video terminal, Tom French, c/o Philips Data Systems, 3320 Holcomb Bridge Rd, Norcross GA 30092.

FOR SALE: Hewlett-Packard HP-185B oscilloscope with 187C dual trace plug in. Triggered sweep, 1C-100 Mhz sampling, internal DC level, 50 Mhz sine wave, pulse calibration signals. One knob cracked but scope works good. $300. Mike Tenner, Rt 2, Rogers Rd, Fletcher NC 28732. (704) 684-2112.

WANTED: I am looking for information on a FREIDEN "6510 Compuprint." (1) Pin outs on the aux output plugs of unit (2). Necessary data to interface this unit with a 8080 system.

WANTED: New or used LA36 DEWriter II. I have written several programs in Altair BASIC. For information send $0.25 to Timothy G Roscoe, 153 Lodge 9, RFD 1, Box 52, Charlottesville VA 22901.

WANTED: Need schematics and manuals for DURA MACH 10, also tech data for ITIL System 3016SQD. SPARES (or small video terminal. Tom French, c/o (704) 684-2112.

FOR SALE: IBM 2315 disk cartridge (S/N 227211 12725 W 55 Terrace, Shawnee KS 66216.

FOR SALE: MITS B8-4MDC 4 K dynamic memory card. Fully assembled and tested by MITS $190; B8-4MDP parallel port with cable and connectors, assembled and tested $60. Complete set of Mark-8 boards with one extra memory board all brand new plus highly regulated Precision Systems power supply +5 V, B, A, and 12 V, 20 A, adjustable to -9 V, includes Radio Electronics Mark-8 brochure all for $110. Steve Calders, 965 E State St, Ithaca NY 14850. (607) 273-9234.

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FOR SALE: I am a supply of new INTEL and TI 8080 microprocessor chips for $25 each. These can be used to update your Altair computer, to control intelligent peripherals, or for experimental circuits. Sockets and specs are available if requested. G Lorenz, Box 710 LU, Lockport IL 60441. (181) 838-4930.

WANTED: Low cost new or used terminal and/or acoustic coupler for private use. Write Bob LaFkin, Lodger 9, RFD 1, Box 52, Charlottesville VA 22901.

FOR SALE: Zilog Z-80 third generation microprocessor chip. $95 each including shipping and handling. We are a club and will purchase these chips from the manufacturer at quantity discount prices. We need a minimum of 25 orders. For a description of the Z-80 see the August 1976 BYTE page 32. Shipment via Kristoffer Kales, 166 Marshland Rd, Apalachin NY 13732. (607) 625-2972. Sorry, no CODs, no credit cards.


FOR SALE: Limited supply of core memories from major computer manufacturer with spec sheets. 1K, 2K, 4K, 8K, 16K, 32K. $35: spec sheets. $0.75. Include shipping, excess refunded. Jim Kuiper, 542 Linden Ln, Ann Arbor MI 48103.


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SWAP OR SELL: One (1) tape punch machine with keyboard, 75 cps punch and Burrough display. $400. Four (4) 75 cps punch mechanisms and card drivers. $75 each. Three (3) high performance stepper motor systems (2 motors and power supply and control logic). $300 each. Honeywell 3C cards - three (3) ICs (FC320 and BC320); one (1) D8-1; nine (9) D8-2. Call Mr. Spitzak, 113 Everett St, Concord MA 01742.

FOR SALE: I am an HP-65 calculator to sell before I buy a computer, since having both would take too large a byte out of my savings. $700 buys it, Joseph R Danek, 3945 E Birchwood Av, Cudahy Wi 53110. Call (414) 769-7498 between 9 and 12 AM CST.

FOR SALE: Issues 1-12 of BYTE, good condition. Best offer above cost of magazine. Robert Campbell, 4324 Walker St NE, Cedar Rapids IA 52402. (139) 393-4191.

FOR SALE: Altair 8080 computer, fully assembled and tested, with 1 K static RAM, $500 plus shipping and handling. R A Stook, Cherry Dr, 11581. (516) 791-7451.

FOR SALE: PREMITEK core stack, model 999-1510-00-16 K words by 24 bits, no other data. Will include 34 type SN75728 sense amps. Best Offer over $200. Request contact: Steve Marum, 116 Western Hills Dr, Apt 136-J, Howe, TX 75059. (312) 532-5292.

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FOR SALE: High speed paper tape punch, Tele­type Corp (BRP6) with maintenance manuals and parts manual. Eight channels at 110 characters per second. Very good working condition. Best offer. Ronald Howland, 23 Sunner St, Milford MA 01757.

AVAILABLE: Copies 1-9 of BYTE (two copies of issue 2). Any offer will be considered but would prefer to sell all in one transaction. Contact: John R Kaser, 750 Peabody Ave Corvallis OR 97330. (503) 745-5702.

FOR SALE: 8080 based operating system featuring 11 human-engineered commands, allows full control of loading/examining memory, octal or hex dump, execute control of cassette tape storage. Included are 47 pages of source code, operating instructions, and schematics for 256-byte ordinate stack, serial-parallel interface, PROM interface. Condition .75 postpaid. If 15 orders are not received within 30 days from publication date of this ad, your check will be returned unopened. William E Severance Jr, Center Lovell ME 04016. (207) 925-2771.
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For more information circle A 104
I first became interested in microprocessors about a year ago. After much thought, I decided to investigate this rapidly growing field. I did not have any particular goal in mind but I did want to learn how they work and what they can do. Therefore, I decided not to buy a kit but to build my own from scratch. I happened to select the Motorola processor for a number of reasons which I won’t consider here. After a few weeks, I had a small system up and running. I even managed to interface an old "Tele-Term" that I borrowed from the Mayo Clinic where I work. Now (I thought) I had the cat by the tail (or the byte by the bit?).

It wasn’t long until I became impatient with the slowness of the Tele-Term, its loud clacking, and the reams of paper I was going through. What did I need? A video terminal, of course. There are a number of good kits on the market place. My impression was that they are either too expensive for my homebrew budget or they are Altair compatible. Now I needed Altair compatibility for my homebrew system like a write only memory. It would not have been a trivial task to interface any of the affordable video modules designed for the Altair to my homebuilt 6800 system. What could I do?

The answer was in the June 1976 issue of BYTE. Mr. Gantt’s article “Build a Television Display” [page 16] provided the basic information I needed on television interfacing. I changed the circuit around a bit, added a few goodies, incorporated some memory, and wrote a few lines of software. I am now using a video terminal that you would like. The following paragraphs should outline everything you need to know to complete one of your own.

Design Specifications

For my purposes a video terminal had to have a number of features I deemed to be desirable. First, I wanted immediate access to any character on the screen without having to mess around moving little white boxes. This feature allows me, for example, to keep a real time clock display in the upper right hand corner of the screen. This video terminal uses a simple minded direct memory access technique enabling a complete screen update in the twinkling of an eye. I chose a screen configuration of 16 lines by 32 characters per line. This limited amount of data didn’t really concern me since I would also be using scrolling.
Figure 2: Detail Schematic of the Video Generation Circuitry. This section of the design includes all timing logic and character generation logic. See table 1 for a complete parts list for figures 2 and 3, and see table 2 for the power wiring list.
Figure 3: Detail schematic of the system interface and memory for this video terminal design. In this diagram, the processor interface is at the top and left edge, and the video generator interface to figure 2 is at the right of the drawing.
allows the display of any 16 consecutive lines of the 32 lines kept in memory. To be fancy, I thought it desirable to have both white on black characters and the reverse (black on white) for highlighting. The terminal should use the standard power supplies I had available in my system (+5, +15, -15 V). Since I didn’t want to fool around modifying my television I included an RF modulator to feed the signal to the TV antenna inputs. My entire system was built on Vector #3677 and 3682 DIP plugboards. Therefore, this video terminal should also fit on the same type of board.

Finally, and most important, it had to be compatible with MY system. I should probably add that this terminal can of course be adapted for any computer system. It is a lot easier to interface Motorola systems to Intel systems than vice versa.

Functional Implementation

Figure 1 shows the relationship between various modules comprising this video terminal. The system incorporates a 1 K X 8 programmable memory to refresh the screen. The contents of the first 512 bytes is constantly being accessed by the video display generator. The video output is routed through coax to an RF modulator, adjusted, in my case, to channel 5. This is coupled to a nine inch (22.86 cm) GE black and white portable TV through a six foot length of coax and an impedance matching transformer. The interface section of the terminal is quite simple. Its sole purpose is to allow the processor to access the video memory whenever it desires. I felt that an occasional high priority interruption to the display was preferable to slowing down the processor. After the system was built, I discovered that no interference could be seen on the terminal when the processor was updating the display.

This display interface was built on a standard 4½" by 9½" (11.4 cm by 24.1 cm) Vector #3677 plugboard which I highly recommend. The board has two power buses etched on the reverse side. I have never experienced any problems with the power distribution while using these boards. The board was wire wrapped with all integrated circuits in sockets. Isolated discrete components were mounted with wire wrapable terminals. Analog subsystems were mounted on dual in line header plugs which, in turn, were mounted in wire wrapped integrated circuit packages.

Listing 1: A Memory Test Program for the 6800. This program tests the user memory of the television interface. If an error is found, the program stores the parameters of the erroneous location in locations VALUE (the test pattern to be stored), RSLT (the garbled test pattern read from the bad location) and ADDR (the address of the bad location). The limits of the test are arbitrary, being set by the constants at STRTADR and ENADAR. An error condition is concluded by entry into an endless loop of one instruction in length, thus locking up the machine until reset by the programmer making the test.

<table>
<thead>
<tr>
<th>Addr</th>
<th>Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000</td>
<td>DE 22</td>
<td>MTST</td>
<td>LDX</td>
<td>STRTADR</td>
<td>X := STRTADR [define starting address];</td>
</tr>
<tr>
<td>0002</td>
<td>86 00</td>
<td>LOOP1</td>
<td>LDAA</td>
<td>#0</td>
<td>A := 0 [define first test pattern];</td>
</tr>
<tr>
<td>0004</td>
<td>A7 00</td>
<td>LOOP2</td>
<td>STA</td>
<td>0,X</td>
<td>@X = A [write test pattern];</td>
</tr>
<tr>
<td>0006</td>
<td>01 NOP</td>
<td>LOOP2</td>
<td>NOP</td>
<td></td>
<td>Let the memory circuits settle</td>
</tr>
<tr>
<td>0007</td>
<td>01 NOP</td>
<td>LOOP2</td>
<td>NOP</td>
<td></td>
<td>down a bit between accesses;</td>
</tr>
<tr>
<td>0008</td>
<td>E6 00</td>
<td>LOOP2</td>
<td>LDA</td>
<td>0,X</td>
<td>B := @X [read test pattern back];</td>
</tr>
<tr>
<td>000A</td>
<td>11</td>
<td>CBA</td>
<td>BNE</td>
<td>ERROR</td>
<td>Does test pattern read match original?</td>
</tr>
<tr>
<td>000B</td>
<td>26 09</td>
<td>BNE</td>
<td>INCA</td>
<td></td>
<td>If not then quit with error;</td>
</tr>
<tr>
<td>000D</td>
<td>4C</td>
<td>INCA</td>
<td>INCA</td>
<td></td>
<td>A := A + 1 [define next test pattern];</td>
</tr>
<tr>
<td>000E</td>
<td>4D</td>
<td>INCA</td>
<td>INCA</td>
<td></td>
<td>Is A = 0? [have all patterns been used]?;</td>
</tr>
<tr>
<td>000F</td>
<td>26 F3</td>
<td>BNE</td>
<td>INX</td>
<td>LOOP2</td>
<td>If not then continue cycle at current address;</td>
</tr>
<tr>
<td>0011</td>
<td>08</td>
<td>INX</td>
<td>INX</td>
<td></td>
<td>X := X + 1 [define next test address];</td>
</tr>
<tr>
<td>0012</td>
<td>9C 24</td>
<td>CFX</td>
<td>ENADR</td>
<td></td>
<td>Is X = last address?</td>
</tr>
<tr>
<td>0014</td>
<td>26 EC</td>
<td>CFX</td>
<td>ENADR</td>
<td></td>
<td>If not then restart test loops;</td>
</tr>
<tr>
<td>0016</td>
<td>97 1E</td>
<td>ERROR</td>
<td>STAA</td>
<td>VALUE</td>
<td>VALUE := A [indicate source value];</td>
</tr>
<tr>
<td>0018</td>
<td>D7 1F</td>
<td>ERROR</td>
<td>STAB</td>
<td>RSLT</td>
<td>RSLT := B [indicate resulting value];</td>
</tr>
<tr>
<td>001A</td>
<td>DF 20</td>
<td>STX</td>
<td>ADDR</td>
<td></td>
<td>ADDR := X [indicate address of problem];</td>
</tr>
<tr>
<td>001C</td>
<td>20 FE</td>
<td>OOPSLOOP</td>
<td>BRA</td>
<td>OOPSLOOP</td>
<td>Hang up in endless loop until restart;</td>
</tr>
</tbody>
</table>

Data Required By MTST: These locations are at absolute addresses in the first page of memory, and are referenced by direct addressing. If the program is relocated, the variables should remain in page zero.

<table>
<thead>
<tr>
<th>Addr</th>
<th>Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>001E</td>
<td>00</td>
<td>VALUE</td>
<td>FCB</td>
<td>0</td>
<td>Error value;</td>
</tr>
<tr>
<td>001F</td>
<td>00</td>
<td>RSLT</td>
<td>FCB</td>
<td>0</td>
<td>Error result;</td>
</tr>
<tr>
<td>0020</td>
<td>00 00</td>
<td>ADDR</td>
<td>FDB</td>
<td>0</td>
<td>Error address;</td>
</tr>
<tr>
<td>0022</td>
<td>00 00</td>
<td>STRTADR</td>
<td>FDB</td>
<td>0</td>
<td>Starting address of test;</td>
</tr>
<tr>
<td>0024</td>
<td>00 00</td>
<td>ENADAR</td>
<td>FDB</td>
<td>0</td>
<td>Ending address of test;</td>
</tr>
</tbody>
</table>
Table 1: Video Terminal Parts List. This listing summarizes the parts identifications, sources of supply and approximate cost of this design as built by the author. The costs for most parts are typical. The only part for which it may be difficult to find alternate sources of supply is the Pixe-Verter, a brand name product. The names and addresses of the vendors used by the author are listed at the end of the table.

<table>
<thead>
<tr>
<th>Quan</th>
<th>Type</th>
<th>IC number</th>
<th>Source</th>
<th>Approximate Cost</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td></td>
<td>Integrated Circuits, TTL</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>7400</td>
<td>IC53</td>
<td>James</td>
<td>.18</td>
</tr>
<tr>
<td>2</td>
<td>7404</td>
<td>IC32, IC64</td>
<td>James</td>
<td>.32</td>
</tr>
<tr>
<td>2</td>
<td>7410</td>
<td>IC33, IC42</td>
<td>James</td>
<td>.40</td>
</tr>
<tr>
<td>6</td>
<td>7485</td>
<td>IC11, IC23</td>
<td>James</td>
<td>.80</td>
</tr>
<tr>
<td>2</td>
<td>7486</td>
<td>IC76, IC77</td>
<td>James</td>
<td>.78</td>
</tr>
<tr>
<td>2</td>
<td>7490</td>
<td>IC31, IC44</td>
<td>James</td>
<td>1.38</td>
</tr>
<tr>
<td>1</td>
<td>7492</td>
<td>IC52</td>
<td>James</td>
<td>.82</td>
</tr>
<tr>
<td>2</td>
<td>74123</td>
<td>IC43, IC45</td>
<td>James</td>
<td>2.10</td>
</tr>
<tr>
<td>3</td>
<td>74157</td>
<td>IC14, IC15, IC16</td>
<td>James</td>
<td>3.90</td>
</tr>
<tr>
<td>1</td>
<td>74165</td>
<td>IC65</td>
<td>James</td>
<td>1.10</td>
</tr>
<tr>
<td>1</td>
<td>74182</td>
<td>IC46</td>
<td>James</td>
<td>1.50</td>
</tr>
<tr>
<td>3</td>
<td>74193</td>
<td>IC47, IC54, IC55</td>
<td>James</td>
<td>4.30</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Integrated Circuits, MOS</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>8T978</td>
<td>IC12, IC13, IC17</td>
<td>SD</td>
<td>4.47</td>
</tr>
<tr>
<td>8</td>
<td>21L02-1</td>
<td>IC24, IC25, IC26, IC27, IC34, IC35, IC36, IC37</td>
<td>SD</td>
<td>12.95</td>
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<tr>
<td>1</td>
<td>2513N</td>
<td>IC57</td>
<td>James</td>
<td>11.00</td>
</tr>
<tr>
<td>1</td>
<td>MMS320</td>
<td>IC51</td>
<td>Nexus</td>
<td>4.95</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Hardware</td>
<td></td>
<td></td>
</tr>
<tr>
<td>27</td>
<td>16 pin Wire Wrap Sockets</td>
<td>James</td>
<td>11.34</td>
<td></td>
</tr>
<tr>
<td>9</td>
<td>14 pin Wire Wrap Sockets</td>
<td>James</td>
<td>3.51</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>24 pin Wire Wrap Socket</td>
<td>James</td>
<td>1.05</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>14 pin DIP Plug</td>
<td>James</td>
<td>.64</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>16 pin DIP Plug</td>
<td>James</td>
<td>.70</td>
<td></td>
</tr>
<tr>
<td>21</td>
<td>Wire Wrap Terminals, type T-49</td>
<td>James</td>
<td>1.25</td>
<td></td>
</tr>
<tr>
<td>300*</td>
<td>#30 ga Wire Wrap Wire (9.95/1000')</td>
<td>Ace</td>
<td>3.50</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>Capacitors</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>22 pF</td>
<td></td>
<td>James</td>
<td>.05</td>
</tr>
<tr>
<td>2</td>
<td>47 pF</td>
<td></td>
<td>James</td>
<td>.10</td>
</tr>
<tr>
<td>1</td>
<td>100 pF</td>
<td></td>
<td>James</td>
<td>.05</td>
</tr>
<tr>
<td>1</td>
<td>.0047 mF, Mylar</td>
<td>James</td>
<td>.12</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>.01 mF, Mylar</td>
<td>James</td>
<td>.12</td>
<td></td>
</tr>
<tr>
<td>31</td>
<td>.1 mF, ceramic bypass (3.75/50)</td>
<td>James</td>
<td>2.33</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>1 mF, Tant</td>
<td>James</td>
<td>.28</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>100 mF, 16 volt, electrolytic</td>
<td>James</td>
<td>.38</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>Resistors</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>47 ohm, 1/4 watt, 5% carbon</td>
<td>James</td>
<td>.05</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>100 ohm</td>
<td></td>
<td>James</td>
<td>.05</td>
</tr>
<tr>
<td>1</td>
<td>150 ohm</td>
<td></td>
<td>James</td>
<td>.05</td>
</tr>
<tr>
<td>2</td>
<td>330 ohm</td>
<td></td>
<td>James</td>
<td>.10</td>
</tr>
<tr>
<td>1</td>
<td>600 ohm</td>
<td></td>
<td>James</td>
<td>.06</td>
</tr>
<tr>
<td>1</td>
<td>1 k</td>
<td></td>
<td>James</td>
<td>.15</td>
</tr>
<tr>
<td>1</td>
<td>18 k (particular value unit dependent)</td>
<td>James</td>
<td>.05</td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>20 k, 10 Turn, Trimpots #43P203</td>
<td>James</td>
<td>4.05</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>Semiconductors</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>1N4742, 12 V Zener Diode</td>
<td>James</td>
<td>.29</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>1N751A, 5 V Zener Diode</td>
<td>James</td>
<td>.25</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>2N3904, NPN GP Transistor</td>
<td>James</td>
<td>.25</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>Miscellaneous</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>10 MHz Crystal # CY12A</td>
<td>James</td>
<td>4.95</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Vector #3577 Plugboard</td>
<td>B-A</td>
<td>10.38</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Vector R644 Plugboard Receptacle</td>
<td>B-A</td>
<td>4.32</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>Pixe-Verter, Model #PXV-2A</td>
<td>ATV Rsh</td>
<td>8.50</td>
<td></td>
</tr>
<tr>
<td>10*</td>
<td>RG 59/U Coax</td>
<td>Radio Shk</td>
<td>.80</td>
<td></td>
</tr>
<tr>
<td>1</td>
<td>72 ohm to 300 ohm Transformer</td>
<td>Radio Shk</td>
<td>2.85</td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>RF Connectors</td>
<td>Radio Shk</td>
<td>.89</td>
<td></td>
</tr>
</tbody>
</table>

Approximate Total Cost $115.28

Hardware Configuration

Figure 2 is the schematic of the video processing subsystem. This circuitry is substantially the same as the circuit designed in the article by Mr Gantt. Several component values have been altered from his original design. 74123s were used to reduce the package count with excellent results. The dot counter clock is not derived from the crystal frequency. Instead, a one shot multivibrator is used to give variable character width. This allows one to adjust the line width to the sweep time of the individual TV being used. This frequency can be increased to allow 64 characters per line if desired. Although they are clear, I prefer not to use a magnifying glass to read the data on the nine inch TV screen. Exclusive OR gates were inserted between the 2513 character generator and the 74165 shift register to allow for reverse characters. Note that a cursor is nothing more than a reverse space. Only six data lines are required to specify a particular 6 bit ASCII subset character code. This allows the two remaining data lines to contain control information. If bit 7 is off (the most significant bit), the exclusive OR gates act as inverters to produce a reverse character. If bit 7 is on, they act as buffers, passing logically true data for a standard character. Bit 6 is currently unused. This could be used to enable a blinking gate to make individual characters flash on and off. Or it could be used to disable the character generator and enable a handblown PROM array which would allow a certain degree of graphic text capability. The video combiner

Vendors' Addresses

SD Sales; POB 28810; Dallas TX 75228.
Burstein-Applebee; 3199 Mercer St; Kansas City MO 64111.
Nexus Trading; Box 3357; San Leandro CA 94578.
James Electronics; 1021 Howard St; San Carlos CA 94070.
ATV Research; 13th and Broadway; Dakota City NE 68731.
ACE Electronic Parts; 5400 Mitchelldale B-8; Houston TX 77092.
is different from that shown in Mr Gantt's article. The 2N3904 transistor is controlled by the addition of the two inputs (composite sync and video). It provides the proper interface to the RF modulator. Note that nearly every integrated circuit is bypassed with a 0.1 mF ceramic capacitor. This insures a clean power supply line with little or no switching transient noise. I felt this to be especially important in view of the different nonrelated frequencies in the terminal. Notice the small circled numbers that are alongside of the discrete components in the crystal time base and video combiner systems. These refer to the pin locations on an IC plug which holds the components.

Anyone familiar with interface boards will recognize the simplicity of the one shown in figure 3. The address lines on the left side of the schematic are from the processor's buffered address bus. The data lines at the top are to the bidirectional 8 bit data bus. The 10 address lines and eight data lines to the right are interconnections to the display terminal controller. The high order address lines from the processor along with the 6800's VMA (Valid Memory Address) signal are decoded by the four bit magnitude comparators IC11 and IC23. The memory address is set by the levels on the B side inputs of these 7485s. The schematic shows a setting for a memory address between 0000 to OFFF, IC23 pin 6 toggles to a positive level whenever the high order address from the processor bus matches the preset address. Within nanoseconds the data selectors (74157s, IC14, IC15, IC16) switch control of the memory address lines from the display generator to the processor bus. Half a microsecond later, with the address firmly established on the memory chips, the phase 2 clock goes high enabling the write line (if writing data) or the output buffers (if reading data). While the memory reference is being made by the processor, the terminal hardware may attempt to load a character. The character it gets is not necessarily the one at the address it wants but the character that the processor is addressing. This would seem to cause an improper character to be displayed. However, since this contention occurs so infrequently and the refresh is so rapid, no visible interference is seen on the TV screen in a typical situation. The programmable memories are of the 21L02-1 variety. Except for the data in and data out connections, the memory integrated circuits are all wired in parallel. They are permanently enabled by tying their chip select lines to ground. This hardware is about as simple as can be expected. It should not present any problems to anyone with any experience in assembly of electronics. Photos 1 to 17 show waveforms at selected test points identified on the schematics. These photos illustrate typical waveforms of my completed display board, taken from a Tektronix 455 oscilloscope.

**Software Support**

The primary disadvantage of this system as a terminal is the lack of a local mode like a hard copy printer or traditional display terminal. All data to be written on the screen must pass through the processor. This is not a serious disadvantage unless one desires a stand alone toy TV typewriter. You may choose to develop your own software (you have to if your processor is not a 6800!), or, if you are running a 6800 system, you might like to give mine a try.

This software is a collection of completely relocatable subroutines (that is, the following package can reside anywhere in memory without changing any subroutine addresses). There are five entry points of interest. They allow your programs to:

**Table 2: Power Wiring List.** This table lists each integrated circuit of this project and its power supply wiring pins. The rest of the wiring is done according to the schematics of figures 2 and 3.

<table>
<thead>
<tr>
<th>No</th>
<th>Device</th>
<th>+5 V</th>
<th>-5 V</th>
<th>-12 V</th>
<th>GND</th>
</tr>
</thead>
<tbody>
<tr>
<td>IC11</td>
<td>7485</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC12</td>
<td>8T97</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC13</td>
<td>8T97</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC14</td>
<td>74157</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC15</td>
<td>74157</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC16</td>
<td>74157</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC17</td>
<td>8T97</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC21</td>
<td>A1</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC23</td>
<td>7485</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC24</td>
<td>21L02-1</td>
<td>10</td>
<td>9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC25</td>
<td>21L02-1</td>
<td>10</td>
<td>9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC26</td>
<td>21L02-1</td>
<td>10</td>
<td>9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC27</td>
<td>21L02-1</td>
<td>10</td>
<td>9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC31</td>
<td>7490</td>
<td>5</td>
<td>10</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC32</td>
<td>7404</td>
<td>14</td>
<td>7</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC33</td>
<td>7410</td>
<td>14</td>
<td>7</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC34</td>
<td>21L02-1</td>
<td>10</td>
<td>9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC35</td>
<td>21L02-1</td>
<td>10</td>
<td>9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC36</td>
<td>21L02-1</td>
<td>10</td>
<td>9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC37</td>
<td>21L02-1</td>
<td>10</td>
<td>9</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC42</td>
<td>7410</td>
<td>14</td>
<td>7</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC43</td>
<td>74123</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC44</td>
<td>7490</td>
<td>5</td>
<td>10</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC45</td>
<td>74123</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC46</td>
<td>74182</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC47</td>
<td>74193</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC51</td>
<td>MM8320</td>
<td>8</td>
<td>1</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC52</td>
<td>7492</td>
<td>5</td>
<td>10</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC53</td>
<td>7400</td>
<td>14</td>
<td>7</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC54</td>
<td>74193</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC55</td>
<td>74193</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC57</td>
<td>2513</td>
<td>24</td>
<td>12</td>
<td>10</td>
<td></td>
</tr>
<tr>
<td>IC61</td>
<td>A2</td>
<td>11 &amp; 13</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC64</td>
<td>7404</td>
<td>14</td>
<td>7</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC65</td>
<td>74165</td>
<td>16</td>
<td>8</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC76</td>
<td>7486</td>
<td>14</td>
<td>7</td>
<td></td>
<td></td>
</tr>
<tr>
<td>IC77</td>
<td>7486</td>
<td>14</td>
<td>7</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

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Waveform Photographs

The oscilloscope photos, 1 to 17, are included for trouble shooting purposes. These were taken on a Tektronix 455 oscilloscope using a 10X probe. Unless otherwise noted, the vertical sensitivity is 1 volt per division. The horizontal sweep speed and test point location are shown in the caption of each photograph. The ground reference line is one division below the center line in each photograph.

Photo 1: Test point 1, pin 1 of IC31, 50 ns per division.

Photo 2: Test point 2, pin 1 of IC43, 200 ns per division.

Photo 3: Test point 3, pin 4 of IC43, 200 ns per division.

Photo 4: Test point 4, pin 13 of IC45, 20 μs per division.

Photo 5: Test point 5, pin 12 of IC44, 5 ms per division.

Photo 6: Test point 6, pin 1 of IC44, 2 ms per division.

Photo 7: Test point 7, pin 5 of IC43, 2 ms per division.

Photo 8: Test point 8, pin 12 of IC45, 50 ns per division.

Photo 9: Test point 9, pin 6 of IC42, 100 ns per division.

Photo 10: Test point 10, pin 3 of IC53, 10 μs per division.

Photo 11: Test point 11, pin 2 of IC55, 200 μs per division.

Photo 12: Test point 12, pin 4 of IC64, 200 μs per division.

Photo 13: Test point 13, pin 12 of IC42, 500 μs per division.

Photo 14: Test point 14, video output, 0.5 V per division vertically, 2 ms per division horizontally.

Photo 15: Test point 15, video output, 0.5 V per division vertically, 100 μs per division horizontally.

Photo 16: Test point 16, pin 6 of IC23, 1 μs per division.

Photo 17: Test point 17, pin 6 of IC33, 500 ns per division.
1. Display a new line of ASCII text.
2. Scroll all lines up by one.
3. Erase one character line.
4. Add one new character to the display.
5. Erase the entire screen.

The preambles for each subroutine should adequately explain the calling sequence and conventions used. These subroutines assume that six words are available in the first page (256) of memory (hexadecimal address 0 to FF). These words are used to take advantage of Motorola's direct addressing feature. To display a character in a preset location on the screen, initialize the words CHAR and LINE to the desired location, load the 6 bit ASCII character into the A accumulator and branch to the VCHAR subroutine.

The complete relocatable software is included as listing 2 with this article. A symbolic example is given here to show the use of these routines. Suppose that you desire to erase the screen, display a title, a prompting message, and place a cursor at the next character location. This can be accomplished by the following code:

```
START
JMP ESCRN
LDX #TITLE
JMP VLINE
LDX #PROMPT
JMP VLINE
LDA #BAD
JMP VCHAR

TITLE
FCC 'GENIE OPERATING SYSTEM'
PROMPT
FCC 'WHAT IS YOUR DESIRE, MASTER?'

Or if you really have to have a routine which will allow you to type data on your keyboard and look at it on the screen:

LOCAL
LOCAL
LOOP
JMP ESCRN
LDA #804
BNE LOOP
JMP ESCRN
LDX #TITLE
JMP VLINE
JMP VCHAR

Note that scrolling is done automatically for you after you write the 32nd character on the 16th line.

Construction

Before you can begin building this terminal, you first must obtain the necessary components. Refer to the component list in table 1. I have listed the vendors from which
Photo 19: Video Terminal Board, Wiring Side. This photograph shows the wire wrapped construction of the circuit's prototype. All integrated circuit locations were labelled with masking tape containing device location and device type. All integrated circuit power connections were soldered to the etched power supply buses which are part of the Vector plugboard used for the circuit. The orientation of pin 1 is uniformly the upper left corner of the integrated circuit, as documented by the typical pinout map shown pasted to the upper right side of the board.

I purchased the parts. I selected these people because I knew I would get quality components at reasonable prices in a short time. The prices listed are included as a guide. Check the advertisements in this issue to see if they have changed.

The first step in building this (or any) board is to determine exactly where the various components will be located. See photo 18, photo 19 and figure 4 for the layout I used. Then install all of your bypass capacitors. This is easy to do at this stage. Solder them directly to the etched lands on the reverse of the Vector board between the known locations of the wire wrap sockets. Next (and this is a trick that will really reduce the wire wrap errors) cut masking tape into sections a little smaller than the size of the integrated circuit top. Write on the masking tape the integrated circuit number and the TTL suffix. For example,

Photo 20: A Detail of the Computer System. This 6800 microcomputer currently consists of four cards: an IO card, a processor card, a 4K byte programmable memory card, and the video terminal card described in this article. One spare location at the left is awaiting a 16K dynamic programmable memory card which is under development. The ribbon connectors in the lower right hand corner are used to interface a control panel. Each board is supplied from a separate 5V regulator which is mounted on the chassis for superior heat sinking capability.
“IC45-123” identifies the fifth integrated circuit in the fourth column as a 74123. Pin 1 is always in the upper left hand corner looking from the wrap side of the board. Place the label on the wrap side of the board where the socket will go. Next, put a dab of cement on the bottom of the integrated circuit socket and insert it on the board. (I used “DUCO” cement. Epoxy or hot melt glue can be used, but are nearly impossible to remove once set.) Remember that 16 pin sockets are a little longer than the 14 pin variety and you’ll be OK. Refer to figure 4 for the configuration I used. After the glue has set, wire the power supply lines to the wire wrap sockets. To do this, wrap half a dozen turns around a power pin and solder the other end to the nearest power bus. Don’t “daisy chain” a bunch of circuits together with one attachment to the power bus. The 30 gauge wire can’t adequately handle the required switching current for more than a few chips. Insert the wire wrap terminals where the discrete components will be placed. Many of these can be soldered directly to the power planes. Otherwise, they have enough friction to prevent them from falling out before they are wrapped. It’s time for one more trick to reduce the number of wire wrap errors. Get a Xerox copy of the schematics (figures 2 and 3). [BYTE encourages this and gives full permission for such private use duplication.] Each time you complete a connection, use a felt tipped pen to draw over the line on the

Figure 4: Video Terminal Component Layout. This reduced scale drawing shows the relative position of the parts of the video terminal design as constructed by the author. See photo 18 for a pictorial version of this layout, and see photo 19 for the reverse side of the author’s card as wired for his system.

Listing 2: Complete Video Support Software for a Motorola 6800 Processor. This package consists of self relocating routines to perform display utility functions. Self relocation is accomplished by exclusively employing branch instructions (relative addressing) for program control within the package, and using the stack as a temporary where necessary. Control variables are assumed to be in low memory.

The following allocations are located in page 0 of memory, so that the video support software can take advantage of the Motorola 6800 direct addressing mode. Relocation of these variables should be confined to page 0, in which case the address constants used for the direct addressing references would be altered to reflect new locations. The main text of the subroutines themselves is completely position independent, which means relocation can be accomplished simply by loading the program code at a different point in memory address space and calculating new addresses for the “external references” summarized in a table at the end of this listing.

<table>
<thead>
<tr>
<th>Abs Addr</th>
<th>Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>0020 00</td>
<td>CHAR RMB</td>
<td></td>
<td></td>
<td></td>
<td>Character position, 0 (left) to 31 (right);</td>
</tr>
<tr>
<td>0021 00</td>
<td>LINE RMB</td>
<td></td>
<td></td>
<td></td>
<td>Line number, 0 (top) to 15 (bottom);</td>
</tr>
<tr>
<td>0022 00</td>
<td>CHPSN ROB</td>
<td></td>
<td></td>
<td></td>
<td>Memory address pointer to character;</td>
</tr>
<tr>
<td>0023 00</td>
<td>CHPSN EDI</td>
<td></td>
<td></td>
<td></td>
<td>Low order byte of memory address pointer;</td>
</tr>
<tr>
<td>0024 00</td>
<td>SAVEX ROB</td>
<td></td>
<td></td>
<td></td>
<td>Index register save area;</td>
</tr>
</tbody>
</table>

The following equate assigns a value to the address of the video display memory for the purposes of symbolic reference within this listing. The addresses of the displayed portion of memory in the prototype of this design are 0C00 to 0FFF in hexadecimal.

| VIDEO EDI | =50030 |

Listing 2 is continued on the next three pages . . .
VLINE — This subroutine displays a new line of text on the screen. On entry to VLINE, the index register X has the address of the start of the ASCII text string to be displayed. The string is terminated using an ASCII EOT character, hexadecimal $4D$, as the last character.

<table>
<thead>
<tr>
<th>Addr</th>
<th>Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000</td>
<td>VLINE</td>
<td>EQU</td>
<td>*</td>
<td></td>
<td>Entry point, line display routine;</td>
</tr>
<tr>
<td>0001</td>
<td></td>
<td>PSHA</td>
<td></td>
<td></td>
<td>Save A on stack;</td>
</tr>
<tr>
<td>0002</td>
<td>7E 00 20</td>
<td>CLRF</td>
<td>CHAR</td>
<td></td>
<td>CHAR := 0 (perform carriage return);</td>
</tr>
<tr>
<td>0004</td>
<td>7C 00 21</td>
<td>INC</td>
<td>LINE</td>
<td></td>
<td>LINE := LINE + 1 (perform line feed);</td>
</tr>
<tr>
<td>0007</td>
<td>A6 00</td>
<td>VLP</td>
<td>DX</td>
<td>A = 6X</td>
<td>Display character (possibly new character to A);</td>
</tr>
<tr>
<td>0009</td>
<td>81 04</td>
<td>CMPA</td>
<td>4</td>
<td></td>
<td>Is it end of text?</td>
</tr>
<tr>
<td>000B</td>
<td>27 05</td>
<td>BEQ</td>
<td>VLINE</td>
<td></td>
<td>If so then return to caller;</td>
</tr>
<tr>
<td>000D</td>
<td>8D 15</td>
<td>BSR</td>
<td>VCHAR</td>
<td></td>
<td>CALL VCHAR (display the character);</td>
</tr>
<tr>
<td>000F</td>
<td>08</td>
<td>INX</td>
<td></td>
<td>X := 1</td>
<td>(point to next character);</td>
</tr>
<tr>
<td>0010</td>
<td>20 F5</td>
<td>BRA</td>
<td>VLP</td>
<td></td>
<td>Reiterate until done;</td>
</tr>
<tr>
<td>0013</td>
<td>37</td>
<td>VLDNE</td>
<td>PULA</td>
<td></td>
<td>Restore A from stack;</td>
</tr>
<tr>
<td>0013</td>
<td></td>
<td>RTS</td>
<td></td>
<td></td>
<td>Return to caller;</td>
</tr>
</tbody>
</table>

ESCRN — This subroutine is used to erase the entire screen. It has no input parameters.

<table>
<thead>
<tr>
<th>Addr</th>
<th>Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>0014</td>
<td>ESCRN</td>
<td>EQU</td>
<td>*</td>
<td></td>
<td>Entry point, erase screen routine;</td>
</tr>
<tr>
<td>0015</td>
<td></td>
<td>PSHA</td>
<td></td>
<td></td>
<td>Save A on stack;</td>
</tr>
<tr>
<td>0016</td>
<td>86 0F</td>
<td>LDA A</td>
<td>#15</td>
<td>A := 15</td>
<td>(set number of lines to erase);</td>
</tr>
<tr>
<td>0019</td>
<td>4A</td>
<td>DECA</td>
<td></td>
<td></td>
<td>A := A - 1 (decrement line count in A);</td>
</tr>
<tr>
<td>002A</td>
<td></td>
<td>FC F8</td>
<td>BGE</td>
<td>ESQLP</td>
<td>If A &lt;= 0 then continue the loop;</td>
</tr>
<tr>
<td>002C</td>
<td></td>
<td>CMPA</td>
<td>#10</td>
<td></td>
<td>LINE := 0 (move cursor to top of screen);</td>
</tr>
<tr>
<td>002F</td>
<td>7F 00 21</td>
<td>CLRF</td>
<td>CHAR</td>
<td>CHAR := 0</td>
<td>(move cursor to top of screen);</td>
</tr>
<tr>
<td>0039</td>
<td></td>
<td>RTS</td>
<td></td>
<td></td>
<td>Return to caller;</td>
</tr>
<tr>
<td>003C</td>
<td>27 01</td>
<td>VLF</td>
<td>INC</td>
<td>LINE := LINE + 1</td>
<td>(perform line feed);</td>
</tr>
<tr>
<td>003E</td>
<td></td>
<td>RTS</td>
<td></td>
<td></td>
<td>Return to caller;</td>
</tr>
</tbody>
</table>

VCHAR — This subroutine displays one character on the screen. On entry, the A accumulator should contain the ASCII character code to be displayed. VCHAR updates the control variables LINE and CHAR which determine screen location; VCHAR ignores all ASCII control codes except a carriage return or line feed.

<table>
<thead>
<tr>
<th>Addr</th>
<th>Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>0024</td>
<td>VCHAR</td>
<td>EQU</td>
<td>*</td>
<td></td>
<td>Entry point of character display routine;</td>
</tr>
<tr>
<td>0026</td>
<td>81 00</td>
<td>CMFA</td>
<td>#00</td>
<td>CHAR := 0</td>
<td>Character (a carriage return)</td>
</tr>
<tr>
<td>0028</td>
<td></td>
<td>BEG</td>
<td>VCR</td>
<td></td>
<td>If so then go jump CHAR pointer;</td>
</tr>
<tr>
<td>002A</td>
<td></td>
<td>BEG</td>
<td>VLF</td>
<td></td>
<td>If so then go jump LINE pointers;</td>
</tr>
<tr>
<td>002C</td>
<td></td>
<td>CMPA</td>
<td>#10</td>
<td></td>
<td>Check for ASCII control character;</td>
</tr>
<tr>
<td>002E</td>
<td></td>
<td>BGE</td>
<td>VOK</td>
<td></td>
<td>BGE VOK</td>
</tr>
<tr>
<td>0030</td>
<td></td>
<td>LT A</td>
<td></td>
<td></td>
<td>Return with no action;</td>
</tr>
<tr>
<td>0033</td>
<td>7F 00 20</td>
<td>VCR</td>
<td>CLR</td>
<td>CHAR := 0</td>
<td>(perform carriage return);</td>
</tr>
<tr>
<td>0035</td>
<td></td>
<td>RTS</td>
<td></td>
<td></td>
<td>Return to caller;</td>
</tr>
<tr>
<td>0037</td>
<td>7C 00 21</td>
<td>VLF</td>
<td>INC</td>
<td>LINE := LINE + 1</td>
<td>(perform line feed);</td>
</tr>
<tr>
<td>0039</td>
<td></td>
<td>RTS</td>
<td></td>
<td></td>
<td>Return to caller;</td>
</tr>
</tbody>
</table>

copy. You are done when all of the lines are marked over. Remember to mark the power supply lines too. I should probably insist that you recheck all of your connections after you’re done… however, I don’t and I don’t expect that you will either. It is easier to verify your connections as you make them and fix the ones you missed during checkout.

Now that your board is wrapped it’s time to stuff all the circuits in and turn the power on, right? WRONG. Go slowly and test your work. You may end up saving some expensive circuits. First, measure your +5 V power supply. If it is not within 0.25 V of 5 V, find out why. Too low a voltage impedes performance. Too high and your chip life is reduced. Next, install the interface chips (IC11, IC12, IC13, IC14, IC15, IC16, IC17, IC23 and IC33). Put a scope on pin 1 of IC16 and verify a positive pulse each time you address this memory space. The address of the memory space is determined by the B side inputs to the 7485s. This test can be done by a front panel or a software loader. This select should be about 1.0 μs in duration if you are running with a 1 MHz clock. Verify the address inputs at the programmable memory socket locations to make sure the 74157s are switching correctly. Look at IC33 pin 3 and see a 500 ns negative pulse (normally high, goes low for about 500 ns, then high again) when you are writing to the programmable memory. Verify that there is no pulse when reading. Check for the reverse at IC33 pin 6. Expect a negative pulse when reading and just a high level when writing. Turn the power off and insert the eight 21L02-1 memory circuits. Each time a circuit is inserted, look to make sure all the pins are in the socket and not bent over. Power up again and run your memory test program. This verifies that your system can access this memory and that the integrated circuits are all good. An example of a simple memory test program called MTST is included in this article as listing 1.

When you are sure that the processor is interfaced to memory correctly, insert IC32, IC31, and IC43. Mount the DIP plug with the oscillator components in the IC21 socket. Look at IC31 pin 1 on your scope and check for a 10 MHz “square” wave. See photo 1 for an example. Photo 2 shows the 2 MHz wave at IC43 pin 1. If all is well so far, put your probe on IC43 pin 4. This should be pretty close to a 2 MHz square wave. Adjust the timing resistor, if necessary, to obtain a 50% duty cycle. This doesn’t have to be exact but the 5320 is happier with a square wave. Measure pin 1 of IC51 and verify a −12 V (±5%) DC voltage. With power off, insert this magical inte-
trigated circuit into its socket. This S320 generates all sorts of good signals and saves a lot of board space. With power on (and pin 1 still at a clean -12 V), scope pins 11, 12, 14, 15, and 16. They will be switching between +4.5 and -11 V. Don’t be alarmed by the negative output voltage. They will pop up to ground when a TTL load is hung on them. With power off again, insert IC45, IC46, IC47, IC64, IC44, and IC42. Adjust the Line Delay pot for a 20 μs positive pulse at IC55 pin 14. This adjusts the left hand margin on the TV display. It will be trimmed to a final value at a later time. Adjust the Top of Page pot for a 3 ms positive pulse at IC44 pin 14 (this will also be trimmed later). Verify pulses at IC57 pins 14, 15, and 16. Set the Character Width pot to midrange (about 6.25 MHz at IC32 pin 12). Refer to the waveform photographs if problems are encountered. Insert everything else except for the character generator (IC57). Check that the address lines are toggling and that data is being presented to the character generator on pins 17 through 22. IC65 pin 9 should be switching erratically. Verify the power supply connections to IC57. The +5, -5, and -12 V connections should be within 5% and should be clean, that is, without more than 100 mV of noise.

Turn the power off and remove the 2513 from its protective packing. This is the last device to be added to the board. It is also the most expensive circuit so don’t blow it. With power on, recheck the supplies and the outputs from this circuit.

Connect the video output from this terminal module to the video input of an RF modulator. I obtained excellent results using a Pixe-Verter. The RF output is transmitted by coax to a 72 to 300 ohm transformer. Disconnect the antenna from the back of your TV and attach the leads from this transformer. Tune to the channel you selected when building the Pixe-Verter with some sort of display on the TV screen. Then you can go to town using the display.

The results of my project are shown in photos 20 and 21.

Trouble Shooting

Fortunately, this version of a video terminal worked the first time it was tried. This means I don’t have any suggestions for locating failures based on experience. If you run into trouble, compare your waveforms

Listing 2, continued:

VSCROL — This subroutine moves all lines on the display up by one position. No input parameters are necessary.

<table>
<thead>
<tr>
<th>Rel</th>
<th>Addr</th>
<th>Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>009C</td>
<td>9</td>
<td>GCHAR</td>
<td>EQU</td>
<td>*</td>
<td>Entry point of scrolling subroutine;</td>
<td></td>
</tr>
<tr>
<td>009C</td>
<td>36</td>
<td>PSHA</td>
<td></td>
<td></td>
<td>Save A on stack;</td>
<td></td>
</tr>
<tr>
<td>009C</td>
<td>37</td>
<td>PSHA</td>
<td></td>
<td></td>
<td>Save A on stack;</td>
<td></td>
</tr>
<tr>
<td>009C</td>
<td>5F</td>
<td>CLRB</td>
<td></td>
<td></td>
<td>B = 0 (set local character position to zero);</td>
<td></td>
</tr>
<tr>
<td>009D</td>
<td>13</td>
<td>BSR</td>
<td>GCHAR</td>
<td></td>
<td>CALL GCHAR (calculate character address);</td>
<td></td>
</tr>
<tr>
<td>009D</td>
<td>24</td>
<td>STX</td>
<td>SAVE</td>
<td></td>
<td>Save index register;</td>
<td></td>
</tr>
<tr>
<td>009D</td>
<td>22</td>
<td>LDX</td>
<td>CHPSN</td>
<td></td>
<td>X := CHPSN [get calculated character address];</td>
<td></td>
</tr>
<tr>
<td>009D</td>
<td>20</td>
<td>LDAAB</td>
<td>+32</td>
<td></td>
<td>B := 32 (the number of characters in a line);</td>
<td></td>
</tr>
<tr>
<td>009D</td>
<td>20</td>
<td>LDAAB</td>
<td>+32</td>
<td></td>
<td>A := (arithmetic means put a blank in each pos);</td>
<td></td>
</tr>
<tr>
<td>009D</td>
<td>07</td>
<td>A</td>
<td>00</td>
<td></td>
<td>X := A [move the blank to current location];</td>
<td></td>
</tr>
<tr>
<td>009D</td>
<td>05</td>
<td>A</td>
<td>14</td>
<td></td>
<td>X := X + 1 [point to next location];</td>
<td></td>
</tr>
<tr>
<td>009D</td>
<td>4A</td>
<td>DECB</td>
<td></td>
<td></td>
<td>B := B – 1 (decrement loop counter);</td>
<td></td>
</tr>
<tr>
<td>009E</td>
<td>26</td>
<td>FAE</td>
<td>ELOP</td>
<td></td>
<td>If count remains then reiterate;</td>
<td></td>
</tr>
<tr>
<td>009F</td>
<td>1</td>
<td>DE</td>
<td>74</td>
<td></td>
<td>Restore index register;</td>
<td></td>
</tr>
<tr>
<td>009F</td>
<td>2</td>
<td>LDX</td>
<td>SAVE</td>
<td></td>
<td>Restore A from stack;</td>
<td></td>
</tr>
<tr>
<td>009F</td>
<td>3</td>
<td>PULB</td>
<td></td>
<td></td>
<td>Restore B from stack;</td>
<td></td>
</tr>
<tr>
<td>009F</td>
<td>4</td>
<td>RTS</td>
<td></td>
<td></td>
<td>Return to caller;</td>
<td></td>
</tr>
</tbody>
</table>

ELINE — This subroutine is used to erase one line from the display. The line number is specified by the value in accumulator A upon entry.

<table>
<thead>
<tr>
<th>Rel</th>
<th>Addr</th>
<th>Hex Code</th>
<th>Label</th>
<th>Op</th>
<th>Operand</th>
<th>Commentary</th>
</tr>
</thead>
<tbody>
<tr>
<td>0094</td>
<td>8</td>
<td>ELINE</td>
<td>EQU</td>
<td>*</td>
<td>Entry point of line erase routine;</td>
<td></td>
</tr>
<tr>
<td>0094</td>
<td>37</td>
<td>PSHA</td>
<td></td>
<td></td>
<td>Save B on stack;</td>
<td></td>
</tr>
<tr>
<td>0094</td>
<td>38</td>
<td>PSHA</td>
<td></td>
<td></td>
<td>Save A on stack;</td>
<td></td>
</tr>
<tr>
<td>0094</td>
<td>5F</td>
<td>CLRB</td>
<td></td>
<td></td>
<td>B := 0 (set local character position to zero);</td>
<td></td>
</tr>
<tr>
<td>0095</td>
<td>17</td>
<td>TBA</td>
<td>A := 8</td>
<td></td>
<td>[put it in A for calculation];</td>
<td></td>
</tr>
<tr>
<td>0095</td>
<td>33</td>
<td>PUlB</td>
<td></td>
<td></td>
<td>Restore the displacement in line from 8 ;</td>
<td></td>
</tr>
<tr>
<td>0096</td>
<td>20</td>
<td>STAA</td>
<td>O,X</td>
<td></td>
<td>Then store it in the current line;</td>
<td></td>
</tr>
<tr>
<td>0096</td>
<td>22</td>
<td>VSCR1</td>
<td>A := X</td>
<td></td>
<td>[point to the next character];</td>
<td></td>
</tr>
<tr>
<td>0096</td>
<td>32</td>
<td>*</td>
<td>BASEADDR</td>
<td></td>
<td>This subroutine is used to erase one line from the display. The line number is specified by the value in accumulator A upon entry.</td>
<td></td>
</tr>
</tbody>
</table>

GCHAR — This subroutine calculates the memory address of a character specified by the current character position, CHAR. The formula is:

CHPSN := 32 * A + B + BASEADDR

Where A is the line number, passed in accumulator A, B is the character position value, passed in accumulator B, and BASEADDR is a constant giving the first address in the character display area of memory. The value of BASEADDR in the author’s system is hexadecimal 0CC0. Since the low order offset is zero, this constant is only added into the high order at location 0CC0 of this listing.
Listing 2, continued:

Notation conventions:

RMB = "reserve memory byte" with or without label, uninitialized.
RDB = "reserve double byte" with or without label, uninitialized.
EQU = "equate". Assign an address value to a label.
# = indicator for immediate addressing on Motorola 6800.
$nnn = hexadecimal value nnn.
nnn = decimal value nnn.
* = the current location counter as in an assembly.
'X' = notation for ASCII character X.
HVIDEO = notation for high order byte of address VIDEO.
@X = data at location X (used in commentary).

External Symbol Table:

The following symbols and their relative addresses are the entry points to the video display support software. To calculate the absolute addresses needed to reference these entries, add the starting address at which you load the package to each of these offsets, giving the absolute address to reference in a jump to subroutine instruction.

<table>
<thead>
<tr>
<th>Relative Address</th>
<th>Label</th>
<th>Operation</th>
</tr>
</thead>
<tbody>
<tr>
<td>0000</td>
<td>VLINE</td>
<td>Line display</td>
</tr>
<tr>
<td>0014</td>
<td>ESCRN</td>
<td>Erase screen</td>
</tr>
<tr>
<td>0024</td>
<td>VCHAR</td>
<td>Display one character</td>
</tr>
<tr>
<td>008C</td>
<td>VSCROL</td>
<td>Scroll up one line</td>
</tr>
<tr>
<td>0084</td>
<td>ELINE</td>
<td>Erase one line</td>
</tr>
<tr>
<td>009C</td>
<td>GCHAR</td>
<td>Calculate address given line, position</td>
</tr>
</tbody>
</table>

Future Additions

If you want to display more characters on the TV screen, try disconnecting the wire from IC55 pin 2 to IC64 pin 11. Replace with a wire from IC55 pin 6 to IC64 pin 11). Wire IC55 pin 2 to the 9th address bit at IC14 pin 2. Readjust the Character Width pot to squeeze all those characters on a single line. The software will have to be adjusted to handle the new memory configuration of 16 by 64.

Like to try graphic text? Functionally replace the 2513 with your own PROM. Bit 6 could be used to perform this selection electronically. This PROM could be used to define various line segments within a character field depending upon the 6 (or 7) bit code supplied.

The very nicest thing about a homebuilt project is that after it is working, you're not afraid to modify it! Happy Wrapping.

Photo 21: A Microcomputer Development Workshop? The processor is off in the left hand corner of the table, with a cassette tape recorder to its right. A keyboard with ASCII encoding is connected to the IO card for control of the processor. The video display's television set output is to the left of the oscilloscope at the right side of the picture. The parts cabinets, wire wrap gun, soda pop and ash tray were essential to the development of this system.
We took everything we learned from selling 4Kx8 RAM boards for the past year, added some of this year’s circuit tricks, and came up with ECONORAM—a memory board that is even more remarkable due to its low price. We've engineered this with the user in mind, giving you several benefits:

- 3 regulators to share power load, plus optimized thermal design, means a cooler running microcomputer
- Typical current consumption of under 750 ma gives your power supply a break
- Fast—zero wait states
- All TTL support ICs are latest Low Power Schottky types
- For reliable and unambiguous data transfer, all addresses, data lines, and outputs are buffered for minimum loading and maximum output capability
- Power-on clear included

All these features are packed on to an Altair-sized, industrial quality double-sided PC board, with sockets for all ICs, 7 tantalum capacitors for power supply decoupling, and plenty of bypass capacitors---39 of them, in fact, as well as a logic print and instructions. ASSEMBLED/TESTED UNITS ALSO AVAILABLE FOR A

* Typical current consumption of under 750 ma gives your power supply a break

ECONORAM 4K.

|$99.95

100 PIN EDGE CONNECTOR

$5 EACH--$22 FOR 5

4/$1 TO-220 HEAT SINKS

| 4Kx8 NAKED RAM | $88

This 4k by 8 memory board has no frills, just storage. Designed for compatibility with JOBT systems, this board is also ideal for other microcomputers using bi-directional buffered data/ address bus systems. Same size as J01 memory card, plus low-power operation (750 mw) to keep you on good terms with your power supply.

If you don't need the onboard regulation or address/data buffers of our "bigger brother" 4K board, then this is the way to go.

Sockets included for all ICs.

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2Kx8 BOARD $135.00

"EconoRom" [$179.95

ALTAR 805/IMSAI/ALTAIR COMPARABLE. This is a 4K by 8 EROM board...the ideal place for putting software, be it assembler, editor, or any custom set of routines. Additionally, this board may expand to 8Kx8 by simply adding more sockets and EROMs; also available is a 2Kx8 version $129.95. Full 4K. LOW POWER: 8K board requires 3A @ 5V, & 150 ma @ -12V. Buffered addresses for highest loading, buffered outputs for maximum drive. Kit includes sockets, double-sided quality PC board, on board regulators, logic print, and instructions. Program it yourself, or have us do the programming.

|$189.95

8080 Software Board

We took our ECONORAM board kit, but instead of including blank EROMs, these are programmed with assembler, editor, monitor routines for the 8080. This is a valuable first step if you're trying to get away from machine language programming. There's not really enough room here to fully describe all the functions of the software...but if you sent us $2.95 (refundable) for our flyer we'll make it worth your while.

|$29.95

PACE PACKET

Learn about PACE, the 16 bit microprocessor chip, with this 80 page booklet. Contains detailed and specific information on the chip itself, software, systems evaluation, and more. Also includes 11" X 17" laid-out logic print of PACE implementation.

|$29.95

MicroMONITOR

We've taken the S224, a 4K EROM, and programmed it with some software for your ROM. With this software, you may:

- Examine and fill memory
- Punch and read paper tape
- Print and recover from programs.

Our package consists of the programmed S224 as well as a complete software listing.
Many people have done as I have, which is to put aside their 8008 and replace it with an 8080A or newer generation equipment. This 8008 unit which is kicking around can solve the chief disadvantage of vector graphics — software refresh. The 8008 is more than adequate to drive the controller with fixed data tables: Why not take advantage of it? A very reasonable solution is to dedicate your Scelbi, Mark 8, or what-have-you-kluge to run and refresh the display. The graphics program and refresh vector table would be contained within the 8008 as well as a very simple communications driver which allows it to talk with your new 8080, Z-80, 6800 or what have you. Communication would be between a couple of parallel input and output ports. The 8080 system could contain all the number crunching routines and large programs such as Space War while the 8008 drew and refreshed the playing field or hyper space. Vector table updates would be sent from the main game processor to the 8008 display processor periodically as the game progressed. This system would be fantastic.

### Bigger Displays

While 5 inch scopes are quite adequate, full appreciation of vector graphics is realized only on large screen displays. Commercially sold large screen XY displays start at about $600. Hal Chamberlin, in his *Computer Hobbyist* articles mentioned earlier, describes how such a display can be built (with some difficulty) using television style display mechanisms. His work was an invaluable help to me in getting my display going; the circuits you see in this article are my adaptations of some of the circuits Hal published in his excellent publication in connection with his vector display design. *The Computer Hobbyist* is located at Box 295, Cary NC 27511. At last report, back issues were available.

Another possible source of big screen displays is auctions of electronic equipment (often attended by dealers in surplus). For example, *Electronic News* often publishes

### REFERENCES

Worth noting are two articles which contain information on vector graphics experimentation beyond that contained in this issue of BYTE:

**Concerning the conversion of the Sanders 708 see:**

Ciarcia, Steve and Robertson, Carl L: “Simple Graphics Terminal Using Inexpensive Surplus Equipment;” *73 Magazine*, September 1976, pages 116-123. (The circuits shown in figure 2 of the present article are revised versions of some of the circuits in author Ciarcia's earlier published work cited here.)

**Concerning the generation of character graphics for a vector display see:**


**Concerning experimentation with a magnetic deflection CRT display built from scratch, see:**

A series of graphics articles by Hal Chamberlin in Volume 1, issues 1, 2 and 3 of *The Computer Hobbyist.*

---

### Table 2: Refresh Vector Table for Drawing the Star Ship Enterprise

This table contains the information needed (in octal) to generate the Enterprise on a vector display. The addresses are relative to page 001, starting at location 50, for use with the program of listing 2. The end of the display string is indicated by the octal code 377 found stored at location 330. If you were to put some extra imaging information in the picture, the additional vectors would begin at location 330 instead of the end code. The fine print numbers in figure 4 near each line segment are the addresses of the appropriate vector specification in this table.

<table>
<thead>
<tr>
<th>Vector Address</th>
<th>X</th>
<th>Y</th>
<th>X</th>
<th>Y</th>
<th>commentery</th>
</tr>
</thead>
<tbody>
<tr>
<td>050</td>
<td>004</td>
<td>104</td>
<td>014</td>
<td>070</td>
<td>Begin Enterprise's bridge</td>
</tr>
<tr>
<td>064</td>
<td>014</td>
<td>070</td>
<td>110</td>
<td>070</td>
<td></td>
</tr>
<tr>
<td>060</td>
<td>030</td>
<td>070</td>
<td>064</td>
<td>060</td>
<td></td>
</tr>
<tr>
<td>064</td>
<td>054</td>
<td>060</td>
<td>074</td>
<td>070</td>
<td></td>
</tr>
<tr>
<td>070</td>
<td>110</td>
<td>070</td>
<td>120</td>
<td>104</td>
<td></td>
</tr>
<tr>
<td>074</td>
<td>120</td>
<td>104</td>
<td>004</td>
<td>104</td>
<td></td>
</tr>
<tr>
<td>100</td>
<td>014</td>
<td>104</td>
<td>040</td>
<td>110</td>
<td>Phaser weapons bank</td>
</tr>
<tr>
<td>104</td>
<td>040</td>
<td>110</td>
<td>120</td>
<td>104</td>
<td></td>
</tr>
<tr>
<td>110</td>
<td>040</td>
<td>110</td>
<td>042</td>
<td>114</td>
<td></td>
</tr>
<tr>
<td>114</td>
<td>042</td>
<td>114</td>
<td>064</td>
<td>114</td>
<td></td>
</tr>
<tr>
<td>120</td>
<td>064</td>
<td>114</td>
<td>070</td>
<td>116</td>
<td></td>
</tr>
<tr>
<td>124</td>
<td>046</td>
<td>114</td>
<td>050</td>
<td>120</td>
<td></td>
</tr>
<tr>
<td>130</td>
<td>050</td>
<td>120</td>
<td>060</td>
<td>120</td>
<td></td>
</tr>
<tr>
<td>124</td>
<td>060</td>
<td>120</td>
<td>062</td>
<td>114</td>
<td></td>
</tr>
<tr>
<td>140</td>
<td>074</td>
<td>070</td>
<td>104</td>
<td>034</td>
<td>Bridge connecting strut line</td>
</tr>
<tr>
<td>144</td>
<td>104</td>
<td>034</td>
<td>064</td>
<td>030</td>
<td></td>
</tr>
<tr>
<td>150</td>
<td>064</td>
<td>030</td>
<td>064</td>
<td>010</td>
<td></td>
</tr>
<tr>
<td>154</td>
<td>064</td>
<td>010</td>
<td>104</td>
<td>004</td>
<td></td>
</tr>
<tr>
<td>160</td>
<td>104</td>
<td>004</td>
<td>140</td>
<td>004</td>
<td></td>
</tr>
<tr>
<td>164</td>
<td>140</td>
<td>004</td>
<td>210</td>
<td>014</td>
<td></td>
</tr>
<tr>
<td>170</td>
<td>210</td>
<td>014</td>
<td>204</td>
<td>024</td>
<td></td>
</tr>
<tr>
<td>174</td>
<td>204</td>
<td>024</td>
<td>170</td>
<td>027</td>
<td></td>
</tr>
<tr>
<td>200</td>
<td>164</td>
<td>032</td>
<td>140</td>
<td>034</td>
<td></td>
</tr>
<tr>
<td>204</td>
<td>140</td>
<td>034</td>
<td>104</td>
<td>034</td>
<td></td>
</tr>
<tr>
<td>210</td>
<td>140</td>
<td>034</td>
<td>114</td>
<td>076</td>
<td>Bridge connecting strut line</td>
</tr>
<tr>
<td>214</td>
<td>074</td>
<td>032</td>
<td>074</td>
<td>006</td>
<td>Phaser weapons bank</td>
</tr>
<tr>
<td>220</td>
<td>064</td>
<td>020</td>
<td>054</td>
<td>030</td>
<td></td>
</tr>
<tr>
<td>224</td>
<td>054</td>
<td>030</td>
<td>054</td>
<td>010</td>
<td></td>
</tr>
<tr>
<td>230</td>
<td>054</td>
<td>010</td>
<td>064</td>
<td>020</td>
<td></td>
</tr>
<tr>
<td>234</td>
<td>054</td>
<td>020</td>
<td>050</td>
<td>020</td>
<td></td>
</tr>
<tr>
<td>240</td>
<td>134</td>
<td>104</td>
<td>134</td>
<td>130</td>
<td>Engine pod outline</td>
</tr>
<tr>
<td>244</td>
<td>134</td>
<td>130</td>
<td>320</td>
<td>130</td>
<td></td>
</tr>
<tr>
<td>250</td>
<td>320</td>
<td>130</td>
<td>304</td>
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<td>End of picture code</td>
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Figure 4: The Star Ship Enterprise, drawn on a graphing grid. One way to prepare data for a display such as this is to plot it out ahead of time on a coordinate grid, such as graph paper. This figure was constructed using the data of table 2; but in the normal procedure the figure would be drawn first, and then one would prepare the table of vector specifications.

Figure 3: Using the graphics display for engineering outputs. This is a concocted display to illustrate XY plotting situations. Whatever "output" is, it varies with "time" in a ragged sawtooth defined by several vectors.
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Only 1" X 1.5", input 5 to 12 VDC, output is 60Hz square wave for portable or mobile clocks. PC board is drilled.

MTX-60H .............................................. $5.88
function with a del and attempt to execute it:

NEW

TABLE OF SQUARES
1 1

TABLE OF SQUARES
2 4

Something is wrong, so you reenter the function definition mode and list your function:

NEW

[6]

[N]

NEW

[1] N=0

[2] 'TABLE OF SQUARES'

[3] N=N+1

[4] N=N*2

[5] +(N#10)/2

The line which used to be 2 is now 3, since APL renumbers all lines to integers when you close the function. You could change the 2 to a 3 in the fifth line; however, there is a better way. If you have to insert or delete lines from your function again, all places where there is a branch arrow may also have to be changed. If APL did not provide a way around this problem, the language would not be as popular as it is. In a function you can specify a variable to become a label by putting it at the beginning of a line and following it by a colon. Whenever you execute that function the labels in it are automatically assigned the value of the lines where they are located. The function when corrected using a label would look like this:

NEW

[1] N=0

[2] 'TABLE OF SQUARES'

[3] LOOPLABEL: N=N+1

[4] N=N*2

[5] +(N#10)/2 / LOOPLABEL

The function NEW above is a niladic function, which returns no result. Niladic means it has no arguments. Here is an example of a niladic function which returns a result:

VRESULT=THISFUN

{[1] X=A+B

[2] RESULT=px

V

The function could be called inside an expression and used wherever a variable could be used. For example:

A+1

B+1 2 3 4

3+THISFUN

7

THISFUN calculates the sum of A and B then finds the length of the sum and returns it as the value of THISFUN. In the function

---

Proposed Micro APL Specifications

Operators:

All monadic and dyadic scalar operators will be implemented (except for the exponential, logarithmic and circular if space does not permit).

The following monadic mixed operators will be implemented: ravel, index generator, shape. The following will probably be implemented: grade up, grade down, execute, and reversal. Catenation, index of, reshape, and compression will be the dyadic mixed operators implemented, probably along with: take, drop, element of, rotate, and perhaps encode and decode if space permits.

The only composite operator implemented will be reduction.

Data Structures:

Numeric and character data will be allowed, but all numbers will be stored in IBM 360/370 single precision floating point format. Character data will be stored one character every four bytes to conform with floating point format. The space allocated for character and numeric data will be 1 to 2 K, so the maximum number of elements in all variables and internal variables created by evaluation of an expression must be less than 256 to 512. Vector will be the only type of array allowed.

Functions:

Up to eight functions may be defined in workspace. The total memory for function storage will be around 1 to 2 K. Although the functions are stored in essentially the same format in which they are defined, a number of pointers also have to be stored in this area. Recursive functions and local variables may or may not be allowed depending on the amount of memory available.

Total Memory Requirement:

12 K 8008 system. An 8080 or 6800 version could probably run in 8 K by reducing the amount of memory allocated to the workspace.
the value that will be returned is assigned to the dummy variable specified in the function header (in this case, RESULT).

A function could also be monadic, as this function which finds the cosine of a number:

\[
\forall c \cdot \cos x
\]

\[ \cos 2\pi x \]

\[ v \]

A monadic function which returns a result, such as \( \cos \), could be used anywhere a monadic operator is legal. (See table 1 for the meaning of symbols used.) Thus APL allows the programmer to effectively create new APL operators, which sometimes adds the readability of a program. An example of the use of this particular function is:

\[
(\cos 02) + (\cos 03)
\]

This is certainly more readable than

\[ 2002 + 3003 \]

which would calculate \( \cos (2\pi) + \cos (3\pi) \). A dyadic function which returns a result could be used anywhere a dyadic operator is legal, so the function ADD could replace +:

\[
\forall a b + \cdot a \text{ add } b
\]

\[ \text{ADD } 4 \]

\[ 3 \]

This should give you a good idea of the power of APL on a large system, but how useful would APL be on your small system byte banger? Obviously many of the operators would take a good deal of the memory of an average small system to implement (matrix divide, for example). Another problem is that since APL is so generalized in its operations, it is somewhat memory inefficient. For example, to add two vectors, A and B, together, you have to type is:

\[ A + B \]

but, in order to calculate the sum, APL has to make a copy of each of the vectors first; so if the length of A and B is 64 (256 bytes at 4 bytes per floating point number), then 1 K would be in use during this operation. Using a comparable program in BASIC would require 516 bytes, since the sum could be calculated one element at a time, printing each sum out as it was calculated. There is also an IO problem, since most people have ASCII encoded terminals (or the equivalent), terminals which do not have the entire APL character set on them.

The only way I see that APL could be practical for a memory and IO limited personal processor is if the features were limited (only vectors, for instance, instead of up to 63 dimensions for arrays), and if the number of operators were kept to a workable minimum. All the scalar operators are performed in a similar manner, so they could be easily implemented. But only the most powerful of the mixed operators should be implemented, for example:

\[ p / t \]
Of the composite operations, reduction is the most used, and easiest to implement. Whether or not character data would be allowed depends on what size system was available. An easy way to handle character data would be to store one character every four bytes, so the routines used for numbers would not have to take care of the special case of character data. Although this method would waste memory in the workspace proper, it would greatly reduce the size of the interpreter, and in a small system this is where most of the memory is used. On large systems, logical (1 and 0) data is stored as bit level data for memory efficiency, but on a small system the major programming problem of unpacking bits would probably not be worth the small savings it would provide.

GLOSSARY

Array: An array is a group of numbers (or characters) which in APL can be subscripted or treated as a single object. Vectors are the only type of arrays discussed in this article; however, a full implementation of APL allows matrices and up to 63 dimensions for arrays.

Character: As an APL data type, character is the kind of operand which is allowed for most mixed operators, but not for scalar operators other than = and ≠.

Command: An APL system command causes some operation to occur, such as destroying the current workspace, or loading a new workspace from an external device. A command begins with a right parenthesis and has an English keyword, such as } CLEAR or } SAVE. A command is normally legal in either execute or function definition mode.

Compiler: A program which translates a high level source program into machine language object code is called a compiler.

Composite operator: A generalized operator which takes a built-in operator(s) and performs it (them) in a special way. An example is reduction, which takes a scalar operator and performs it upon all the elements of the operand, right to left.

Dyadic: A mathematical term meaning having two operands. An APL function or operator which is dyadic must have an operand on both sides of it.

Execute mode: This is the APL system mode where an expression such as 1+1 will print the result. The del is used to leave the execute mode for the function definition mode.

Function: This is the name of an APL program. Since a workspace may have more than one function and a function can be niladic, monadic, or dyadic, and may or may not return a result, functions can be used as main programs, subroutines, or functions.

Function definition mode: This is the mode in which APL functions are created. The del is used to go back and forth between the execute and function definition modes.

Function header: This is the first line of a function, before the actual program starts. It gives information to the interpreter about the function: Does the function return a result? What, if any, local variables are used in the function?

Interpreter: APL is implemented as an interpreter, a program which takes a source listing of the high level program and performs operations as the meaning of the program is being translated.

Mixed operator: In APL a mixed operator is one that allows or requires the operand(s) not to obey the rule for the size and shape that scalar operators do require.

Monad: A function or operator which has only one operand to the right of the operator.

Niladic: A function which has no operands.

Operator: An operator is a built-in function which performs some common task such as addition, and is represented by a single, reserved, character.

Quad: The quad is used in expressions to perform input and output, and in the function definition mode to list the function. To the right of an assignment arrow quad will request an expression, which will be evaluated, and the result used in place of the quad in the expression. To the left of an assignment arrow, quad prints out the value assigned to it. Quote-Quad is for input of character string data only.

Rank: This is the shape of the shape of an array; in other words the number of dimensions of the array.

Scalar: A single value, such as 8 or ~23.4. Scalars can be used with dyadic scalar operators to operate on all the elements of the other operand.

Scalar operator: An operator which obeys this rule: If the size of the two operands (for the dyadic operation) is the same, do the operation on the values in parallel. If one or the other is scalar, do the operation between the scalar and all the elements of the other operand.

Shape: In a full implementation of APL, this is a vector which represents the dimension of an array.

Subscript: This points to which elements of an array are to be used. APL allows subscripts to be vectors, a feature most other languages do not allow.

Variable: A symbolic name given to a value, such as 3, or ~4. A local variable (dummy) is one which will be destroyed after the function in which it is in finishes executing.

Vector: A one dimensional array, the only type of array which can be represented as a constant in APL.

Workspace: The APL name for all the functions, variables, and internal state indication data which the user has created.
The storage problem of A+B could easily be avoided by writing a program similar to the one in BASIC:

\[
\text{VNOPROBLEM}
\]

\[
[1] \text{N} \leftarrow 0
\]

\[
[2] \text{LOOP: N} \leftarrow \text{N+1}
\]

\[
[3] \text{A}[\text{N}]+B[\text{N}]
\]

\[
[4] \rightarrow (\text{N} \neq \text{N}) / \text{LOOP}
\]

\[
V
\]

**BIBLIOGRAPHY**


Kenneth Iverson, *A Programming Language*, Queens University, Kingston, Ontario, 1968. This is a fairly mathematical type book, and does not represent APL as it was implemented, although Iverson is the creator of APL.


Sandra Pakin, *APL/360*, Science Research Associates, Chicago, 1972. This is a manual for the IBM 360 implementation of APL.


*Xerox APL Reference Manual*, Xerox Corp, El Segundo CA 1973. This is where I got the idea of mnemonic representation of APL characters using the $.

In APL the programmer has the advantage of being able to choose whether or not he or she wants to use the built-in vector operator or program it, which is something that the programmer of most small system BASICs does not have.

As far as the character set problem is concerned, a translation table could be built to translate ASCII input like $R (control R) into the internal code for ρ, or $I into the internal code for I. Once translated, the computer would not care if the I came from an APL terminal or even a Baudot Teletype. Or, an ASCII keyboard could be used when the internal codes for the APL character set were chosen so that the positions of the characters on the ASCII keyboard simulated where the same key was on the APL keyboard. An upper case I would be \( I \) while i would be translated into \( i \). The same translation would occur with \( R \) and \( ρ \); \( r \) and \( R \). On such a system a TV display could be converted to show a 5 by 7 representation of the character, as shown in figure 1.

![Figure 1](image.png)

**Figure 1**: Two examples of alternate dot matrices for APL characters. The character at the left is the Greek character rho, shown in an approximation which distinguishes it from a Roman P. The character at the right is a Greek iota.

Of course, software would have to handle the translation from the internal codes to the graphics codes, and software would have to take care of the cursor; so that if the APL programmer backspaced to create a legal overstrike, such as ‘ over . to form . ; or \( \overline{R} \) over \( \overline{I} \) to form \( \hat{\phi} \), the rotate operator, it would appear as if the overstrike actually occurred. (On most CRTs, it would not have; but rather it would have been replaced by a new code, created by the software as soon as the backspace and corresponding overstrike were entered.)

Some people love APL and some people hate it. I think it is one of the best interpreters around, next to BASIC. I hope to be able to implement a subset of APL on my computer in my spare time so that it will speak more than one language. I’m not sure how powerful a small system APL would be, but I will report my success or failure in a later article. In the meantime, I'd like to hear from anybody who is interested in or knowledgeable about small systems APL.
Texas Instruments has announced (in marketing literature of somewhat limited circulation) a new single chip video controller integrated circuit which is envisioned as part of the 9900 family line. This is a single chip generator for all the timing and control information needed to run a raster scan display interfaced to an LSI processor’s bus. The grapevine says that it is being sampled at the present time, and will be on distributor shelves next spring. The same grapevine identifies a second, similar controller chip announced by another company as well. Either item would make excellent material for a tutorial review article in BYTE since these chips have obvious uses in personal computing systems.

Editor’s Pet Peeve: All you wonderful users of the English language, engineering subset, take note: A "baud rate" is a redundant abomination. The concept is data rate, sometimes measured in units of baud which we take to signify bits per second. (The original definition of a rate measured in baud is a little more complex.)

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- 1K of on board 2102 RAM.
- Serial interface built into CPU chip.

*Fairbug is a registered trademark of Fairchild Corp.

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<td>$459.00</td>
<td>$539.00, $599.00 or $840.00 Depending On System</td>
<td>$395.00</td>
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**TINY 2K BASIC (AVAILABLE) OCT. 15, 1976 $25.00**

**FULL BASIC (AVAILABLE) DEC. 15, 1976 $50.00**

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DIODES

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FND 500-25 C.C.

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SOLD STATE SALES

PO BOX 74B
SOMERVILLE, MA. 02143

INTEGRATED CIRCUITS

PRINTED CIRCUIT BOARD

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Silicon Power Rectifiers

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REGULATED MODULAR POWER SUPPLIES

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LINEAR CIRCUITS

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SANKEN AUDIO POWER AMPS

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- The Power Semiconductor Handbook for Design Engineers by Texas Instruments Incorporated. To complement the low power transistor handbook, TI supplies this 800 page tome on high power transistors and related switching devices. Here is where you find data on the brute force monsters which are used to control many Watts electronically. Fill out your library with this book, available for only $3.95.
- Understanding Solid State Electronics by Texas Instruments Incorporated. This is an excellent tutorial introduction to the subject of transistor and diode circuitry. The book was created for the reader who wants or needs to understand electronics, but can’t devote years to the study. This 242 page softbound book is a must addition to the beginner’s library at only $2.95.
- The Optoelectronics Data Book for Design Engineers by Texas Instruments Incorporated. This 366 page book is a compendium of information on TI phototransistors, LEDs and related devices. Order yours at $2.95.

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When you build a project, you need this same sort of information. All you find in the advertisements for parts are mysterious numbers identifying the little beasts… hardly the sort of information which can be used to design a custom logic circuit. You can find out about many of the numbers by using the information found in these books. No laboratory bench is complete without an accompanying library shelf filled with references – and this set of Texas Instruments engineering manuals plus Don Lancaster’s TTL Cookbook will provide an excellent starting point or addition to your personal library.
**MINIATURE LAMPS**

**BRIGHT-GLO Incandescent Lamps**

- **Ultra-luminized Series, 100.0 hr. life**
- **Versatile, low cost indicator lamp**
- Ideal for Stereo Amplifiers, Mobile Equipment, Instrumentation, Control and Display Panels, etc.

**High temperature, T 1-3/4 lamps** - Metal Base - Wire Terminals. Metal base increases light output and protects lamp from shock and vibration.

- 61, 685 pcs - 6.3 volts, 75 ma, 8" wire leads.
- 40,263 pcs - 6.3 volts, 200 ma, 12" wire leads.

**DISCOUNT SCHEDULE**

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**BARGAINS**

**PURITY - NO MINIMUM QUANTITY REQUIRED**

**INDICATOR LIGHTS**

**HIGH POWER DUMMIE LOAD**

Mfg. Eastern Microwave. 910-1254...RF Coaxial Load Register utilizing water flow or cool air and providing a load resistance of 50 ohms for inputs from DC to 4000 MHz. Maximum input power is 1000 watts. Requires a flow of 0.018 GPM per 100 watts of input power; 100 psi pressure. Composition setting on water inlet and outlet for cooling. Wide variety of applications. 5/8" x 1-1/2" flange. Complete assembled unit in stock. Sizes: 5-1/8" diameter by 5-3/8" long. Shipping weight, 2 lbs. 9,000 pcs in stock, NEW BOXED......$14.95 each.

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**LIGHTED PUSH-BUTTON SWITCHES**

**TANTALUM CAPACITORS**

**METALIZED PAPER FILM**

**ELECTROLYTIC CAPACITORS**

**Computer Grade Capacitors**

**Electrolytic Capacitors**

**TUBULAR, HIGH RELIABILITY**

**INDIANAPOLIS**

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- **Ultra-luminized Series, 100.0 hr. life**
- **Versatile, low cost indicator lamp**
- Ideal for Stereo Amplifiers, Mobile Equipment, Instrumentation, Control and Display Panels, etc.

**High temperature, T 1-3/4 lamps** - Metal Base - Wire Terminals. Metal base increases light output and protects lamp from shock and vibration.

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**METALIZED PAPER FILM**

**ELECTROLYTIC CAPACITORS**

**TUBULAR, HIGH RELIABILITY**
Production Description:

The Astral 2000 system is based upon the Motorola 6800 central processor design. The use of any one of the many microprocessors is subject to numerous design choices in the details of how the chip will be buffered and interact with the rest of the computer world. The designer of the Astral 2000 computer chose to take a route which seems inherent in the design simplicity of the second generation microprocessors such as the 6800. The Astral 2000 bus is a minimum complexity, minimum pinout design which in essence simply buffers the processor pins of the 6800. As a result, it fits into the standard 44 contact (dual 22 pin) edge connectors which are widely available at moderate cost. This choice of a minimum pinout backplane configuration also makes it possible for this computer to use standard Vector Electronic Co cards as the basis for homebrew peripheral interfaces.) This simplicity of the backplane bus and use of standard connectors is one of the most elegant features of the Astral 2000.

Without indulging in a major review, here in summary is what the 6800 processor chosen for the Astral 2000 will give the programmer in machine assembly language:
1 index register (16 bits),
1 stack pointer register (16 bits),
2 accumulators (8 bits),
1 flag register (6 bits active),
5 addressing modes for data operations (direct 8 bit, extended 16 bit, immediate, indexed with 8 bit offset, and inherent operands),
4 addressing modes for processor control operations (relative with 8 bit signed offset for branches, jumps and subroutine calls, with extended 16 bit addresses or addresses indexed by 8 bit offset, and inherent operands for miscellaneous processor control instructions).

Data control manipulations include the usual and expected operations of a good general purpose instruction set in the second generation of microprocessors. Also worth noting are a decimal adjust instruction to handle packed decimal data and push and pull operations for the accumulators utilizing the stack as temporary data storage. The processor has a software interrupt, a reset sequence, a maskable interrupt line, and a nonmaskable interrupt line; all of these except the reset completely save the processor state prior to the beginning of the new instruction sequence. These interrupt-like operations are vectored to a new program location via 4 pointers located in the last 8 bytes of address space (locations FFF8 to FFFF.) For more complete description of the 6800 architecture see the Motorola 6800 literature.

As implemented in an Astral 2000 system, the first 56 K bytes of a total 64 K bytes in the 6800 memory address space are left open for ordinary programmable memory, the single most valuable resource of any general purpose processor's central processing unit. What this means is that the user can insert cards in increments of 8 K to the point where some level less than or equal to 56 K has been acquired. (This assumes that there are enough card slots in the backplane to accommodate such an expansion.) M&R Enterprises presently has available both an 8 K programmable memory board and an 8 K EROM board (using the 5204 UV erasable chips) with which to take advantage of memory address space. The standard package of the Astral 2000 includes one of the 8 K programmable memory boards. The upper 8 K of a Motorola 6800's address space is reserved for the system monitor and peripherals of the Astral 2000 design.

The Monitor and IO

The basic concept of the Astral 2000 is that of a "turn key" system, even when the unit is purchased in kit form. An aspect of this is the preassembled and tested processor board and memory board. Another aspect of this is in the physical configuration seen in the photographs. The front panel may seem at first sight to be an unimaginative repeat of the traditional front panel seen in computers from time immemorial. But it is not essential, and is put in the design apparently for
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The Astral 2000 computer is $995 partially assembled or $1250 fully assembled and tested. Additional fully assembled 8 K RAM boards are $245 each and the 8 K EROM board is $59.95. The VID-80 video terminal is $189.95 in kit form or $245 fully assembled and tested. IO tape interface units are $49.95 each. The software package includes Astral BASIC on magnetic tape cassette or paper tape (specify), complete documentation and a free one year subscription to the Astral Newsletter, all for $35. The Astral 2000 is available from M&R Enterprises, POB 61011, Sunnyvale CA 94088.

The toggle switches and lamps don't really control a thing directly, since they lead directly to a group of PIA ports, as do the other “front panel” features such as the system's real time clock.

The “turn key” effect is achieved by two subsystems of the central processor board design and an optional VID-80 video display terminal board. The processor board contains the key to turn key operation, a 2 K byte ROM monitor. This monitor program can be used in one of two modes: It can drive the VID-80 terminal interface board, or a standard serial line interface with both 20 mA current loop (Teletype compatible) and EIA RS-232C compatible drivers for typical commercial terminals. The serial terminal interface also includes control lines for auxiliary functions such as reader and punch control.

The logical features of the Astral 2000's monitor program will prove quite useful. The input of the monitor is buffered so that commands can be repeated simply by entering an ASCII space code from the keyboard. In the context of a command like the one which dumps “n” bytes, this can be a saver of keystrokes: once “TYPE 8” has been entered, additional 8 byte groups of data can be dumped in sequence by simply entering a space. The monitor also includes machine language debugging facilities to aid the low level language hacker. These debugging facilities include patching and displaying memory contents, insertion of break points, stepping through break points, etc. The Astral 2000 monitor also has larger scale data manipulation facilities which include memory checksum calculation, “block insert” for temporary program patches, a command which can be used to calculate relative branch offsets, and patch points for the software interrupt, nonmaskable interrupt or maskable interrupt requirements of applications systems and programs.

High Level Language Facilities

A major concern of most users is the need for high level language facility. In the Astral 2000 case, one of the strong points in the descriptive literature is its 8 K extended BASIC implementation. This is part of a standard $35 software package which is available to the purchaser of the system. The descriptive literature of Astral BASIC implies that it will prove quite useful, whether the application is business processing, games hacking, or a host of other small computer uses. Here is a summary list of the points found in the Astral BASIC which supplement the usual features of any good extended BASIC.

- Floating point arithmetic with user selectable precisions of 6, 9, 13 or 16 decimal digits. (Trade execution time off against precision of calculation.)
- A unique DO statement references groups of statements by number to provide a simple form of subroutine call not usually found in BASIC.
- Full statement trace facility.
- Variable length character strings of unlimited (ie: 2**16) length.
- Substring search function for character strings.
- Complete line oriented editing facility including a renumbering facility which alters all GO TOs.
- Formatted output with PRINT USING, an essential for practical applications programming.

Miscellaneous

Rounding out the details of the Astral 2000, the standard version includes an audio interface for magnetic tape recording, a real time clock based upon a standard 24 hour clock chip accessed through PIA's and level shifters, and a centralized power supply with 5 V at 12 A. Prices for several of the component modules are printed in the caption for photo 2.
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This book, published by McGraw Hill in 1971, is a fundamental starting point for any person designing peripheral and custom logic employing TTL integrated circuits. While its publication date precludes any reference to the later additions to the TTL 7400 series of components found in the Data Books, it is nevertheless the source of a wealth of ideas on TTL integrated circuits and design of logic with this family of circuits.

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A chapter on Arithmetic Elements gives fundamental descriptions of binary arithmetic, diagrams of the basic gate configurations for combinatorial logic adders, and a section on number representations for use in computers. Much of the material in this section is dated, due to the fact that the later 74181 series of multiple function arithmetic units had not yet appeared when the book was written. But for a background on arithmetic operations implemented with the simpler 7483 circuits, this chapter is ideal. A chapter on Counters and a chapter on Shift Registers complete the detail logic sections. The book is closed out by a chapter on miscellaneous Other Applications including a simple binary multiplier, a 12 hour digital clock and a modulo-300 adder.

The most important use of this book is its value as an introduction to TTL logic. By reading and studying it, you will begin to understand the ways in which SSI and MSI TTL gates can be utilized in your own experimental logic designs. After studying this text, you should be able to make much more sense out of the technical information summaries typically published as specifications sheets and data catalogs.

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*MICROCOMPUTER DESIGN by Donald P. Martin, Martin Research. Edited and Published by Kerry S. Berland, Martin Research.

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Even Intel, the originator of the microprocessor revolution, is hard put to compete with the wealth of information found in Martin Research's new second edition of Microcomputer Design. This is the book which was originally published as an expensive (but quite practical) engineering report in loose leaf form, at about the time the microprocessor technology was first catching on in the form of the 8086. This 388 page second edition of the manual is loaded with detailed information on how to build and use computers based on the 8086 and 8080.

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Updates to the 9900 Line

Texas Instruments has announced additions to the TMS9900 microcomputer product family in a release dated July 20. A short summary of the additions, which should show up in personal computing end products in the next half year or so, is as follows:

- **TMS9980**: This is a new MOS version of the TMS9900, packaged as a standard 40 pin dual in line package with a physical description similar to most 8 bit microprocessors: 8 bit data bus, 16 bit address bus, etc. But there is a difference. If readers will recall Robert Baker’s article on the TMS9900 chip in the April 1976 *BYTE*, the internal architecture of a 9900 is that of a 16 bit minicomputer with hardware multiply and divide, 16 general purpose register like work areas, etc. The same instruction set is executed by the 9980 with a slight drop in speed of execution due to the fact that byte addressing is now done in the external world with an 8 bit wide memory and peripherals data path instead of a 16 bit data path. This product is to be sampled late in 1976, and we expect at least one manufacturer to put this on an Altair compatible plug in board for the personal computing market. The hardware of the 9980 features an onchip oscillator and clock generator, so the breadboarding and production of hardware with this chip should prove convenient.

- **TMS9904** is a 4 phase clock generator and driver for use with the TMS9900 computer circuit, using a crystal controlled input.

- **TMS9901** is a programmable systems...
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interface for the TMS9900 or TMS9980, which interfaces directly to the processor's CRU port for interrupt priority, IO control and interval timing. It provides 15 individually maskable interrupt request lines or up to 16 programmable IO ports, and can be programmed as an interval timer with resolution from 21 μs to 699 μs.

- **TMS9902** is the 9900 family's version of a UART. This circuit is customized to the TI CRU (Communications Register Unit) IO addressing scheme, and features data rates from 5 to 76,800 bits per second, character lengths from 5 to 8 bits, and 1, 1.5 or 2 stop bits per character with or without parity.

- **TMS9903** is the synchronous communications port for the 9980 and 9900 computers. This is similar to what is sometimes called a "USART" and features a wide variety of options. It will handle most synchronous data transmission protocols, including the BISync and IBM's new Synchronous Data Link Control discipline, at data rates from DC to 250,000 bits per second.

Samples have not yet been delivered on these items, and pricing is to be announced when samples are available. Inquiries should be directed to Texas Instruments Inc, POB 5012, MS/84, Dallas TX 75222, attention "9900 Family".

---

**A New Graphics Option for OSI**

Shown off at the Personal Computing 76 show in Atlantic City was the interface which produces these pictures. The manufacturer of the "Super Video Board" which generates 128 by 128 raster graphics is Ohio Scientific Instruments, 11679 Hayden St, Hiram OH 44234. This board, which plugs into the OSI Model 400 system, can be used, as in photo 1, to draw pictures with low to moderate resolution, and to display the output of a software "logic state analyzer" program, as in photo 2.

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